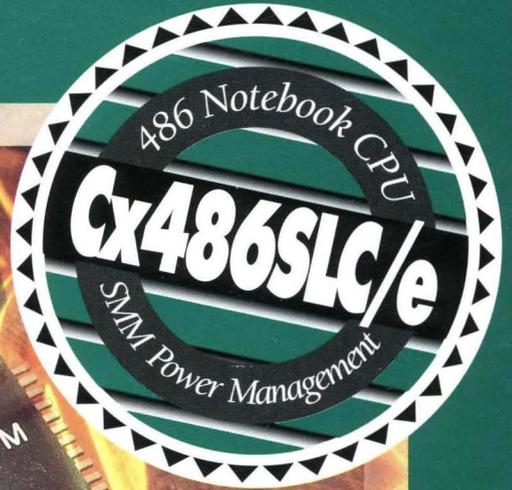


CYRIX Cx486SLC™ MICROPROCESSOR

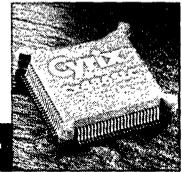
Data Sheet





CYRIX Cx486SLC/e™ MICROPROCESSOR

High-Performance 486-Style CPU with Advanced Power Management for Notebook and Battery-Powered Systems



Cx486SLC/e Data Sheet

◆ 486 PERFORMANCE

- Up to 2.4 times faster than 386SL at same frequency
- Landmark 2.0=107 MHz, Norton SI 6.0 = 52 at 33 MHz
- On-chip hardware multiplier accelerates graphics
- Clock speeds up to 33 MHz

◆ 486-STYLE ARCHITECTURE

- Single-cycle RISC-like 32-bit integer core
- Integrated instruction and data cache
- Executes 486SX instruction set
- Runs DOS, Windows, OS/2, Unix

◆ SMALL 100-PIN QFP PACKAGE

- Compatible with 16-bit 386SX bus interface allowing compact system design
- Companion low-power QFP math coprocessor

◆ ADVANCED POWER MANAGEMENT

- Software or hardware initiated low-power suspend mode
- Full static design permits stop clock state
- On-chip cache significantly reduces power-consuming external memory accesses
- 3 V and 5 V versions

◆ SYSTEM MANAGEMENT MODE

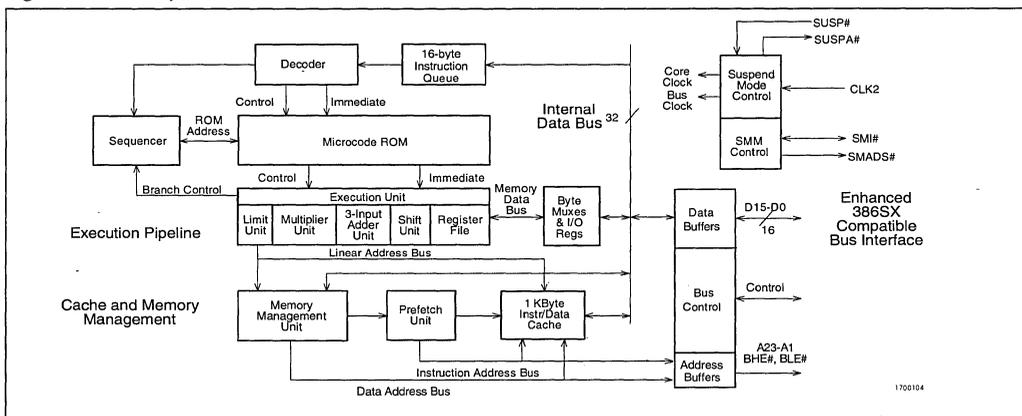
- High priority SMI interrupt and separate memory address space
- Facilitates system-wide power management for maximum battery life
- Rapid SMI service routine entry and exit
- I/O trapping for power management of peripherals

The Cyrix Cx486SLC/e is an enhanced version of the Cx486SLC specifically designed for demanding battery-powered applications. The Cx486SLC/e offers high performance integrated with advanced features for both CPU power management and system-wide power management.

The Cx486SLC/e's System Management Mode (SMM) provides a high priority interrupt, I/O trapping and a separate address space used to enhance and simplify power management software. Fast entry and exit of SMM allows frequent use of this feature without performance degradation.

High performance is achieved through use of a single cycle execution unit and a 32-bit internal data path that couple tightly to an on-chip instruction/data cache. This architecture results in up to 2 to 3 times the performance of conventional 386SL notebook CPUs. Additionally, the on-chip cache reduces overall system power by minimizing external memory accesses.

Additionally, the CPU's power consumption can be minimized through use of easy-to-design suspend/resume functionality augmented by a static CPU core. When active, these features result in a significant reduction in CPU power (0.1% of active power). The 3V version consumes less than one third the power of the 5V device.



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*High-Performance 486-Class CPU with Advanced Power
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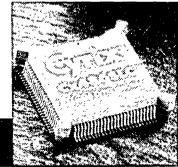
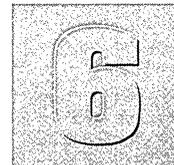
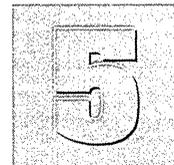
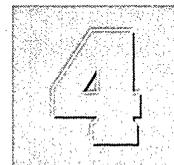
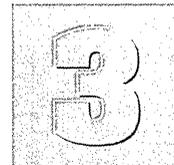
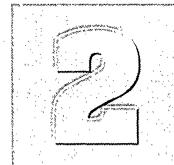


TABLE OF CONTENTS

1. Product Overview	
1.1 Introduction	1-1
1.2 Execution Pipeline	1-1
1.3 On-Chip Cache	1-2
1.4 Power Management	1-2
1.5 System Management Mode	1-3
1.6 Signal Summary	1-4
2. Programming Interface	
2.1 Processor Initialization	2-1
2.2 Instruction Set Overview	2-3
2.3 Register Set	2-4
2.4 Address Spaces	2-32
2.5 Interrupts and Exceptions	2-40
2.6 System Management Mode	2-47
2.7 Shutdown and Halt	2-53
2.8 Protection	2-55
2.9 Virtual 8086 Mode	2-58
3. Bus Interface	
3.1 Overview	3-1
3.2 Signal Descriptions	3-3
3.3 Functional Timing	3-12
4. Electrical Specifications	
4.1 Electrical Connections	4-1
4.2 Absolute Maximum Ratings	4-2
4.3 Recommended Operating Conditions	4-3
4.4 DC Characteristics	4-4
4.5 AC Characteristics	4-5
5. Mechanical Specifications	
5.1 Pin Assignments	5-1
5.2 Package Dimensions	5-4
5.3 Thermal Characteristics	5-5
6. Instruction Set	
6.1 General Instruction Format	6-1
6.2 Instruction Fields	6-2
6.3 Flags	6-10
6.4 Clock Counts	6-10



Appendix and Index

Paragraph Number		Page
A.1	Cx486SLC Stepping Revision History	A-1
A.2	Manual Revision History	A-1
A.3	Ordering Information	A-3
-	Index	A-4

LIST OF FIGURES

Figure Number	Figure Name	Page
1-1.	Cx486SLC/e Input and Output Signals	1-4
2-1.	Application Register Set	2-5
2-2.	General Purpose Registers	2-6
2-3.	Segment Selector	2-7
2-4.	EFLAGS Register	2-9
2-5.	System Register Set	2-12
2-6.	Control Registers	2-13
2-7.	Descriptor Table Registers	2-15
2-8.	Application and System Segment Descriptors	2-16
2-9.	Gate Descriptor	2-18
2-10.	Task Register	2-19
2-11.	32-Bit Task State Segment (TSS) Table	2-20
2-12.	16-Bit Task State Segment (TSS) Table	2-21
2-13.	Configuration Control Register CCR0	2-23
2-14.	Configuration Control Register CCR1	2-24
2-15.	Address Registers ARR1 - ARR4	2-25
2-16.	Debug Registers	2-26
2-17.	Test Registers	2-28
2-18.	Memory and I/O Address Space	2-32
2-19.	Offset Address Calculation	2-34
2-20.	Real Mode Address Calculation	2-35
2-21.	Protected Mode Address Calculation	2-36
2-22.	Selector Mechanism	2-36
2-23.	Paging Mechanism	2-38
2-24.	Directory and Page Table Entry (DTE and PTE) Format	2-38
2-25.	Error Code Format	2-46
2-26.	System Management Memory Address Space	2-47
2-27.	SMI Execution Flow Diagram	2-48

LIST OF FIGURES (Continued)

Figure Number	Figure Name	Page
2-28.	SMM Memory Address Space Header	2-49
2-29.	SMM and Suspend Mode Flow Diagram	2-54
3-1.	Cx486SLC/e Functional Signal Groupings	3-1
3-2.	Internal Processor Clock Synchronization	3-12
3-3.	Bus Activity from RESET until First Code Fetch	3-13
3-4.	Fastest Non-Pipelined Read Cycles	3-15
3-5.	Various Non-Pipelined Bus Cycles (no wait states)	3-16
3-6.	Various Non-Pipelined Bus Cycles with Different Numbers of Wait States	3-17
3-7.	Non-Pipelined Bus States	3-19
3-8.	Fastest Pipelined Read Cycles	3-20
3-9.	Various Pipelined Cycles (one wait state)	3-22
3-10.	Fastest Transition to Pipelined Address Following Idle Bus State	3-23
3-11.	Transitioning to Pipelined Address During Burst of Bus Cycles	3-24
3-12.	Complete Bus States	3-25
3-13.	Interrupt Acknowledge Cycles	3-27
3-14.	Non-Pipelined Bus Cycles Using BS16#	3-28
3-15.	Pipelining Shutdown Cycle	3-29
3-16.	Non-pipelined Halt Cycle using KEN#	3-31
3-17.	Pipelined Cache Fills using KEN#	3-32
3-18.	Masking A20 using A20M# During Burst of Bus Cycles	3-33
3-19.	Requesting Hold from Idle Bus State	3-35
3-20.	Requesting Hold from Active Non-Pipelined Bus	3-36
3-21.	Requesting Hold from Active Pipelined Bus	3-37
3-22.	SMI# Timing	3-39
3-23.	I/O Trap Timing	3-40
3-24.	SUSP# Initiated Suspend Mode	3-41
3-25.	Halt Initiated Suspend Mode	3-42
3-26.	Stopping CLK2 During Suspend Mode	3-43
3-27.	Entering and Exiting Float	3-44
4-1.	Drive Level and Measurement Points for Switching Characteristics	4-6
4-2.	CLK2 Timing Measurement Points	4-7
4-3.	Input Signal Setup and Hold Timing	4-11
4-4.	Output Signal Valid Delay Timing	4-12
4-5.	Data Write Cycle Valid Delay Timing	4-12
4-6.	Data Write Cycle Hold Timing	4-13
4-7.	Output Signal Float Delay and HLDA Valid Delay Timing	4-13
4-8.	RESET Setup and Hold Timing	4-14
5-1.	Top View of Package Pins	5-1
5-2.	100-Pin BQFP Package Dimensions	5-4
6-1.	General Instruction Format	6-1



LIST OF TABLES

Table Number	Table Name	Page
2-1.	Initialized Register Contents	2-2
2-2.	Segment Register Selection Rules	2-8
2-3.	EFLAGS Bit Definitions	2-10
2-4.	CR0 Bit Definitions	2-14
2-5.	Segment Descriptor Bit Definitions	2-17
2-6.	Gate Descriptor Bit Definitions	2-18
2-7.	Configuration Control	2-22
2-8.	CCR0 Bit Definitions	2-23
2-9.	CCR1 Bit Definitions	2-24
2-10.	ARR1 - ARR4 SIZE Field	2-25
2-11.	DR6 and DR7 Field Definitions	2-27
2-12.	TR6 and TR7 Bit Definitions	2-29
2-13.	TR6 Attribute Bit Pairs	2-30
2-14.	TR3 - TR5 Bit Definitions	2-31
2-15.	Memory Addressing Modes	2-34
2-16.	Directory and Page Table Entry (DTE and PTE) Bit Definitions	2-39
2-17.	Interrupt Vector Assignments	2-42
2-18.	Interrupt and Exception Priorities	2-44
2-19.	Exception Changes in Real Mode	2-45
2-20.	Error Code Bit Definitions	2-46
2-21.	SMM Memory Address Space Header	2-50
2-22.	SMM Instruction Set	2-51
2-23.	Descriptor Types Used for Control Transfer	2-57
3-1.	Cx486SLC/e Signal Summary	3-2
3-2.	Signal States During Reset	3-3
3-3.	Byte Enable Line Definitions	3-4
3-4.	Bus Cycle Types	3-5
3-5.	Signal States During Hold Acknowledge	3-10
3-6.	Signal States During Suspend Mode	3-11
4-1.	Pins Connected to Internal Pull-Up and Pull-Down Resistors	4-1
4-2.	Pins Requiring External Pull-Up Resistors	4-1
4-3.	Absolute Maximum Ratings	4-2
4-4.	Recommended Operating Conditions	4-3
4-5.	DC Characteristics (at Recommended Operating Conditions)	4-4
4-6.	Measurement Points for Switching Characteristics	4-5
4-7.	AC Characteristics for Cx486SLC/e-V20	4-8
4-8.	AC Characteristics for Cx486SLC/e-25; Cx486SLC/e-V25	4-9
4-9.	AC Characteristics for Cx486SLC/e-V33	4-10
5-1.	Signal Names Sorted by Pin Number	5-2



LIST OF TABLES (Continued)

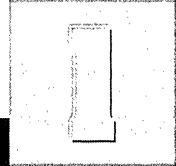
Table Number	Table Name	Page
5-2.	Pin Numbers Sorted by Signal Name	5-3
5-3.	Package Thermal Resistance and Airflow	5-5
5-4.	Cx486SLC/e Maximum Ambient Temperature (T_A) for Various Airflows and Clock Frequencies	5-6
5-5.	Cx486SLC/e-V Maximum Ambient Temperature (T_A) for Various Airflows and Clock Frequencies	5-6
6-1.	Instruction Fields	6-2
6-2.	Instruction Prefix Summary	6-3
6-3.	w Field Encoding	6-4
6-4.	d Field Encoding	6-4
6-5.	reg Field Encoding	6-5
6-6.	mod r/m Field Encoding	6-6
6-6A.	mod r/m Field Encoding Dependent on w Field	6-7
6-7.	mod base Field Encoding	6-8
6-8.	ss Field Encoding	6-8
6-9.	index Field Encoding	6-8
6-10.	sreg2 Field Encoding	6-9
6-11.	sreg3 Field Encoding	6-9
6-12.	eee Field Encoding	6-9
6-13.	Flag Abbreviations	6-10
6-14.	Action of Instruction on Flag	6-10
6-15.	Clock Count Abbreviations	6-11
6-16.	Instruction Set Summary	6-12





CYRIX Cx486SLC/e™ MICROPROCESSOR

High-Performance 486-Class CPU with Advanced Power Management for Notebook and Battery-Powered Systems



Product Overview

1. PRODUCT OVERVIEW

1.1 Introduction

The Cyrix® Cx486SLC/e™ microprocessor is an advanced 32-bit X86 compatible processor offering high performance and integrated power management on a single chip. The Cx486SLC/e is 486SX instruction set compatible and is backward compatible with the 386SX pinout. This CPU provides up to 2 or 3 times the performance of conventional 386SL and 386SX notebook computers at equal clock frequencies.

The Cx486SLC/e is an ideal solution for battery-powered applications in that it typically draws 0.40 mA while the input clock is stopped in suspend mode. Additionally, the Cyrix Cx486SLC/e System Management Mode (SMM) can be used for system power management or software emulation of I/O peripheral devices. The Cx486SLC/e-V version of the CPU offers additional power savings as it operates on a 3-volt as well as 5-volt power supply.

The Cx486SLC/e supports 8, 16 and 32-bit data types and operates in real, virtual 8086 and protected modes. This microprocessor achieves high performance through the use of a highly optimized variable length pipeline combined with a RISC-like single cycle execution unit, an on-chip hardware multiplier and an integrated instruction and data cache. The Cx486SLC/e is available at operating frequencies of 20, 25 and 33 MHz.

1.2 Execution Pipeline

The Cx486SLC/e execution path consists of five pipelined stages that are optimized for minimal instruction cycle times. These five stages are:

- Code Fetch
- Instruction Decode
- Microcode ROM Access
- Execution
- Memory/Register File Write-Back.

Each stage is designed with hardware interlocks which permit successive instruction execution overlap.

The 16-byte instruction prefetch queue fetches code in advance and prepares it for decode, helping to minimize overall execution time. The instruction decoder then decodes four bytes of instructions per clock eliminating the need for a queue of decoded instructions. Sequential instructions are decoded quickly and passed on to the microcode ROM stage of the pipeline. Non-sequential operations do not have to wait for a queue of decoded instructions to be flushed and refilled before execution continues. As a result, both sequential and non-sequential instruction execution times are minimized.

The execution stage takes advantage of a RISC-like single cycle execution unit and a 16-bit hardware multiplier. The write-back stage provides single cycle 32-bit access to the on-chip

cache and posts all writes to the cache and system bus using a two-deep write buffer. Posted writes allow the execution unit to proceed with program execution while the bus interface unit actually completes the write cycle.

1.3 On-Chip Cache

The Cx486SLC/e on-chip cache maximizes overall performance by quickly supplying instructions and data to the internal execution pipeline. On a 386SX system, an external memory access takes a minimum of two clock cycles (zero wait states). For cache hits, the Cx486SLC/e eliminates these two clock cycles by overlapping cache accesses with normal execution pipeline activity. Additional bus bandwidth is gained by presenting instructions and data to the execution pipeline up to 32 bits at a time compared to 16 bits per cycle for an external memory access.

The Cx486SLC/e cache is a 1 KByte write-through unified instruction and data cache. New lines are allocated only during memory read cycles. The cache can be configured as direct-mapped or as two-way set associative. The direct-mapped organization is a single set of 256 four-byte lines. When configured as two-way set associative, the cache organization consists of two sets of 128 four-byte lines and uses a Least Recently Used (LRU) replacement algorithm.

1.4 Power Management

1.4.1 Suspend Mode and Static Operation

The Cx486SLC/e power management features allow a dramatic reduction in current consumption when the CPU is in suspend mode (typically less than 2 percent of the operating current). Suspend mode is entered either by a hardware or software initiated action. Using the hardware to initiate suspend mode involves a two-pin handshake using the SUSP# and SUSPA# signals. The software initiates suspend mode through execution of the HALT instruction. Once in suspend mode, the Cx486SLC/e power consumption can be further reduced by stopping the external clock input. The resulting current draw is typically 0.40 mA. Since the Cx486SLC/e is a static device, no internal CPU data is lost when the clock input is stopped.

1.4.2 3-Volt Operation

The Cx486SLC/e-V version of the Cx486SLC/e operates from either a 3-volt or a 5-volt supply. While operating with a 3-volt supply, the power consumed by the 486SLC-V is typically only 30 percent of the power consumed while operating at 5 volts.

1.5 System Management Mode

System Management Mode (SMM) provides an additional interrupt and a separate address space which can be used for system power management or software transparent emulation of I/O peripherals. SMM is entered using the System Management Interrupt (SMI#) which has a higher priority than any other interrupt. While running in protected SMM address space, the SMI interrupt routine can execute without interfering with the operating system or application programs.

After reception of an SMI#, portions of the CPU state are automatically saved, SMM is entered and program execution begins at the base of SMM address space. The location and size of the SMM memory is programmable within the Cx486SLC/e. Seven SMM instructions have been added to the 486SX instruction set that permit saving and restoring of the total CPU state when in SMM mode.

1.6 Signal Summary

The Cx486SLC/e includes two power management signals (SUSP# and SUSPA#), four cache interface signals (FLUSH#, KEN#, RPLSET, and RPLVAL#), an A20 mask input (A20M#) and two SMM signals (SMADS# and SMI#) that are additions to the 386SX signal set. The complete list of Cx486SLC/e signals is shown in Figure 1-1.

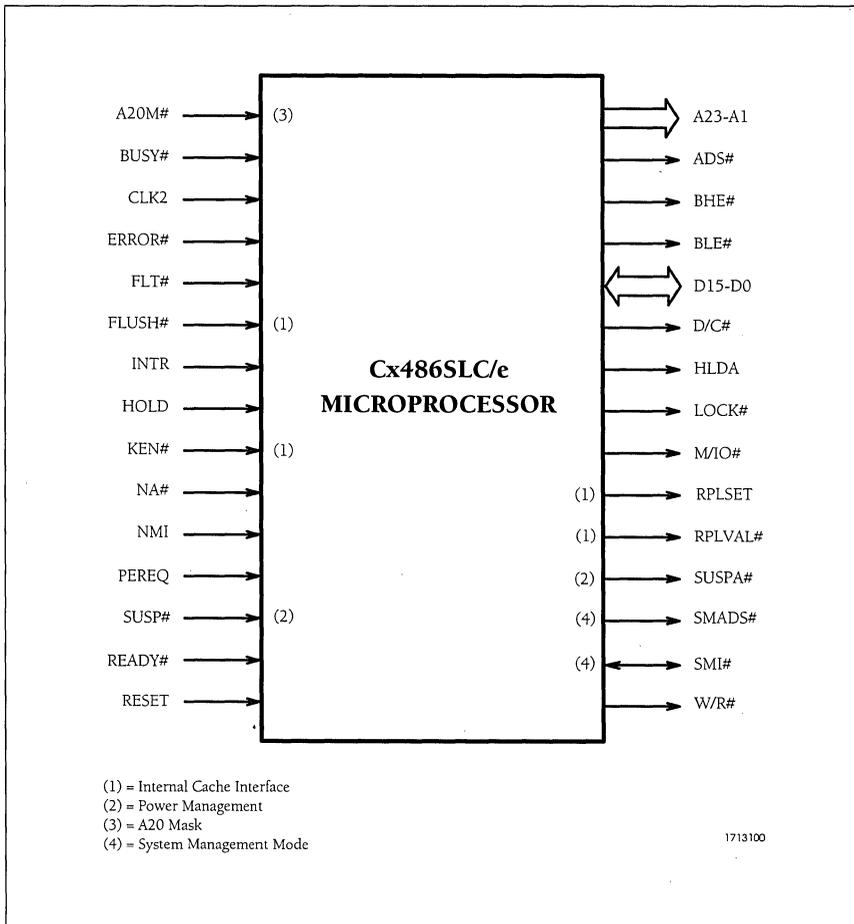


Figure 1-1. Cx486SLC/e Input and Output Signals



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High-Performance 486-Style CPU with Advanced Power Management for Notebook and Battery-Powered Systems



Programming Interface

2. PROGRAMMING INTERFACE

In this chapter, the internal operations of the Cx486SLC/e are described mainly from an application programmer's point of view. Included in this chapter are descriptions of processor initialization, the register set, memory addressing, various types of interrupts and the shutdown and halt process. Also included is an overview of real, virtual 8086, and protected operating modes.

2.1 Processor Initialization

The Cx486SLC/e is initialized when the RESET signal is asserted. The processor is placed in real mode and the registers listed in Table 2-1 are set to their initialized values. RESET invalidates and disables the Cx486SLC/e cache, and turns off

paging. When RESET is asserted, the Cx486SLC/e terminates all local bus activity and all internal execution. During the entire time that RESET is asserted, the internal pipeline is flushed and no instruction execution or bus activity occurs.

Approximately 350 to 450 CLK2 clock cycles (additional $2^{20} + 60$ if self-test is requested) after RESET is negated, the processor begins executing instructions at the top of physical memory (address location FF FFF0h). When the first intersegment JUMP or CALL is executed, address lines A23-A20 are driven low for code segment-relative memory access cycles. While A23-A20 are low, the Cx486SLC/e executes instructions only in the lowest 1 MByte of physical address space until system-specific initialization occurs via program execution.

Table 2-1. Initialized Register Contents

REGISTER	REGISTER NAME	INITIALIZED CONTENTS	COMMENTS
EAX	Accumulator	xxxx xxxxh	0000 0000h indicates self-test passed.
EBX	Base	xxxx xxxxh	
ECX	Count	xxxx xxxxh	
EDX	Data	xxxx 0400 + Revision ID	Revision ID = 11h.
EBP	Base Pointer	xxxx xxxxh	
ESI	Source Index	xxxx xxxxh	
EDI	Destination Index	xxxx xxxxh	
ESP	Stack Pointer	xxxx xxxxh	
EFLAGS	Flag Word	0000 0002h	
EIP	Instruction Pointer	0000 FFF0h	
ES	Extra Segment	0000h	Base address set to 0000 0000h. Limit set to FFFFh.
CS	Code Segment	F000h	Base address set to FFFF 0000h. Limit set to FFFFh.
SS	Stack Segment	0000h	Base address set to 0000 0000h. Limit set to FFFFh
DS	Data Segment	0000h	Base address set to 0000 0000h. Limit set to FFFFh.
FS	Extra Segment	0000h	Base address set to 0000 0000h. Limit set to FFFFh
GS	Extra Segment	0000h	Base address set to 0000 0000h. Limit set to FFFFh
IDTR	Interrupt Descriptor Table Register	Base = 0, Limit = 3FFh	
CR0	Machine Status Word	0000 0010h	
CCR0	Configuration Control 0	00h	
CCR1	Configuration Control 1	00h	
ARR1	Address Region 1	000Fh	4-GByte non-cacheable region.
ARR2	Address Region 2	0000h	
ARR3	Address Region 3	0000h	
ARR4	Address Region 4	0000h	
DR7	Debug Register DR7	0000 0400h	

Note: x= Undefined value

2.2 Instruction Set Overview

The Cx486SLC/e instruction set can be divided into eight types of operations:

- Arithmetic
- Bit Manipulation
- Control Transfer
- Data Transfer
- High-Level Language Support
- Operating System Support
- Shift/Rotate
- String Manipulation.

All Cx486SLC/e instructions operate on as few as 0 operands and as many as 3 operands. A NOP instruction (no operation) is an example of a 0 operand instruction. Two operand instructions allow the specification of an explicit source and destination pair as part of the instruction. These two operand instructions can be divided into eight groups according to operand types:

- Register to Register
- Register to Memory
- Memory to Register
- Memory to Memory
- Register to I/O
- I/O to Register
- Immediate Data to Register
- Immediate Data to Memory.

An operand can be held in the instruction itself (as in the case of an immediate operand), in a register, in an I/O port or in memory. An immediate operand is prefetched as part of the opcode for the instruction.

Operand lengths of 8, 16, or 32 bits are supported. Operand lengths of 8 or 32 bits are

generally used when executing code written for 386- or 486-class (32-bit code) processors.

Operand lengths of 8 or 16 bits are generally used when executing existing 8086 or 80286 code (16-bit code). The default length of an operand can be overridden by placing one or more instruction prefixes in front of the opcode. For example, by using prefixes, a 32-bit operand can be used with 16-bit code or a 16-bit operand can be used with 32-bit code.

Chapter 6 of this manual lists each instruction in the Cx486SLC/e instruction set along with the associated opcodes, execution clock counts and effects on the FLAGS register.

2.2.1 Lock Prefix

The LOCK prefix may be placed before certain instructions that read, modify, then write back to memory. The prefix asserts the LOCK# signal to indicate to the external hardware that the CPU is in the process of running multiple indivisible memory accesses. The LOCK prefix can be used with the following instructions:

- Bit Test Instructions (BTS, BTR, BTC)
- Exchange Instructions (XADD, XCHG, CMPXCHG)
- One-operand Arithmetic and Logical Instructions (DEC, INC, NEG, NOT)
- Two-operand Arithmetic and Logical Instructions (ADC, ADD, AND, OR, SBB, SUB, XOR).

An invalid opcode exception is generated if the LOCK prefix is used with any other instruction, or with the above instructions when no write operation to memory occurs (i. e., the destination is a register).

2.3 Register Set

There are 43 accessible registers in the Cx486SLC/e and these registers are grouped into two sets. The application register set contains the registers frequently used by application programmers, and the system register set contains the registers typically reserved for use by operating systems programmers.

The application register set is made up of:

- Eight 32-bit general purpose registers.
- Six 16-bit segment registers.
- One 32-bit flag register.
- One 32-bit instruction pointer register.

The system register set is made up of the remaining registers which include:

- Three 32-bit control registers.
- Two 48-bit and two 16-bit system address registers.
- Six 32-bit debug registers.
- Two 8-bit and four 16-bit configuration registers.
- Five 32-bit test registers.

Each of the registers is discussed in detail in the following sections.

2.3.1 Application Register Set

The application register set (Figure 2-1) consists of the registers most often used by the applications programmer. These registers are generally accessible and are not protected from read or write access.

The **General Purpose Registers** contents are frequently modified by assembly language instructions and typically contain arithmetic and logical instruction operands.

The **Segment Registers** contain segment selectors, which index into tables located in memory. These tables hold the base address for each segment, as well as other information related to memory addressing.

The **Flag Register** contains control bits used to reflect the status of previously executed instructions. This register also contains control bits that effect the operation of some instructions.

The **Instruction Pointer** register points to the next instruction that the processor will execute. This register is automatically incremented by the processor as execution progresses.

2.3.1.1 General Purpose Registers

The general purpose registers are divided into four data registers, two pointer registers, and two index registers as shown in Figure 2-2.

The **data registers** are used by the applications programmer to manipulate data structures and to hold the results of logical and arithmetic operations. Different portions of the general data registers can be addressed by using different names. An "E" prefix identifies the complete 32-bit register. An "X" suffix without the "E" prefix identifies the lower 16 bits of the register. The lower two bytes of the register can be addressed with an "H" suffix to identify the upper byte or an "L" suffix to identify the lower byte. When a destination operand size specified by an instruction is smaller than the specified destination register, the other bytes of the destination register are not affected when the operand is written to the register.

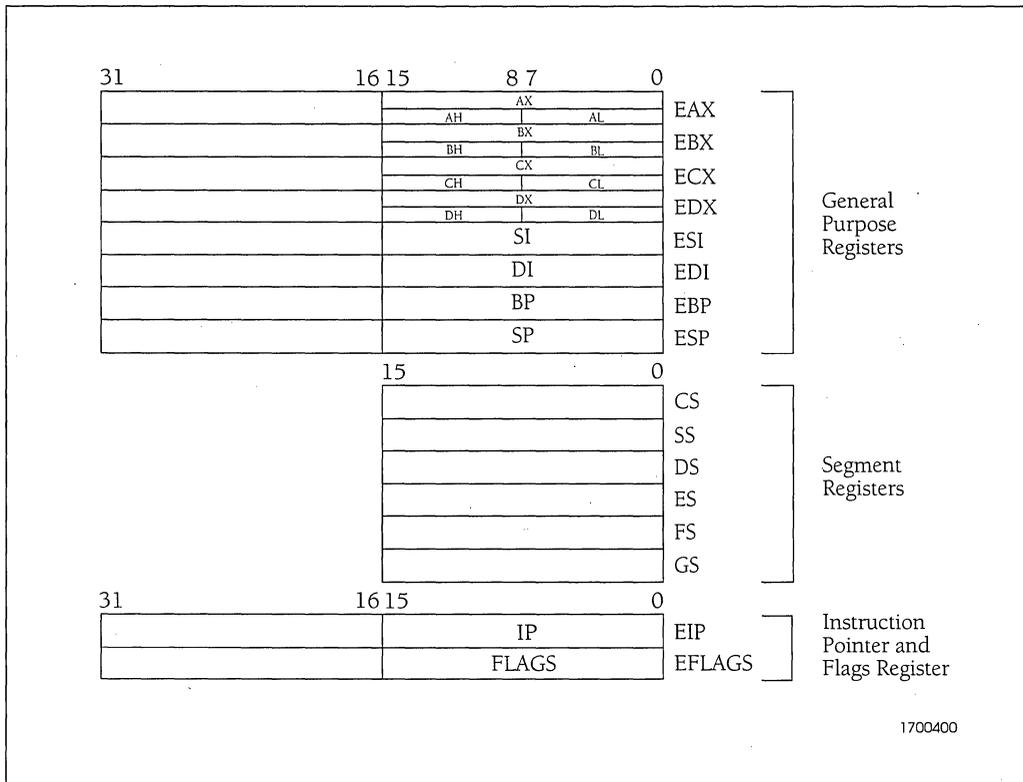


Figure 2-1. Application Register Set

The **pointer and index registers** are listed below:

SI or ESI	Source Index
DI or EDI	Destination Index
SP or ESP	Stack Pointer
BP or EBP	Base Pointer

These registers can be addressed as 16- or 32-bit registers, with the "E" prefix indicating 32 bits. The pointer and index registers can be used as general purpose registers, however, some instructions use a fixed assignment of these registers. For example, repeated string operations always use ESI as the source pointer, EDI as the destination pointer, and ECX as a counter. The instructions

using fixed registers include double-precision multiply and divide, I/O access, string operations, translate, loop, variable shift and rotate, and stack operations.

The Cx486SLC/e processor implements a stack using the ESP register. This stack is accessed during the PUSH and POP instructions, procedure calls, procedure returns, interrupts, exceptions, and

interrupt/exception returns. The microprocessor automatically adjusts the value of the ESP during operation of these instructions.

The EBP register may be used to reference data passed on the stack during procedure calls. Local data may also be placed on the stack and referenced relative to BP. This register provides a mechanism to access stack data in high-level languages.

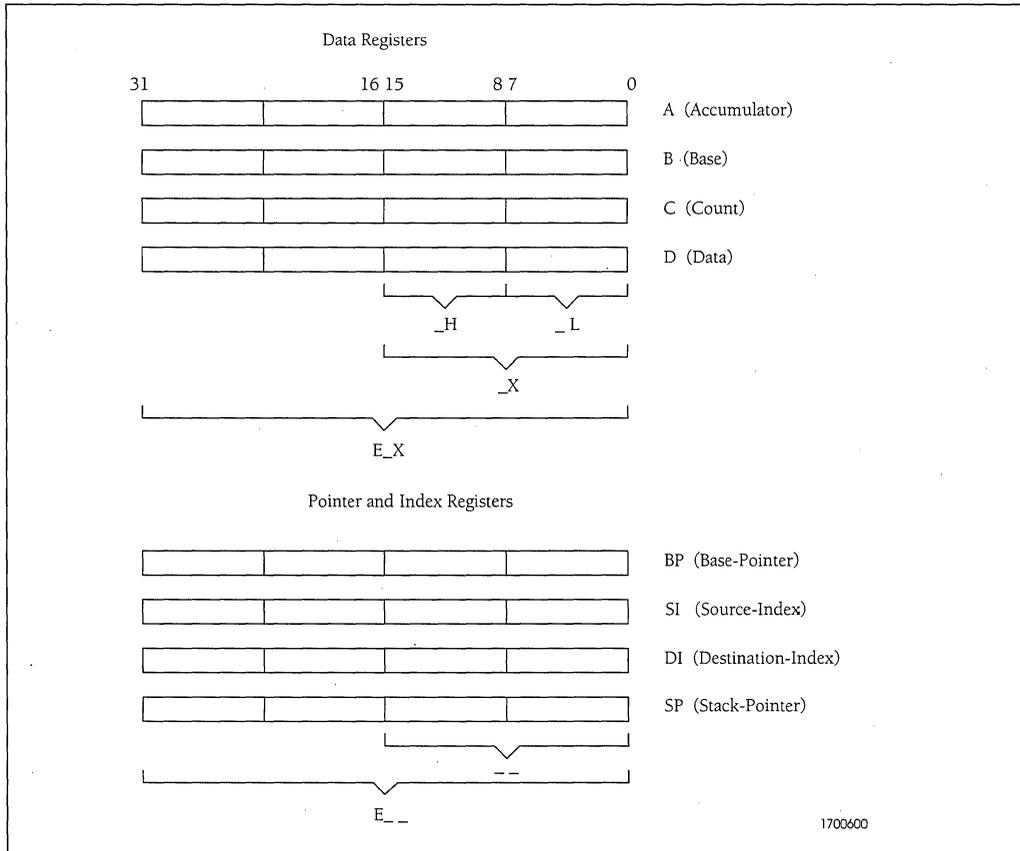


Figure 2-2. General Purpose Registers

2.3.1.2 Segment Registers and Selectors

Segmentation provides a means of defining data structures inside the memory space of the micro-processor. There are three basic types of segments: code, data, and stack. Segments are used automatically by the processor to determine the location in memory of code, data, and stack references.

There are six 16-bit segment registers:

CS	Code Segment
DS	Data Segment
ES	Extra Segment
SS	Stack Segment
FS	Additional Data Segment
GS	Additional Data Segment.

In real and virtual 8086 operating modes, a segment register holds a 16-bit segment base. The 16-bit segment base is multiplied by 16 and a 16-bit or 32-bit offset is then added to it to create a linear address. The offset size is dependent on the current address size. In real mode and in virtual 8086 mode with paging disabled, the linear address is also the physical address. In virtual 8086 mode with paging enabled, the linear

address is translated to the physical address using the current page tables.

In protected mode, a segment register holds a **segment selector** containing a 13-bit index, a table indicator (TI) bit, and a two-bit requested privilege level (RPL) field as shown in Figure 2-3.

The **Index** points into a *descriptor table* in memory and selects one of 8192 (2^{13}) segment descriptors contained in the descriptor table. A *segment descriptor* is an eight-byte value used to describe a memory segment by defining the segment base, the segment limit, and access control information. To address data within a segment, a 16-bit or 32-bit offset is added to the segment's base address. Once a segment selector has been loaded into a segment register, an instruction needs to specify the offset only.

The **Table Indicator** (TI) bit of the selector, defines which descriptor table the index points into. If TI=0, the index references the Global Descriptor Table (GDT). If TI=1, the index references the Local Descriptor Table (LDT). The GDT and LDT are described in more detail later in this chapter.

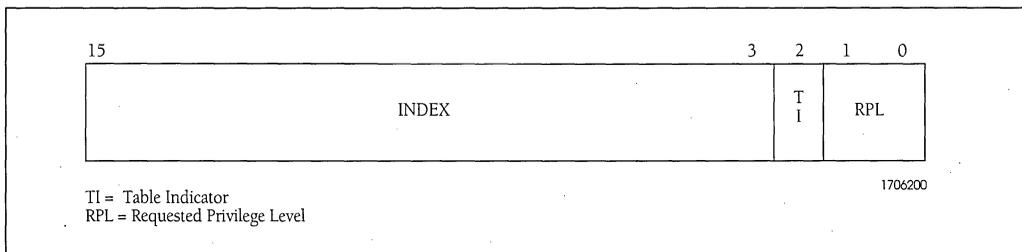


Figure 2-3. Segment Selector

The **Requested Privilege Level (RPL)** field contains a 2-bit segment privilege level (00=most privileged, 11= least privileged). The RPL bits are used when the segment register is loaded to determine the Effective Privilege Level (EPL). If the RPL bits indicate less privilege than the program, the RPL overrides the current privilege level and the EPL is the lower privilege level. If the RPL bits indicate more privilege than the program, the current privilege level overrides the RPL and again the EPL is the lower privilege level.

When a segment register is loaded with a segment selector, the segment base, segment limit and access rights are also loaded from the descriptor table into a user-invisible or hidden portion of the segment register, i.e., cached on-chip. The CPU does not access the descriptor table again until

another segment register load occurs. If the descriptor tables are modified in memory, the segment registers must be reloaded with the new selector values.

The processor automatically selects a default segment register for memory references. Table 2-2 describes the selection rules. In general, data references use the selector contained in the DS register, stack references use the SS register and instruction fetches use the CS register. While some of these selections may be overridden, instruction fetches, stack operations, and the destination write of string operations cannot be overridden. Special segment override prefixes allow the use of alternate segment registers including the use of the ES, FS, and GS segment registers.

Table 2-2. Segment Register Selection Rules

TYPE OF MEMORY REFERENCE	IMPLIED (DEFAULT) SEGMENT	SEGMENT OVERRIDE PREFIX
Code Fetch	CS	None
Destination of PUSH, PUSHF, INT, CALL, PUSHA instructions	SS	None
Source of POP, POPA, POPF, IRET, RET instructions	SS	None
Destination of STOS, MOVS, REP STOS, REP MOVS instructions	ES	None
Other data references with effective address using base registers of: EAX, EBX, ECX, EDX, ESI, EDI EBP, ESP	DS SS	CS, ES, FS, GS, SS CS, DS, ES, FS, GS

2.3.1.3 Instruction Pointer Register

The Instruction Pointer (EIP) register contains the offset into the current code segment of the next instruction to be executed. The register is normally incremented with each instruction execution unless implicitly modified through an interrupt, exception or an instruction that changes the sequential execution flow (e.g., jump, call).

2.3.1.4 Flags Register

The Flags Register, EFLAGS, contains status information and controls certain operations on the Cx486SLC/e microprocessor. The lower 16 bits of this register are referred to as the FLAGS register that is used when executing 8086 or 80286 code. The flag bits are shown in Figure 2-4 and defined in Table 2-3.

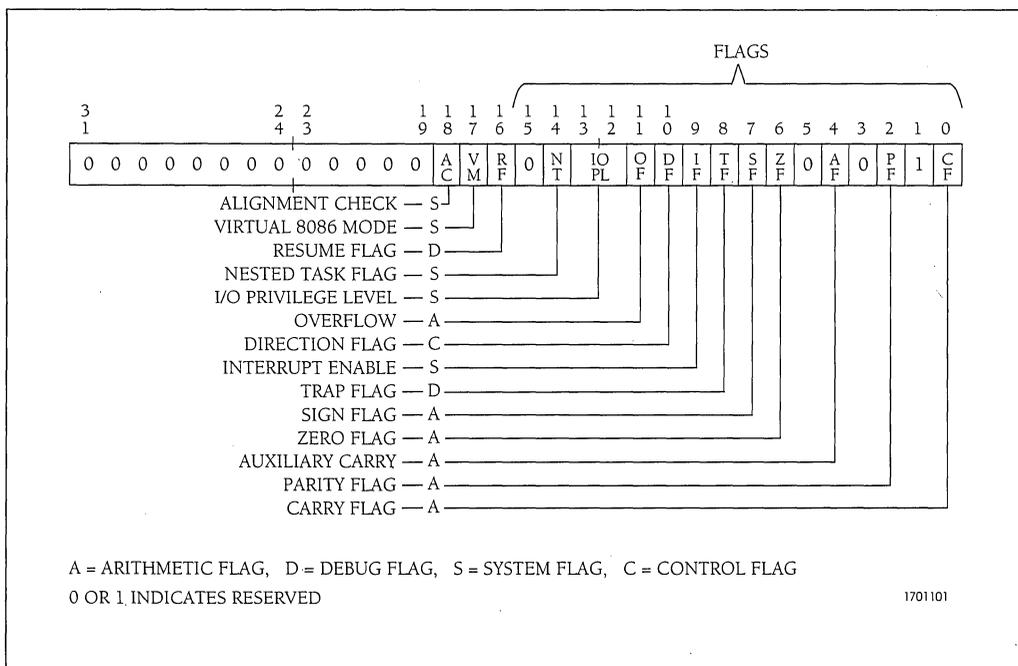


Figure 2-4. EFLAGS Register

Table 2-3. EFLAGS Bit Definitions

BIT POSITION	NAME	FUNCTION
0	CF	Carry Flag: Set when a carry out of (addition) or borrow into (subtraction) the most significant bit of the result occurs; cleared otherwise.
2	PF	Parity Flag: Set when the low-order 8 bits of the result contain an <i>even</i> number of ones; cleared otherwise.
4	AF	Auxiliary Carry Flag: Set when a carry out of (addition) or borrow into (subtraction) bit position 3 of the result occurs; cleared otherwise.
6	ZF	Zero Flag: Set if result is zero; cleared otherwise.
7	SF	Sign Flag: Set equal to high-order bit of result (0 indicates positive, 1 indicates negative).
8	TF	Trap Enable Flag: Once set, a single-step interrupt occurs after the next instruction completes execution. TF is cleared by the single-step interrupt.
9	IF	Interrupt Enable Flag: When set, maskable interrupts (INTR input pin) are acknowledged and serviced by the CPU.
10	DF	Direction Flag: When cleared, DF causes string instructions to auto-increment (default) the appropriate index registers (ESI and/or EDI). Setting DF causes auto-decrement of the index registers to occur.
11	OF	Overflow Flag: Set if the operation resulted in a carry or borrow into the sign bit of the result but did not result in a carry or borrow out of the high-order bit. Also set if the operation resulted in a carry or borrow out of the high-order bit but did not result in a carry or borrow into the sign bit of the result.
12, 13	IOPL	I/O Privilege Level: While executing in protected mode, IOPL indicates the maximum current privilege level (CPL) permitted to execute I/O instructions without generating an exception 13 fault or consulting the I/O permission bit map. IOPL also indicates the maximum CPL allowing alteration of the IF bit when new values are popped into the EFLAGS register.
14	NT	Nested Task: While executing in protected mode, NT indicates that the execution of the current task is nested within another task.
16	RF	Resume Flag: Used in conjunction with debug register breakpoints. RF is checked at instruction boundaries before breakpoint exception processing. If set, any debug fault is ignored on the next instruction.
17	VM	Virtual 8086 Mode: If set while in protected mode, the microprocessor switches to virtual 8086 operation handling segment loads as the 8086 does, but generating exception 13 faults on privileged opcodes. The VM bit can be set by the IRET instruction (if current privilege level=0) or by task switches at any privilege level.
18	AC	Alignment Check Enable: In conjunction with the AM flag in CRO, the AC flag determines whether or not misaligned accesses to memory cause a fault. If AC is set, alignment faults are enabled.

2.3.2 System Register Set

The system register set (Figure 2-5) consists of registers not generally used by application programmers. These registers are typically employed by system level programmers who generate operating systems and memory management programs.

The **Control Registers** control certain aspects of the Cx486SLC/e microprocessor such as paging, coprocessor functions, and segment protection. When a paging exception occurs while paging is enabled, the control registers retain the linear address of the access that caused the exception.

The **Descriptor Table Registers** and the **Task Register** can also be referred to as system address or memory management registers. These registers consist of two 48-bit and two 16-bit registers. These registers specify the location of the data structures that control the segmentation used by the Cx486SLC/e microprocessor. Segmentation is one available method of memory management.

The **Configuration Registers** are used to control the Cx486SLC/e on-chip cache operation, power management features and System Management Mode. The cache, power management and SMM features can be enabled or disabled by writing to these registers. Non-cacheable areas and write-protected areas of physical memory are also defined through the use of these registers.

The **Debug Registers** provide debugging facilities for the Cx486SLC/e microprocessor and enable the use of data access breakpoints and code execution breakpoints.

The **Test Registers** provide a mechanism to test the contents of both the on-chip 1 KByte cache and the translation lookaside buffer (TLB). The TLB is used as a cache for translating linear addresses to physical addresses when paging is enabled. In the following sections, the system register set is described in greater detail.

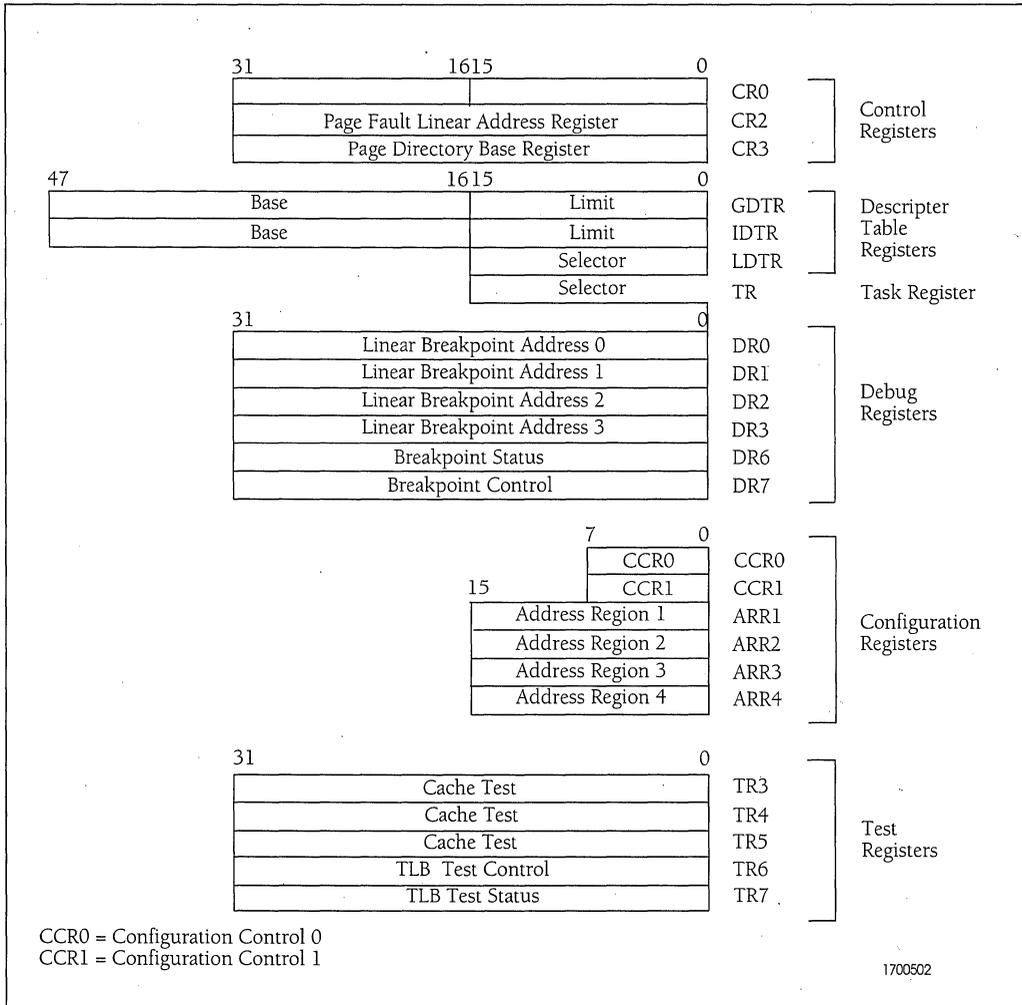


Figure 2-5. System Register Set

2.3.2.1 Control Registers

The control registers (CR0, CR2 and CR3), are shown in Figure 2-6. The CR0 register contains system control flags which control operating modes and indicate the general state of the CPU. The lower 16 bits of CR0 are referred to as the machine status word (MSW). The CR0 bit definitions are described in Table 2-4. The reserved bits in CR0 should not be modified.

When paging is enabled and a page fault is generated, the CR2 register retains the 32-bit linear

address of the address that caused the fault. CR3 contains the 20-bit base address of the page directory. The page directory must always be aligned to a 4 KByte page boundary, therefore, the lower 12 bits of CR3 are reserved.

When operating in protected mode, any program can read the control registers. However, only privilege level 0 (most privileged) programs can modify the contents of these registers.

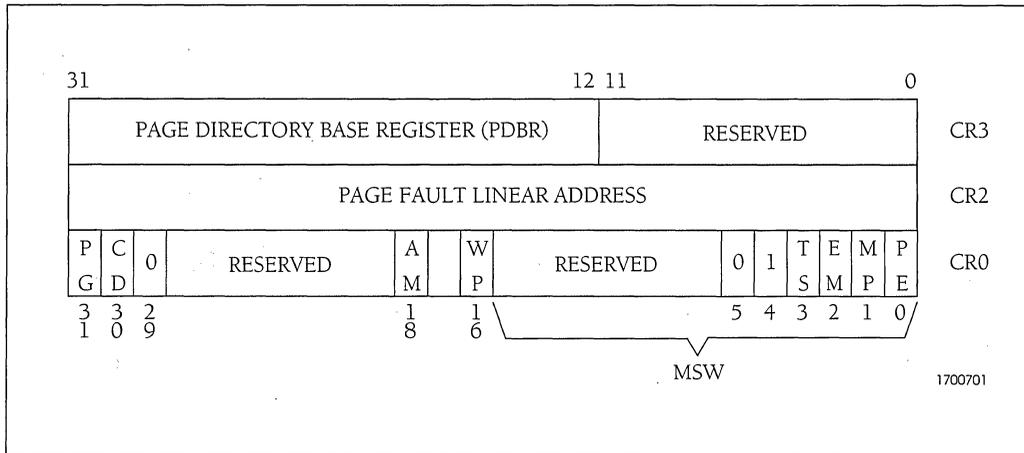


Figure 2-6. Control Registers

Table 2-4. CRO Bit Definitions

BIT POSITION	NAME	FUNCTION
0	PE	Protected Mode Enable: Enables the segment based protection mechanism. If PE=1, protected mode is enabled. If PE=0, the CPU operates in real mode, with segment based protection disabled, and addresses are formed as in an 8086-class CPU.
1	MP	Monitor Processor Extension: If MP=1 and TS=1, a WAIT instruction causes fault 7. The TS bit is set to 1 on task switches by the CPU. Floating point instructions are not affected by the state of the MP bit. The MP bit should be set to one during normal operations.
2	EM	Emulate Processor Extension: If EM=1, all floating point instructions cause a fault 7.
3	TS	Task Switched: Set whenever a task switch operation is performed. Execution of a floating point instruction with TS=1 causes a device not available (DNA) fault. If MP=1 and TS=1, a WAIT instruction also causes a DNA fault.
4	1	Reserved: Do not attempt to modify.
5	0	Reserved: Do not attempt to modify.
16	WP	Write Protect: Protects read-only pages from supervisor write access. The 386-type CPU allows a read-only page to be written from privilege level 0-2. The Cx486SLC/e CPU is compatible with the 386-type CPU when WP=0. WP=1 forces a fault on a write to a read-only page from any privilege level.
18	AM	Alignment Check Mask: If AM=1, the AC bit in the EFLAGS register is unmasked and allowed to enable alignment check faults. Setting AM=0 prevents AC faults from occurring.
29	0	Reserved: Do not attempt to modify.
30	CD	Cache Disable: If CD=1, no further cache fills occur. However, data already present in the cache continues to be used if the requested address hits in the cache. The cache must also be invalidated to completely disable any cache activity.
31	PG	Paging Enable Bit: If PG=1 and protected mode is enabled (PE=1), paging is enabled.

2.3.2.2 Descriptor Table Registers and Descriptors

Descriptor Table Registers

The Global, Interrupt and Local Descriptor Table Registers (GDTR, IDTR and LDTR), shown in Figure 2-7, are used to specify the location of the data structures that control segmented memory management. The GDTR, IDTR and LDTR are loaded using the LGDT, LIDT and LLDT instructions, respectively. The values of these registers are stored using the corresponding store instructions. The GDTR and IDTR load instructions are privileged instructions when operating in protected mode. The LDTR can only be accessed in protected mode.

The **Global Descriptor Table Register (GDTR)** holds a 32-bit base address and 16-bit limit for the Global Descriptor Table (GDT). The GDT is an array of up to 8192 8-byte descriptors. When a segment register is loaded from memory, the TI bit in the segment selector chooses either the GDT or the local descriptor table (LDT) to locate a descriptor. If TI = 0, the index portion of the selector is used to locate a given descriptor within

the GDT table. The contents of the GDTR are completely visible to the programmer. The first descriptor in the GDT (location 0) is not used by the CPU and is referred to as the "null descriptor". If the GDTR is loaded while operating in 16-bit operand mode, the Cx486SLC/e accesses a 32-bit base value but the upper 8 bits are ignored resulting in a 24-bit base address.

The Interrupt Descriptor Table Register

(IDTR) holds a 32-bit base address and 16-bit limit for the Interrupt Descriptor Table (IDT). The IDT is an array of 256 8-byte interrupt descriptors, each of which is used to point to an interrupt service routine. Every interrupt that may occur in the system must have an associated entry in the IDT. The contents of the IDTR are completely visible to the programmer.

The Local Descriptor Table Register (LDTR)

holds a 16-bit selector for the Local Descriptor Table (LDT). The LDT is an array of up to 8192 8-byte descriptors. When the LDTR is loaded, the LDTR selector indexes an LDT descriptor that must reside in the global descriptor table (GDT). The contents of the selected descriptor are cached

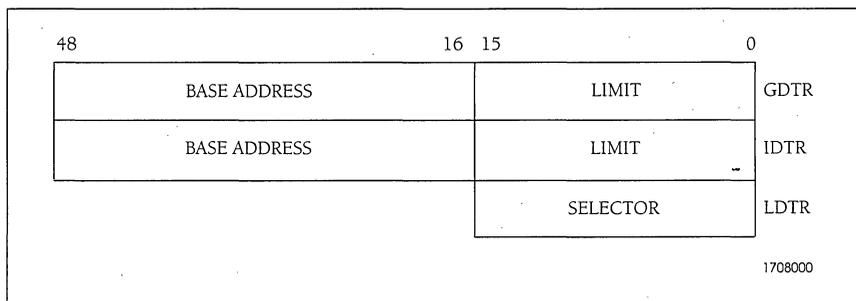


Figure 2-7. Descriptor Table Registers

on-chip in the hidden portion of the LDTR. The CPU does not access the GDT again until the LDTR is reloaded. If the LDT description is modified in memory in the GDT, the LDTR must be reloaded to update the hidden portion of the LDTR.

When a segment register is loaded from memory, the TI bit in the segment selector chooses either the GDT or the LDT to locate a segment descriptor. If TI = 1, the index portion of the selector is used to locate a given descriptor within the LDT. Each task in the system may be given its own LDT, managed by the operating system. The LDTs provide a method of isolating a given task's segments from other tasks in the system.

Descriptors

There are three types of descriptors:

- Application Segment Descriptors that define code, data and stack segments
- System Segment Descriptors that define an LDT segment or a TSS
- Gate Descriptors that define task gates, interrupt gates, trap gates and call gates.

Application Segment Descriptors can be located in either the LDT or GDT. System Segment Descriptors can only be located in the GDT. Dependent on the gate type, gate descriptors may be located in either the GDT, LDT or IDT. Figure 2-8 illustrates the descriptor format for both Application Segment Descriptors and System Segment Descriptors and Table 2-5 lists the corresponding bit definitions.

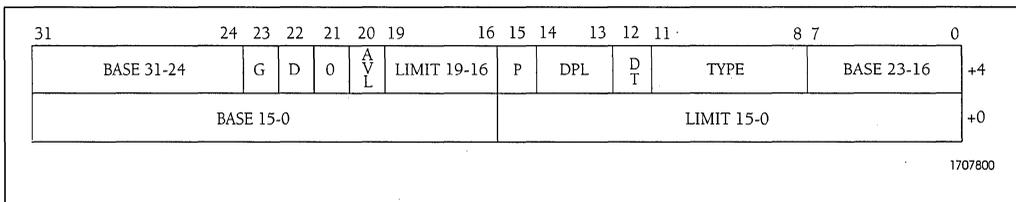


Figure 2-8. Application and System Segment Descriptors

Table 2-5. Segment Descriptor Bit Definitions

BIT POSITION	MEMORY OFFSET	NAME	DESCRIPTION
31-24 7-0 31-16	+4 +4 +0	BASE	Segment base address. 32-bit linear address that points to the beginning of the segment.
19-16 15-0	+4 +0	LIMIT	Segment limit. In real mode, the default segment limit is always 64 KBytes (0FFFFh).
23	+4	G	Limit granularity bit: 0 = byte granularity, 1 = 4 KBytes (page) granularity.
22	+4	D	Default length for operands and effective addresses. Valid for code and stack segments only: 0 = 16 bit, 1 = 32-bit.
20	+4	AVL	Segment available.
15	+4	P	Segment present.
14-13	+4	DPL	Descriptor privilege level.
12	+4	DT	Descriptor type: 0 = system, 1 = application.
11-8	+4	TYPE	Segment type. System descriptor (DT = 0): 0010 = LDT descriptor. 1001 = TSS descriptor, task not busy. 1011 = TSS descriptor, task busy.
11		E	Application descriptor (DT = 1): 0 = data, 1 = executable.
10		C/D	If E = 0: 0 = expand up, limit is upper bound of segment. 1 = expand down, limit is lower bound of segment. If E = 1: 0 = non-conforming. 1 = conforming (runs at privilege level of calling procedure).
9		R/W	If E = 0: 0 = non-readable. 1 = readable. If E = 1: 0 = non-writable. 1 = writable.
8		A	0 = not accessed, 1 = accessed.

Gate Descriptors provide protection for executable segments operating at different privilege levels. Figure 2-9 illustrates the format for Gate Descriptors and Table 2-6 lists the corresponding bit definitions.

Task Gate descriptors are used to switch the CPU's context during a task switch. The selector portion of the Task Gate descriptor locates a Task State Segment. Task Gate descriptors can be located in the GDT, LDT or IDT.

Interrupt Gate descriptors are used to enter a hardware interrupt service routine. Trap Gate descriptors are used to enter exceptions or software interrupt service routines. Trap Gate and Interrupt Gate descriptors can only be located in the IDT.

Call Gate descriptors are used to enter a procedure (subroutine) that executes at the same or a more privileged level. A Call Gate descriptor primarily defines the procedure entry point and the procedure's privilege level.

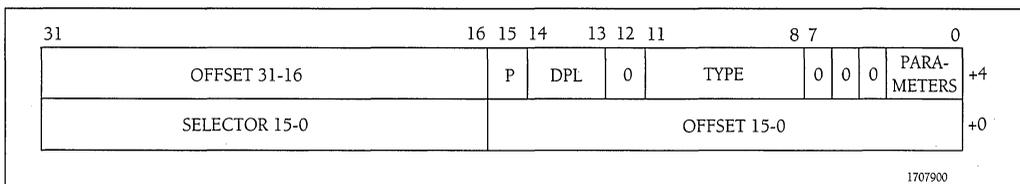


Figure 2-9. Gate Descriptor

Table 2-6. Gate Descriptor Bit Definitions

BIT POSITION	MEMORY OFFSET	NAME	DESCRIPTION
31-16 15-0	+4 +0	OFFSET	Offset used during a call gate to calculate the branch target.
31-16	+0	SELECTOR	Segment selector used during a call gate to calculate the branch target.
15	+4	P	Segment present.
14-13	+4	DPL	Descriptor privilege level.
11-8	+4	TYPE	Segment type: 0100 = 16-bit call gate 0101 = task gate 0110 = 16-bit interrupt gate 0111 = 16-bit trap gate 1100 = 32-bit call gate 1110 = 32-bit interrupt gate 1111 = 32-bit trap gate.
4-0	+4	Parameters	Number of 32-bit parameters to copy from the caller's stack to the called procedure's stack.

2.3.2.3 Task Register

The **Task Register (TR)** holds a 16-bit selector for the current **Task State Segment (TSS)** table as shown in Figure 2-10. The TR is loaded and stored via the LTR and STR instructions, respectively. The TR can only be accessed during protected mode and can only be loaded when the privilege level is 0 (most privileged). When the TR is loaded, the TR selector field indexes a TSS descriptor that must reside in the global descriptor

table (GDT). The contents of the selected descriptor are cached on-chip in the hidden portion of the TR.

During task switching, the processor saves the current CPU state in the TSS before starting a new task. The TR points to the current TSS. The TSS can be either a 286-type 16-bit TSS or a 386/486-type 32-bit TSS as shown in Figures 2-11 and 2-12. An I/O permission bit map is referenced in the 32-bit TSS by the I/O Map Base Address.

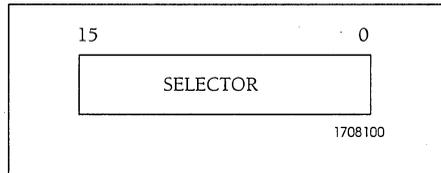


Figure 2-10. Task Register

31	16 15	0	
I/O MAP BASE ADDRESS		0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	T +64h
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0		SELECTOR FOR TASK'S LDT +60h	
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0		GS +5Ch	
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0		FS +58h	
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0		DS +54h	
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0		SS +50h	
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0		CS +4Ch	
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0		ES +48h	
		EDI +44h	
		ESI +40h	
		EBP +3Ch	
		ESP +38h	
		EBX +34h	
		EDX +30h	
		ECX +2Ch	
		EAX +28h	
		EFLAGS +24h	
		EIP +20h	
		CR3 +1Ch	
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0		SS for CPL = 2 +18h	
		ESP for CPL = 2 +14h	
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0		SS for CPL = 1 +10h	
		ESP for CPL = 1 +Ch	
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0		SS for CPL = 0 +8h	
		ESP for CPL = 0 +4h	
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0		BACK LINK (OLD TSS SELECTOR) +0h	

0 = RESERVED. 1708200

Figure 2-11. 32-Bit Task State Segment (TSS) Table

SELECTOR FOR TASK'S LDT	+2Ah
DS	+28h
SS	+26h
CS	+24h
ES	+22h
DI	+20h
SI	+1Eh
BP	+16h
SP	+1Ah
BX	+18h
DX	+16h
CX	+14h
AX	+12h
FLAGS	+10h
IP	+Eh
SP FOR PRIVILEGE LEVEL 2	+Ch
SS FOR PRIVILEGE LEVEL 2	+Ah
SP FOR PRIVILEGE LEVEL 1	+8h
SS FOR PRIVILEGE LEVEL 1	+6h
SP FOR PRIVILEGE LEVEL 0	+4h
SS FOR PRIVILEGE LEVEL 0	+2h
BACK LINK (OLD TSS SELECTOR)	+0h

1708800

Figure 2-12. 16-Bit Task State Segment (TSS) Table

2.3.2.4 Configuration Registers

The Cx486SLC/e contains six registers that do not exist on other x86 microprocessors. These registers include two 8-bit Configuration Control Registers (CCR0 and CCR1) and four 16-bit Address Region Registers (ARR1 through ARR4) as listed in Table 2-7. The CCR and ARR registers exist in I/O memory space and are selected by a "register index" number via I/O port 22h. I/O port 23h is used for data transfer.

Each I/O port 23h data transfer must be preceded by an I/O port 22h register selection, otherwise the second and later I/O port 23h operations are directed off-chip and produce external I/O cycles. If the register index number is outside the C0h - CFh range, external I/O cycles will also occur.

The CCR0 register (Figure 2-13, Table 2-8) defines the type of cache and determines if the 64-KByte memory area on 1-MByte boundaries and 640-KByte to 1-MByte area are cacheable. This register also enables certain pins associated with cache control and suspend mode.

The CCR1 register (Figure 2-14, Table 2-9) is used to setup internal cache operation and System Management Mode (SMM). The ARR registers (Figure 2-15, Table 2-10) are used to define the location and size of the memory regions associated with the internal cache. ARR1-ARR3 define three write protected or non-cacheable memory regions as designated by CCR1 bits WP1-WP3. ARR4 defines a SMM memory space or a non-cacheable memory region as defined by CCR1 bit SM4.

Other CCR1 bits enable RPL and SMM pins and control SMM memory access. The SMAC bit allows access to defined SMM space while not in an SMI service routine. The MMAC bit allows access to main memory that overlaps with SMM memory while in an SMI service routine for data accesses only.

The ARR registers define address regions using a starting address and a block size. The non-cacheable region block sizes range from 4 KBytes to 4 GByte (Table 2-10). A block size of zero disables the address region. The starting address of the address region must be on a block size boundary. For example, a 128 KByte block is allowed to have a starting address of 0 KBytes, 128 KBytes, 256 KBytes, etc. The SMM memory region size is restricted to a maximum of 16 MBytes. The SMM block size must be defined for SMI# to be recognized.

Table 2-7. Configuration Control Registers

REGISTER NAME	REGISTER INDEX	WIDTH
Configuration Control 0 CCR0	C0h	8
Configuration Control 1 CCR1	C1h	8
Address Region 1 ARR1	C5h, C6h	16
Address Region 2 ARR2	C8h, C9h	16
Address Region 3 ARR3	CBh, CCh	16
Address Region 4 ARR4	CEh, CFh	16

Note: The following register index numbers are reserved for future use: C2h, C3h, C4h, C7h, CAh, CDh and D0h through FFh.

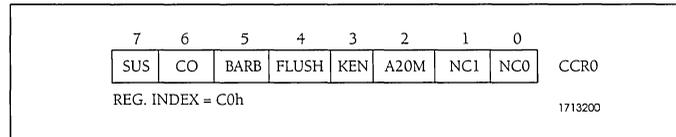
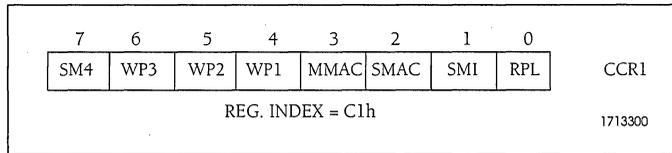


Figure 2-13. Configuration Control Register 0 (CCRO)

Table 2-8. CCRO Bit Definitions

BIT POSITION	NAME	DESCRIPTION
0	NC0	Non-cacheable 1-MByte Boundaries If=1: Sets the first 64 KBytes at each 1-MByte boundary as non-cacheable .
1	NC1	Non-cacheable Upper Memory Area If=1: Sets 640-KByte to 1-Mbyte memory region non-cacheable.
2	A20M	Enable A20M# Pin If=1: Enables A20M# input pin; otherwise pin is ignored.
3	KEN	Enable KEN# Pin If=1: Enables KEN# input pin; otherwise pin is ignored.
4	FLUSH	Enable FLUSH# Pin If=1: Enables FLUSH# input pin; otherwise pin is ignored.
5	BARB	Enable Cache Flush during Hold If=1: Enables flushing of internal cache when hold state is entered.
6	CO	Cache Type Select If=1: Selects direct-mapped cache. If =0: Selects 2-way set associative cache.
7	SUS	Enable Suspend Pins If=1: Enables SUSP# input pin and SUSPA# output pin. If=0: SUSPA# output pin floats, SUSP# input pin is ignored.


Figure 2-14. Configuration Control Register 1 (CCR1)
Table 2-9. CCR1 Bit Definitions

BIT POSITION	NAME	DESCRIPTION
0	RPL	Enable RPL Pins. If=1: RPLSET and RPLVAL# output pins are enabled. If=0: RPLSET and RPLVAL# pins float.
1	SMI	Enable SMM Pins. If=1: SMI# input/output pin and SMADS# output pin are enabled. If=0: SMI# input pin ignored and SMADS# output pin floats.
2	SMAC	System Management Memory Access. If=1: Any access to addresses within the SMM memory space cause external bus cycles to be issued with SMADS# output active. SMI# input is ignored. If=0: No effect on access.
3	MMAC	Main Memory Access. If=1: All data accesses which occur within an SMI service routine (or when SMAC=1) will access main memory instead of SMM memory space. If=0: No effect on access.
4	WP1	Address Region 1 Control. If=1: Region 1 is write protected and cacheable. If=0: Region 1 is non-cacheable.
5	WP2	Address Region 2 Control. If=1: Region 2 is write protected and cacheable. If=0: Region 2 is non-cacheable.
6	WP3	Address Region 3 Control. If=1: Region 3 is write protected and cacheable. If=0: Region 3 is non-cacheable.
7	SM4	Address Region 4 Control. If=1: Region 4 is non-cacheable SMM memory space. If=0: Region 4 is non-cacheable, SMI# input ignored.

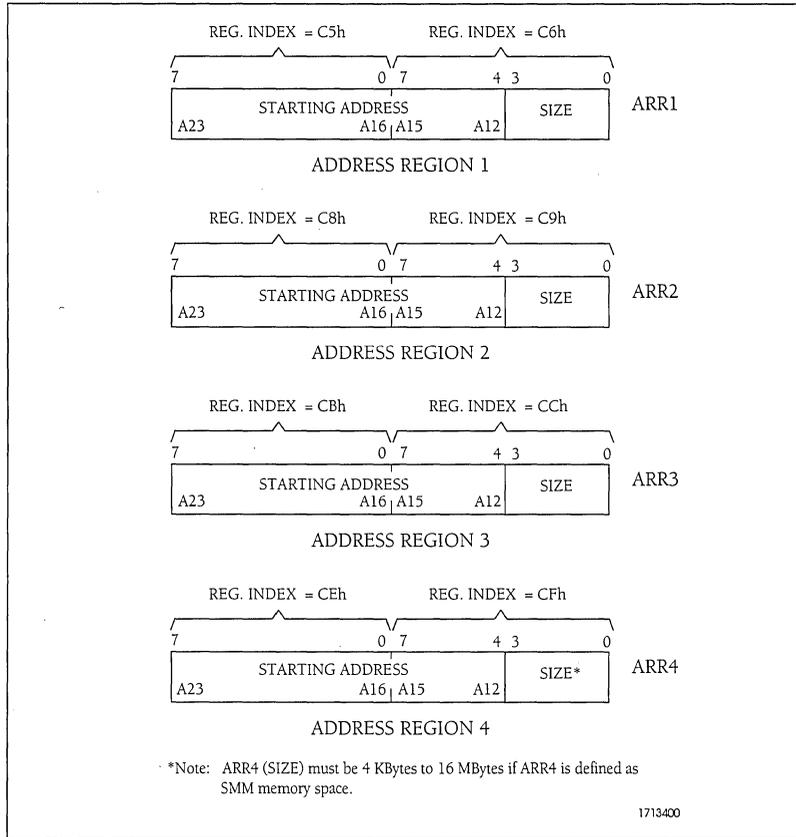


Figure 2-15. Address Region Registers (ARR1 - ARR4)

Table 2-10. ARR1 - ARR4 SIZE Field

BITS 3-0	BLOCK SIZE	BITS 3-0	BLOCK SIZE
0h	Disabled	8h	512 KBytes
1h	4 KBytes	9h	1 MBytes
2h	8 KBytes	Ah	2 MBytes
3h	16 KBytes	Bh	4 MBytes
4h	32 KBytes	Ch	8 MBytes
5h	64 KBytes	Dh	16 MBytes
6h	128 KBytes	Eh	32 MBytes
7h	256 KBytes	Fh	4 GBytes

2.3.2.5 Debug Registers

Six debug registers (DR0-DR3, DR6 and DR7), shown in Figure 2-16, support debugging on the Cx486SLC/e. Memory addresses loaded in the debug registers, referred to as "breakpoints", generate a debug exception when a memory access of the specified type occurs to the specified address. A breakpoint can be specified for a particular kind of

memory access such as a read or a write. Code and data breakpoints can also be set allowing debug exceptions to occur whenever a given data access (read or write) or code access (execute) occurs. The size of the debug target can be set to 1, 2, or 4 bytes. The debug registers are accessed via MOV instructions which can be executed only at privilege level 0.

3	3	2	2	2	2	2	2	2	2	1	1	1	1	1	1	1	1	1	0	9	8	7	6	5	4	3	2	1	0	
1	0	9	8	7	6	5	4	3	2	1	0	9	8	7	6	5	4	3	2	0	9	8	7	6	5	4	3	2	1	0
LEN	R/W	LEN	R/W	LEN	R/W	LEN	R/W	0	0	G	0	0	1	G	L	G	L	G	L	G	L	G	L	G	L	G	L	G	L	
3	3	2	2	1	1	0	0			D				E	E	3	3	2	2	1	1	0	0	1	1	0	0			
0	0	0	0	0	0	0	0	0	0	0	0	0	0	B	B	0	0	1	1	1	1	1	1	1	1	1	B	B	B	B
										T	S																			
BREAKPOINT 3 LINEAR ADDRESS																												DR3		
BREAKPOINT 2 LINEAR ADDRESS																												DR2		
BREAKPOINT 1 LINEAR ADDRESS																												DR1		
BREAKPOINT 0 LINEAR ADDRESS																												DR0		

ALL BITS MARKED AS 0 OR 1 ARE RESERVED AND SHOULD NOT BE MODIFIED.

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Figure 2-16. Debug Registers

The debug address registers DR0-DR3 each contain the linear address for one of four possible breakpoints. Each breakpoint is further specified by bits in the debug control register (DR7). For each breakpoint address in DR0-DR3, there are corresponding fields L, R/W, and LEN in DR7 that specify the type of memory access associated with the breakpoint.

The R/W field can be used to specify instruction execution as well as data access breakpoints. Instruction execution breakpoints are always taken

before execution of the instruction that matches the breakpoint.

The debug status register (DR6) reflects conditions that were in effect at the time the debug exception occurred. The contents of the DR6 register are not automatically cleared by the processor after a debug exception occurs and, therefore, should be cleared by software at the appropriate time.

Table 2-11 lists the field definitions for the DR6 and DR7 registers.

Table 2-11. DR6 and DR7 Field Definitions

REGISTER	FIELD	NUMBER OF BITS	DESCRIPTION
DR6	Bi	1	Bi is set by the processor if the conditions described by DRi, R/Wi, and LENi occurred when the debug exception occurred, even if the breakpoint is not enabled via the Gi or Li bits.
	BT	1	BT is set by the processor before entering the debug handler if a task switch has occurred to a task with the T bit in the TSS set.
	BS	1	BS is set by the processor if the debug exception was triggered by the single-step execution mode (TF flag in EFLAGS set).
DR7	R/Wi	2	Applies to the DRi breakpoint address register: 00 - Break on instruction execution only 01 - Break on data writes only 10 - Not used 11 - Break on data reads or writes.
	LENi	2	Applies to the DRi breakpoint address register: 00 - One byte length 01 - Two byte length 10 - Not used 11 - Four byte length.
	Gi	1	If set to a 1, breakpoint in DRi is globally enabled for all tasks and is not cleared by the processor as the result of a task switch.
	Li	1	If set to a 1, breakpoint in DRi is locally enabled for the current task and is cleared by the processor as the result of a task switch.
	GD	1	Global disable of debug register access. GD bit is cleared whenever a debug exception occurs.

Table 2-12. TR6 and TR7 Bit Definitions

REGISTER NAME	BIT POSITION	DESCRIPTION
TR6	31-12	Linear address. TLB lookup: The TLB is interrogated per this address. If one and only one match occurs in the TLB, the rest of the fields in TR6 and TR7 are updated per the matching TLB entry. TLB write: A TLB entry is allocated to this linear address.
	11	Valid bit (V). TLB write: If set, indicates that the TLB entry contains valid data. If clear, target entry is invalidated.
	10-9	Dirty attribute bit and its complement (D, D#). (Refer to Table 2-13).
	8-7	User/supervisor attribute bit and its complement (U, U#). (Refer to Table 2-13).
	6-5	Read/write attribute bit and its complement (R, R#). (Refer to Table 2-13).
	0	Command bit (C). If = 0: TLB write. If = 1: TLB lookup.
TR7	31-12	Physical address. TLB lookup: data field from the TLB. TLB write: data field written into the TLB.
	11	Page-level cache disable bit (PCD). Corresponds to the PCD bit of a page table entry.
	10	Page-level cache write-through bit (PWT). Corresponds to the PWT bit of a page table entry.
	9-7	LRU bits. TLB lookup: LRU bits associated with the TLB entry prior to the TLB lookup. TLB write: ignored.
	4	PL bit. TLB lookup: If = 1, read hit occurred. If = 0, read miss occurred. TLB write: If = 1, REP field is used to select the set. If = 0, the pseudo-LRU replacement algorithm is used to select the set.
	3-2	Set selection (REP). TLB lookup: If PL = 1, set in which the tag was found. If PL = 0, undefined data. TLB write: If PL = 1, selects one of the four sets for replacement. If PL=0, ignored.

Table 2-13. TR6 Attribute Bit Pairs

BIT (B)	BIT COMPLEMENT (B#)	EFFECT ON TLB LOOKUP	EFFECT ON TLB WRITE
0	0	Do not match.	Undefined.
0	1	Match if the bit is 0.	Clear the bit.
1	0	Match if the bit is 1.	Set the bit.
1	1	Match if the bit is 1 or 0.	Undefined.

Cache Test Registers

The Cx486SLC/e 1-KByte on-chip cache can be configured either as a direct-mapped (256 entries) or as a two-way set associative memory (128 entries per set). Each entry consists of a 23-bit tag, a 32-bit data field, four valid bits and an LRU bit. The 23-bit tag represents the high-order 23 bits of the physical address. The 32-bit data represents the four bytes of data currently in memory at the physical address represented by the tag. The four valid bits indicate which of the four data bytes actually contain valid data. The LRU bit is only accessed when the cache is configured as two-way set associative and indicates which of the two sets was most recently accessed.

The Cx486SLC/e contains three test registers that allow testing of its internal cache. Using these registers, cache test writes and reads may be performed. Cache test writes cause the data in TR3 to be written to the selected set and entry in the cache. Cache test reads allow inspection of the data, valid bits and the LRU bit for the cache entry. For data to be written to the allocated entry, the valid bits for the entry must be set prior to the write of the data. Bit definitions for the cache test registers are shown in Table 2-14.

Table 2-14. TR3-TR5 Bit Definitions

REGISTER NAME	BIT POSITION	DESCRIPTION
TR3	31-10	Cache data. Cache read: data accessed from the cache. Cache write: data to be written into the cache.
TR4	31-9	Tag address. Cache read: tag address from which data is read. Cache write: data written into the tag address of the selected entry.
	7	LRU Bit. (Used with two-way configuration only) Cache read: the LRU bit associated with the cache entry. Cache write: ignored.
	6-3	Valid Bits Cache read: valid bits for the accessed entry, (one bit per byte). Cache write: valid bits written into the entry.
TR5	10-4	Entry Selection Two-Way Configuration: Address bits 8-2 for selecting one of 128 entries. Direct-Mapped Configuration: Address bits 8-2 for selecting one of 256 entries. Cache read: TR5-bit 2 is address bit 9. Cache write: TR4-bit 9 is address bit 9.
	2	Two-Way Configuration: Set selection. If = 0: set 0 is selected. If = 1: set 1 is selected. Direct-Mapped Configuration: Cache read: Address bit 9 for selecting of one of 256 lines.
	1-0	Control bits. These bits control reading or writing the cache. If = 00: Ignored. If = 01: Cache write. If = 10: Cache read. If = 11: Cache flush (marks all entries as invalid).

2.4 Address Spaces

The Cx486SLC/e can directly address either memory or I/O space. Figure 2-18 illustrates the range of addresses available for memory address space and I/O address space. For the Cx486SLC/e, the addresses for physical memory range between 00 0000h and FF FFFFh (16 MBytes). The accessible I/O addresses space ranges between

00 0000h and 00 FFFFh (64 KBytes). The coprocessor communication space exists in upper I/O space between 80 00F8h and 80 00FFh. These coprocessor I/O ports are automatically accessed by the CPU whenever an ESC opcode is executed. The I/O locations 22h and 23h are used for Cx486SLC/e configuration register access.

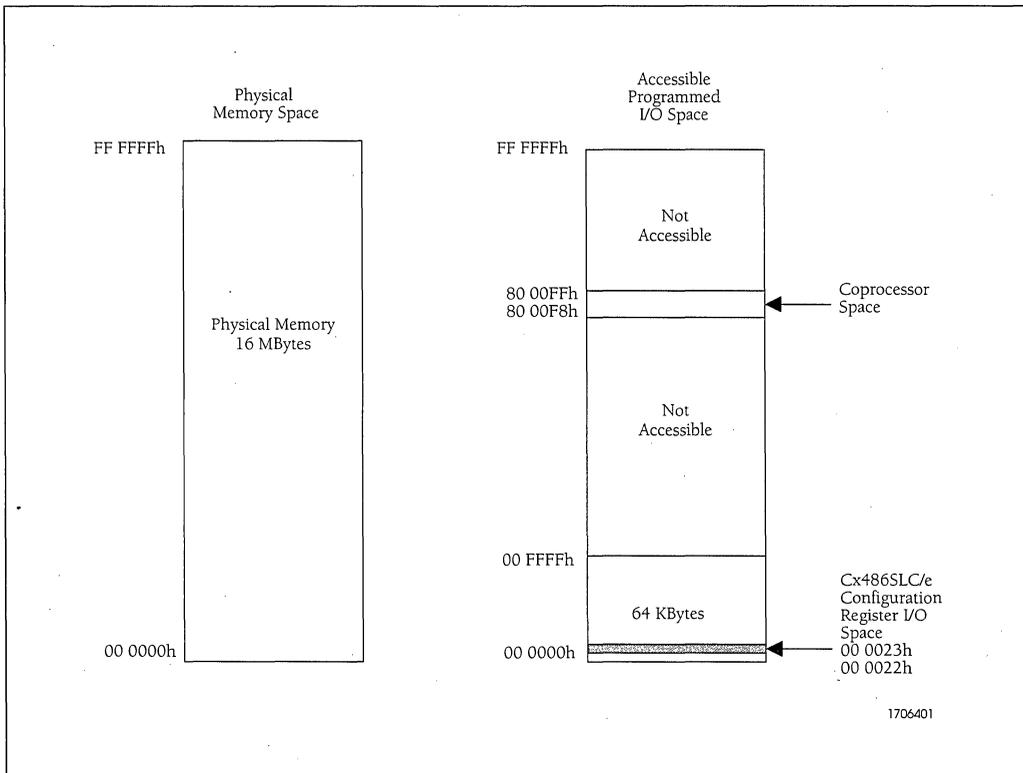


Figure 2-18. Memory and I/O Address Spaces

2.4.1 I/O Address Space

The Cx486SLC/e I/O address space is accessed using IN and OUT instructions to addresses referred to as "ports". The accessible I/O address space is 64 KBytes and can be accessed as 8-bit, 16-bit or 32-bit ports. The execution of any IN or OUT instruction causes the M/IO# pin to be driven low, thereby selecting the I/O space instead of memory space for loading or storing data. The upper 8 address bits are always driven low during IN and OUT instruction port accesses.

The Cx486SLC/e configuration registers reside within the I/O address space at port addresses 22h and 23h and are accessed using the standard IN and OUT instructions. The configuration registers are modified by writing the index of the configuration register to port 22h and then transferring the data through port 23h. Accesses to the on-chip configuration registers do not generate external I/O cycles. However, each port 23h operation must be preceded by a port 22h write with a valid index value. Otherwise, the second and later port 23h operations are directed off-chip and generate external I/O cycles without modifying the on-chip configuration registers. Also, writes to port 22h outside of the Cx486SLC/e index range (C0h to CFh) result in external I/O cycles and do not effect the on-chip configuration registers. Reads of port 22h are always directed off-chip.

2.4.2 Memory Address Space

The Cx486SLC/e directly addresses up to 16 MBytes of physical memory. Memory address space is accessed as bytes, words (16-bits) or doublewords (32-bits). Words and doublewords

are stored in consecutive memory bytes with the low-order byte located in the lowest address. The physical address of a word or doubleword is the byte address of the low-order byte.

With the Cx486SLC/e, memory can be addressed using nine different addressing modes. These addressing modes are used to calculate an offset address often referred to as an effective address. Depending on the operating mode of the CPU, the offset is then combined using memory management mechanisms to create a physical address that actually addresses the physical memory devices.

Memory management mechanisms on the Cx486SLC/e consist of segmentation and paging. Segmentation allows each program to use several independent, protected address spaces. Paging supports a memory subsystem that simulates a large address space using a small amount of RAM and disk storage for physical memory. Either or both of these mechanisms can be used for management of the Cx486SLC/e memory address space.

2.4.2.1 Offset Mechanism

The offset mechanism computes an offset (effective) address by adding together up to three values: a base, an index and a displacement. The base, if present, is the value in one of eight 32-bit general registers at the time of the execution of the instruction. The index, like the base, is a value that is contained in one of the 32-bit general registers (except the ESP register) when the instruction is executed. The index differs from the base in that the index is first multiplied by a scale factor of 1, 2, 4 or 8 before the summation is made. The third component added to the

memory address calculation is the displacement which is a value of up to 32-bits in length supplied as part of the instruction. Figure 2-19 illustrates the calculation of the offset address.

Nine valid combinations of the base, index, scale factor and displacement can be used with the Cx486SLC/e instruction set. These combinations are listed in Table 2-15. The base and index both refer to contents of a register as indicated by [Base] and [Index].

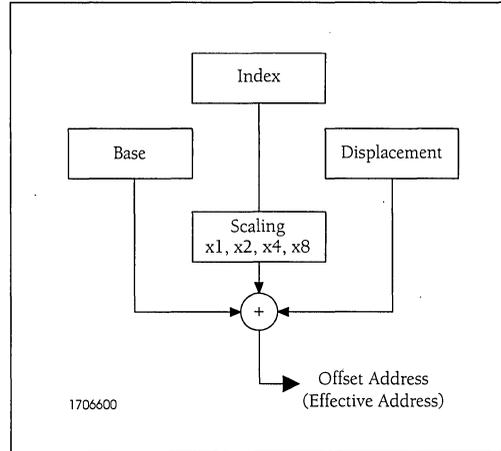


Figure 2-19. Offset Address Calculation

Table 2-15. Memory Addressing Modes

ADDRESSING MODE	BASE	INDEX	SCALE FACTOR (SF)	DISPLACEMENT (DP)	OFFSET ADDRESS (OA) CALCULATION
Direct				x	OA = DP
Register Indirect	x				OA = [BASE]
Based	x			x	OA = [BASE] + DP
Index		x		x	OA = [INDEX] + DP
Scaled Index		x	x	x	OA = ([INDEX] * SF) + DP
Based Index	x	x			OA = [BASE] + [INDEX]
Based Scaled Index	x	x	x		OA = [BASE] + ([INDEX] * SF)
Based Index with Displacement	x	x		x	OA = [BASE] + [INDEX] + DP
Based Scaled Index with Displacement	x	x	x	x	OA = [BASE] + ([INDEX] * SF) + DP

2.4.2.2 Real Mode Memory Addressing

In real mode operation, the Cx486SLC/e only addresses the lowest 1 MByte (2^{20}) of memory. To calculate a physical memory address, the 16-bit segment base address located in the selected segment register is multiplied by 16 and then the 16-bit offset address is added. The resulting 20-bit address is then extended with four zeros in the upper address bits to create the 24-bit physical address. Figure 2-20 illustrates the real mode address calculation. Physical addresses beyond 1 MByte cause a segment limit overrun exception.

The addition of the base address and the offset address may result in a carry. Therefore, the resulting address may actually contain up to 21 significant address bits that can address memory in the first 64 KBytes above 1 MByte.

2.4.2.3 Protected Mode Memory Addressing

In protected mode three mechanisms calculate a physical memory address (Figure 2-21).

- **Offset Mechanism** that produces the offset or effective address as in real mode.
- **Selector Mechanism** that produces the base address.
- Optional **Paging Mechanism** that translates a linear address to the physical memory address.

The offset and base address are added together to produce the linear address. If paging is not used, the linear address is used as the physical memory address. If paging is enabled, the paging mechanism is used to translate the linear address into the physical address. The offset mechanism is described earlier in this section and applies to both real and protected mode. The selector and paging mechanisms are described in the following paragraphs.

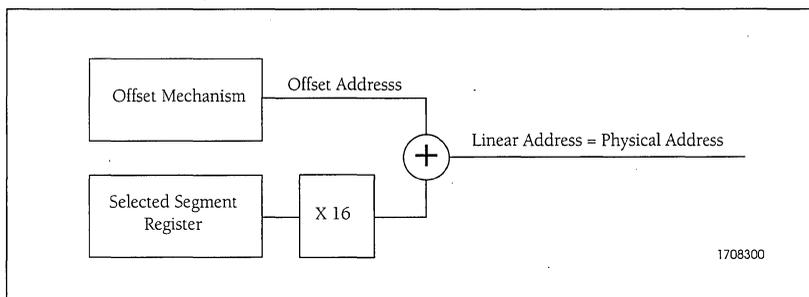


Figure 2-20. Real Mode Address Calculation

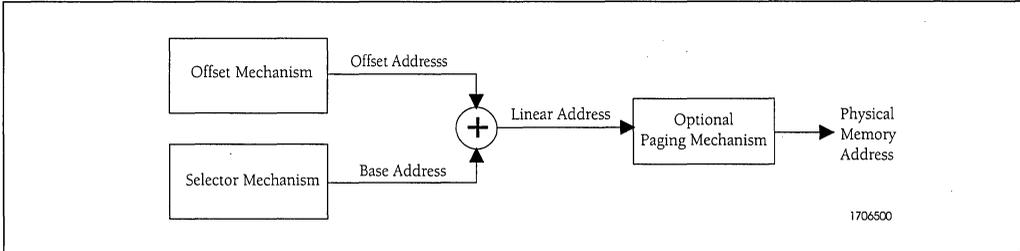


Figure 2-21. Protected Mode Address Calculation

Selector Mechanism

Memory is divided into an arbitrary number of segments, each containing usually much less than the 2³² byte (4 GByte) maximum.

The six segment registers (CS, DS, SS, ES, FS and GS) each contain a 16-bit selector that is used when the register is loaded to locate a segment descriptor in either the global descriptor table (GDT) or the local descriptor table (LDT). The segment descriptor defines the base address, limit

and attributes of the selected segment and is cached on the Cx486SLC/e as a result of loading the selector. The cached descriptor contents are not visible to the programmer. When a memory reference occurs in protected mode, the linear address is generated by adding the segment base address in the hidden portion of the segment register to the offset address. If paging is not enabled, this linear address is used as the physical memory address. Figure 2-22 illustrates the operation of the selector mechanism.

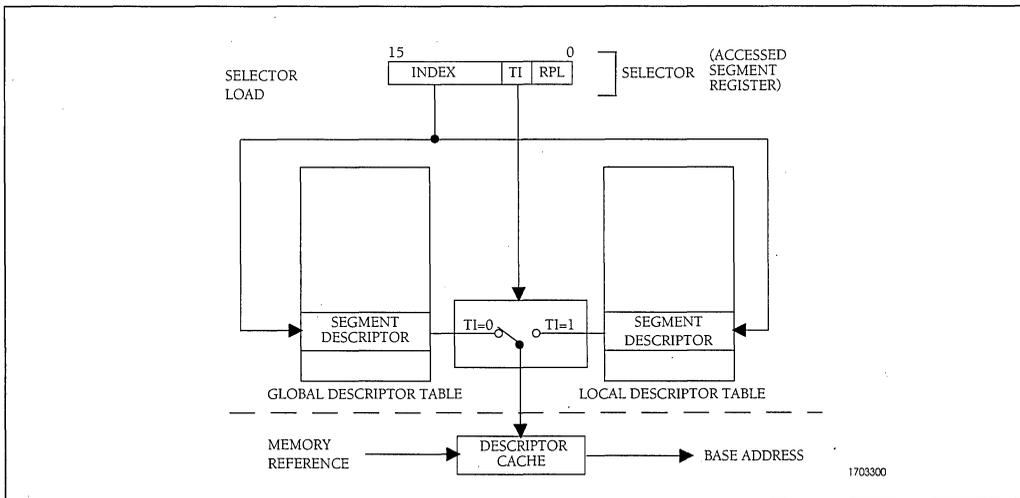


Figure 2-22. Selector Mechanism

Paging Mechanism

The paging mechanism supports a memory subsystem that simulates a large address space with a small amount of RAM and disk storage. The paging mechanism either translates a linear address to its corresponding physical address or generates an exception if the required page is not currently present in RAM. When the operating system services the exception, the required page is loaded into memory and the instruction is then restarted. Pages are either 4 KBytes or 1 MByte in size. The CPU defaults to 4-KByte pages that are aligned to 4 KByte boundaries.

A page is addressed by using two levels of tables as illustrated in Figure 2-23. The upper 10 bits of the 32-bit linear address are used to locate an entry in the **page directory table**. The page directory table acts as a 32-bit master index to up to 1K individual second-level page tables. The selected entry in the page directory table, referred to as the directory table entry, identifies the starting address of the second-level **page table**. The page directory table itself is a page and is, therefore, aligned to a 4 KByte boundary. The physical address of the current page directory is stored in the CR3 control register, also referred to as the Page Directory Base Register (PDBR).

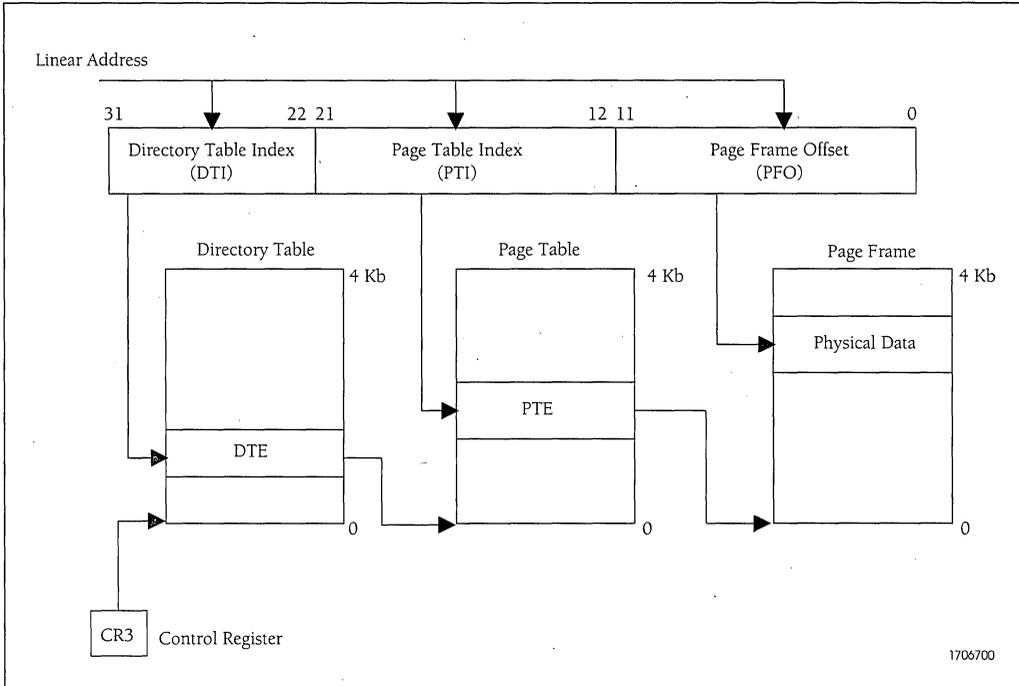
Bits 12-21 of the 32-bit linear address, referred to as the Page Table Index, locate a 32-bit entry in

the second-level page table. This Page Table Entry (PTE) contains the base address of the desired page frame. The second-level page table addresses up to 1K individual page frames. A second-level page table is 4 KBytes in size and is itself a page. The lower 12 bits of the 32-bit linear address, referred to as the Page Frame Offset (PFO), locate the desired data within the page frame.

Since the page directory table can point to 1K page tables, and each page table can point to 1K of page frames, a total of 1M of page frames can be implemented. Since each page frame contains 4 KBytes, up to 4 GBytes of virtual memory can be addressed by the Cx486SLC/e with a single page directory table.

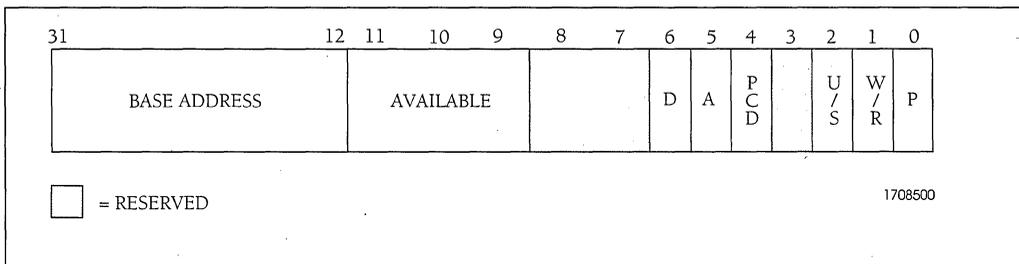
In addition to the base address of the page table or the page frame, each Directory Table Entry or Page Table Entry contains attribute bits and a present bit as illustrated in Figure 2-24 and listed in Table 2-16.

If the present bit (P) is set in the DTE, the page table is present and the appropriate page table entry is read. If P=1 in the corresponding PTE (indicating that the page is in memory), the accessed and dirty bits are updated, if necessary, and the operand is fetched. Both accessed bits are set (DTE and PTE), if necessary, to indicate that the table and the page have been used to translate a linear address. The dirty bit (D) is set before the first write is made to a page.



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Figure 2-23. Paging Mechanism



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Figure 2-24. Directory and Page Table Entry (DTE and PTE) Format

The present bits must be set to validate the remaining bits in the DTE and PTE. If either of the present bits are not set, a page fault is generated when the DTE or PTE is accessed. If P=0, the remaining DTE/PTE bits are available for use by the operating system. For example, the operating system can use these bits to record where on the hard disk the pages are located. A page fault is also generated if the memory reference violates the page protection attributes.

Translation Look-Aside Buffer

The translation look-aside buffer (TLB) is a cache for the paging mechanism and replaces the two-level page table lookup procedure for cache hits. The TLB is a four-way set associative 32-bit entry page table cache that automatically keeps the most commonly used page table entries in the processor. The 32-bit entry TLB, coupled with a 4K page size, results in coverage of 128 KBytes of memory addresses.

Table 2-16. Directory and Page Table Entry (DTE and PTE) Bit Definitions

BIT POSITION	FIELD NAME	DESCRIPTION
31 - 12	BASE ADDRESS	Specifies the base address of the page or page table.
11 - 9	--	Undefined and available to the programmer.
8 - 7	--	Reserved and not available to the programmer.
6	D	Dirty Bit. If set, indicates that a write access has occurred to the page (PTE only, undefined in DTE).
5	A	Accessed Flag. If set, indicates that a read access or write access has occurred to the page.
4	PCD	Page Caching Disable Flag. If set, indicates that the page is not cacheable in the on-chip cache.
3	--	Reserved and not available to the programmer.
2	U/S	User/Supervisor Attribute. If set (user), page is accessible at all privilege levels. ≤ 2 If clear (supervisor), page is accessible only when $CPL \leq 2$.
1	W/R	Write/Read Attribute. If set (write), page is writable. If clear (read), page is read only.
0	P	Present Flag. If set, indicates that the page is present in RAM memory, and validates the remaining DTE/PTE bits. If clear, indicates that the page is not present in memory and the remaining DTE/PTE bits can be used by the programmer.

The TLB must be flushed when entries in the page tables are changed. The TLB is flushed whenever the CR3 register is loaded. An individual entry in the TLB can be flushed using the INVLPG instruction.

2.5 Interrupts and Exceptions

The processing of either an interrupt or an exception changes the normal sequential flow of a program by transferring program control to a selected service routine. Except for SMM interrupts, the location of the selected service routine is determined by one of the interrupt vectors stored in the interrupt descriptor table.

All true interrupts are hardware interrupts and are generated by signal sources external to the CPU. All exceptions (including so-called software interrupts) are produced internally by the CPU.

2.5.2 Interrupts

External events can interrupt normal program execution by using one of the three interrupt pins on the Cx486SLC/e.

- Non-maskable Interrupt (NMI pin)
- Maskable Interrupt (INTR pin)
- SMM Interrupt (SMI# pin)

For most interrupts, program transfer to the interrupt routine occurs after the current instruction has been completed. When the execution returns to the original program, it begins immediately following the interrupted instruction.

The **NMI interrupt** cannot be masked by software and always uses interrupt vector 2 to locate its service routine. Since the interrupt vector is fixed and is supplied internally, no interrupt acknowledge bus cycles are performed. This interrupt is normally reserved for unusual situations such as parity errors and has priority over INTR interrupts.

Once NMI processing has started, no additional NMIs are processed until an IRET instruction is executed, typically at the end of the NMI service routine. If NMI is re-asserted prior to execution of the IRET instruction, one and only one NMI rising edge is stored and then processed after execution of the next IRET.

During the NMI service routine maskable interrupts are still enabled. If an unmasked INTR occurs during the NMI service routine, the INTR is serviced and execution returns to the NMI service routine following the next IRET. If a HALT instruction is executed within the NMI service routine, the Cx486SLC/e restarts execution only in response to RESET, an unmasked INTR or an SMM interrupt. NMI does not restart CPU execution under this condition.

The **INTR interrupt** is unmasked when the Interrupt Enable Flag (IF) in the EFLAGS register is set to 1. With the exception of string operations, INTR interrupts are acknowledged between instructions. Long string operations have interrupt windows between memory moves that allow INTR interrupts to be acknowledged.

When an INTR interrupt occurs, the CPU performs two locked interrupt acknowledge bus

cycles. During the second cycle, the CPU reads an 8-bit vector which is supplied by an external interrupt controller. This vector selects which of the 256 possible interrupt handlers will be executed in response to the interrupt.

The **SMM interrupt** has higher priority than either INTR or NMI. After SMI# is asserted, program execution is passed to an SMI service routine which runs in SMM address space reserved for this purpose. The remainder of this section does not apply to the SMM interrupts. SMM interrupts are described in greater detail later in this chapter.

2.5.2 Exceptions

Exceptions are generated by an interrupt instruction or a program error. Exceptions are classified as traps, faults or aborts depending on the mechanism used to report them and the restartability of the instruction which first caused the exception.

A **trap exception** is reported immediately following the instruction that generated the trap exception. Trap exceptions are generated by execution of a software interrupt instruction during single stepping, at a breakpoint or by software interrupt instruction (INTO, INT 3, INT n, BOUND), by a single-step operation or by a data breakpoint.

Software interrupts can be used to simulate hardware interrupts. For example, an INT n instruction causes the processor to execute the interrupt service routine pointed to by the nth vector in the interrupt table. Execution of the interrupt service routine occurs regardless of the state of the IF flag in the EFLAGS register.

The one byte INT 3, or breakpoint interrupt (vector 3), is a particular case of the INT n instruction. By inserting this one byte instruction in a program, the user can set breakpoints in the code that can be used during debug.

Single-step operation is enabled by setting the TF bit in the EFLAGS register. When TF is set, the CPU generates a debug exception (vector 1) after the execution of every instruction. Data breakpoints also generate a debug exception and are specified by loading the debug registers (DR0-DR7) with the appropriate values.

A **fault exception** is caused by a program error and is reported prior to completion of the instruction that generated the exception. By reporting the fault prior to instruction completion, the CPU is left in a state which allows the instruction to be restarted and the effects of the faulting instruction to be nullified. Fault exceptions include divide-by-zero errors, invalid opcodes, page faults and coprocessor errors. Debug exceptions (vector 1) are also handled as faults (except for data breakpoints and single-step operations). After execution of the fault service routine, the instruction pointer points to the instruction that caused the fault.

An **abort exception** is a type of fault exception that is severe enough that the CPU cannot restart the program at the faulting instruction. Abort exceptions include the double fault (vector 8) and coprocessor segment overrun (vector 9).

2.5.3 Interrupt Vectors

When the CPU services an interrupt or exception, the current program's instruction pointer and flags are pushed onto the stack to allow resumption of execution of the interrupted program. In protected mode, the processor also saves an error code for some exceptions. Program control is then transferred to the interrupt handler (also called the interrupt service routine). Upon execution of an IRET at the end of the service routine, program

execution resumes at the instruction pointer address saved on the stack when the interrupt was serviced.

Interrupt Vector Assignments

Each interrupt (except SMI#) and exception is assigned one of 256 interrupt vector numbers (Table 2-17). The first 32 interrupt vector assignments are defined or reserved. INT instructions acting as software interrupts may use any of interrupt vectors, 0 through 255.

Table 2-17. Interrupt Vector Assignments

INTERRUPT VECTOR	FUNCTION	EXCEPTION TYPE
0	Divide error	FAULT
1	Debug exception	TRAP/FAULT
2	NMI interrupt	
3	Breakpoint	TRAP
4	Interrupt on overflow	TRAP
5	BOUND range exceeded	FAULT
6	Invalid opcode	FAULT
7	Device not available	FAULT
8	Double fault	ABORT
9	Coprocessor segment overrun	ABORT
10	Invalid TSS	FAULT
11	Segment not present	FAULT
12	Stack fault	FAULT
13	General protection fault	TRAP/FAULT
14	Page fault	FAULT
15	Reserved	
16	Coprocessor error	FAULT
17	Alignment check exception	FAULT
18-31	Reserved	
32-255	Maskable hardware interrupts	TRAP
0-255	Programmed interrupt	TRAP

Note: Data breakpoints and single-step are traps. All other debug exceptions are faults.

The non-maskable hardware interrupt (NMI) is assigned vector 2.

In response to a maskable hardware interrupt (INTR), the Cx486SLC/e issues interrupt acknowledge bus cycles used to read the vector number from external hardware. These vectors should be in the range 32 - 255 as vectors 0 - 31 are pre-defined.

Interrupt Descriptor Table

The interrupt vector number is used by the Cx486SLC/e to locate an entry in the interrupt descriptor table (IDT). In real mode, each IDT entry consists of a four-byte far pointer to the beginning of the corresponding interrupt service routine. In protected mode, each IDT entry is an eight-byte descriptor. The Interrupt Descriptor Table Register (IDTR) specifies the beginning address and limit of the IDT. Following reset, the IDTR contains a base address of 0h with a limit of 3FFh.

The IDT can be located anywhere in physical memory as determined by the IDTR register. The IDT may contain different types of descriptors: interrupt gates, trap gates and task gates. Interrupt gates are used primarily to enter a hardware interrupt handler. Trap gates are generally used to enter an exception handler or software interrupt handler. If an interrupt gate is used, the Interrupt Enable Flag (IF) in the EFLAGS register is cleared before the interrupt handler is entered. Task gates are used to make the transition to a new task.

2.5.4 Interrupt and Exception Priorities

As the Cx486SLC/e executes instructions, it follows a consistent policy for prioritizing exceptions and hardware interrupts. The priorities for competing interrupts and exceptions are listed in Table 2-18. SMM interrupts always take precedence. Debug traps for the previous instruction and next instructions are handled as the next priority. When NMI and maskable INTR interrupts are both detected at the same instruction boundary, the Cx486SLC/e microprocessor services the NMI interrupt first.

The Cx486SLC/e checks for exceptions in parallel with instruction decoding and execution. Several exceptions can result from a single instruction. However, only one exception is generated upon each attempt to execute the instruction. Each exception service routine should make the appropriate corrections to the instruction and then restart the instruction. In this way, exceptions can be serviced until the instruction executes properly.

The Cx486SLC/e supports instruction restart after all faults, except when an instruction causes a task switch to a task whose task state segment (TSS) is partially not present. A TSS can be partially not present if the TSS is not page aligned and one of the pages where the TSS resides is not currently in memory.

Table 2-18. Interrupt and Exception Priorities

PRIORITY	DESCRIPTION	NOTES
0	SMM hardware interrupt.	SMM interrupts are caused by SMI# asserted and always have highest priority.
1	Debug traps and faults from previous instruction.	Includes single-step trap and data breakpoints specified in the debug registers.
2	Debug traps for next instruction.	Includes instruction execution breakpoints specified in the debug registers.
3	Non-maskable hardware interrupt.	Caused by NMI asserted.
4	Maskable hardware interrupt.	Caused by INTR asserted and IF = 1.
5	Faults resulting from fetching the next instruction.	Includes segment not present, general protection fault and page fault.
6	Faults resulting from instruction decoding.	Includes illegal opcode, instruction too long, or privilege violation.
7	WAIT instruction and TS = 1 and MP = 1.	Device not available exception generated.
8	ESC instruction and EM = 1 or TS = 1.	Device not available exception generated.
9	Coprocessor error exception.	Caused by ERROR# asserted.
10	Segmentation faults (for each memory reference required by the instruction) that prevent transferring the entire memory operand.	Includes segment not present, stack fault, and general protection fault.
11	Page Faults that prevent transferring the entire memory operand.	
12	Alignment check fault.	

2.5.5 Exceptions in Real Mode

Many of the exceptions described in Table 2-17 are not applicable in real mode. Exceptions 10, 11, and 14 do not occur real mode. Other exceptions have slightly different meanings in real mode as listed in Table 2-19.

Table 2-19. Exception Changes in Real Mode

VECTOR NUMBER	PROTECTED MODE FUNCTION	REAL MODE FUNCTION
8	Double fault.	Interrupt table limit overrun.
10	Invalid TSS.	--
11	Segment not present.	--
12	Stack fault.	SS segment limit overrun.
13	General protection fault.	CS, DS, ES, FS, GS segment limit overrun.
14	Page fault.	--

Note: -- = does not occur

2.5.6 Error Codes

When operating in protected mode, the following exceptions generating a 16-bit error code:

- Double Fault
- Alignment Check
- Invalid TSS
- Segment Not Present
- Stack Fault
- General Protection Fault
- Page Fault

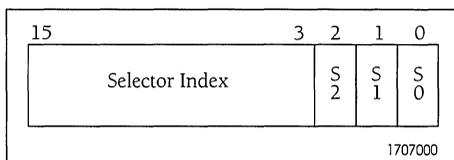


Figure 2-25. Error Code Format

The error code format is shown in Figure 2-25 and the error code bit definitions are listed in Table 2-20. Bits 15-3 (selector index) are not meaningful if the error code was generated as the result of a page fault. The error code is always zero for double faults and alignment check exceptions.

Table 2-20. Error Code Bit Definitions

FAULT TYPE	SELECTOR INDEX (BITS 15-3)	S2 (BIT 2)	S1 (BIT 1)	S0 (BIT 0)
Page Fault	Reserved	Fault caused by: 0 = not present page 1 = page-level protection violation.	Fault occurred during: 0 = read access 1 = write access.	Fault occurred during: 0 = supervisor access 1 = user access.
IDT Fault	Index of faulty IDT selector.	Reserved	1	If = 1, exception occurred while trying to invoke exception or hardware interrupt handler.
Segment Fault	Index of faulty selector.	T1 bit of faulty selector.	0	If = 1, exception occurred while trying to invoke exception or hardware interrupt handler.

2.6 System Management Mode

2.6.1 Introduction

System Management Mode (SMM) provides an additional interrupt which can be used for system power management or software transparent emulation of I/O peripherals. SMM is entered using the System Management Interrupt (SMI#) which has a higher priority than any other interrupt, including NMI. After reception of an SMI#,

portions of the CPU state are automatically saved, SMM is entered and program execution begins at the base of SMM address space (Figure 2-26). Running in protected SMM address space, the interrupt routine does not interfere with the operating system or any application program.

Seven SMM instructions have been added to the 486SX instruction set that permit saving and restoring of the total CPU state when in SMM mode. Two new pins, SMI# and SMADS#, support SMM functions.

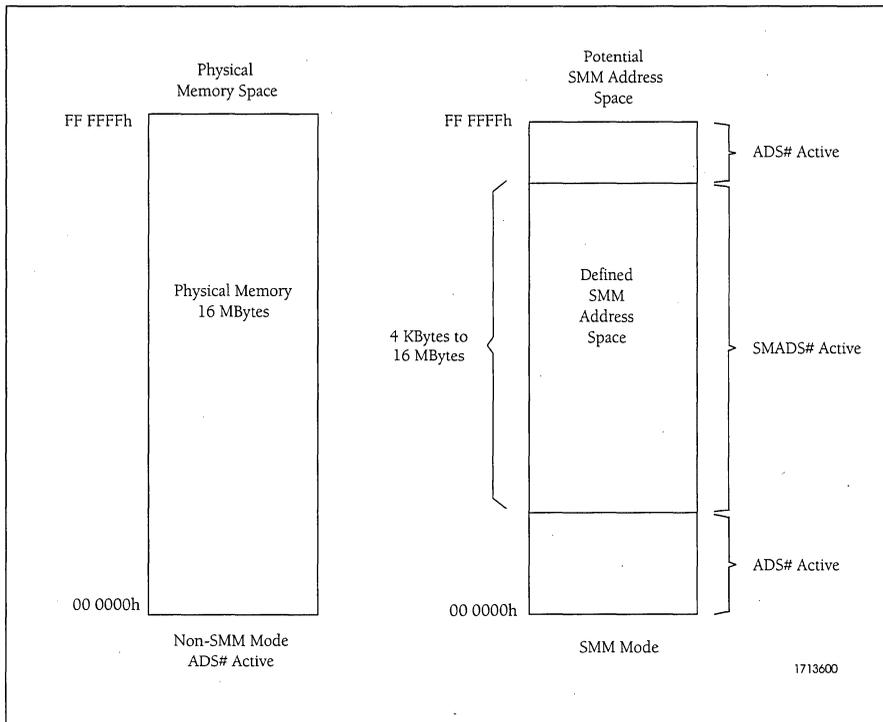


Figure 2-26. System Management Memory Address Space

2.6.2 SMM Operation

SMM operation is summarized in Figure 2-27. Entering SMM requires the assertion of the SMI# pin for at least four CLK2 periods. For the SMI# input to be recognized, the following configuration register bits must be set as shown below:

SMI	CCR1 (1)	= 1
SMAC	CCR1 (2)	= 0
SM4	CCR1 (7)	= 1
ARR4	SIZE (3-0)	> 0

The configuration registers are discussed in detail earlier in this chapter. After recognizing SMI#, and prior to executing the SMI service routine, some of the CPU state information is changed. Prior to modification, this information is automatically saved in the SMM memory space header located at the top of SMM memory space. After the header is saved, the CPU enters real mode and begins executing the SMI service routine starting at the SMM memory base address.

The SMI service routine is user definable and may contain system or power management software. If the power management software forces the CPU to power down, or the SMI service routine modifies more than what is automatically saved, the complete CPU state information must be saved.

A complete CPU state save is performed by using MOV instructions to save normally accessible information, and by using the SMM instructions to save CPU information that is not normally accessible to the programmer. As will be explained, SMM instructions (SVDC, SVLDT, and SVTS) are used to store the LDTR, TSR, and the segment registers and their associated descriptor cache

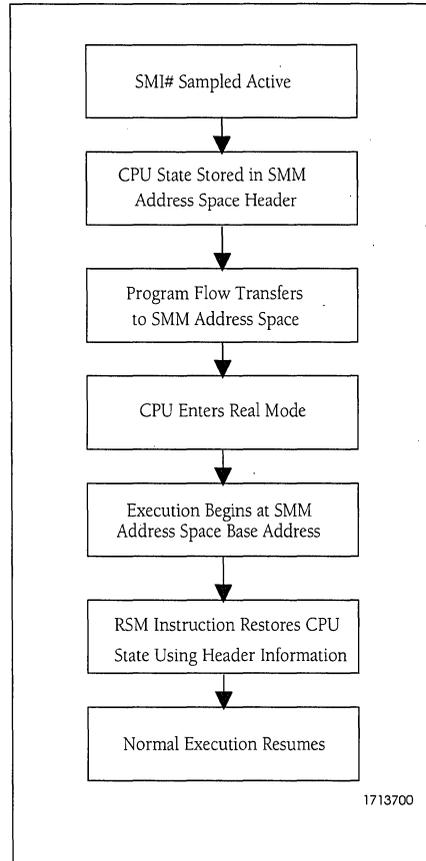


Figure 2-27. SMI Execution Flow Diagram

entries in 80-bit memory locations. After power up or at the end of the SMI service routine, the MOV and additional SMM instructions (RSDC, RSLDT and RSTS) are used to restore the CPU state. The SMM RSM instruction returns the CPU to normal execution.

2.6.3 SMM Memory Space Header

With every SMI interrupt, certain CPU state information is automatically saved in the SMM memory space header located at the top of SMM

address space (Figure 2-28 and Table 2-21). The header contains CPU state information that is modified when servicing an SMI interrupt. Included in this information are two pointers. The Current IP points to the instruction executing when the SMI was detected. The Next IP points

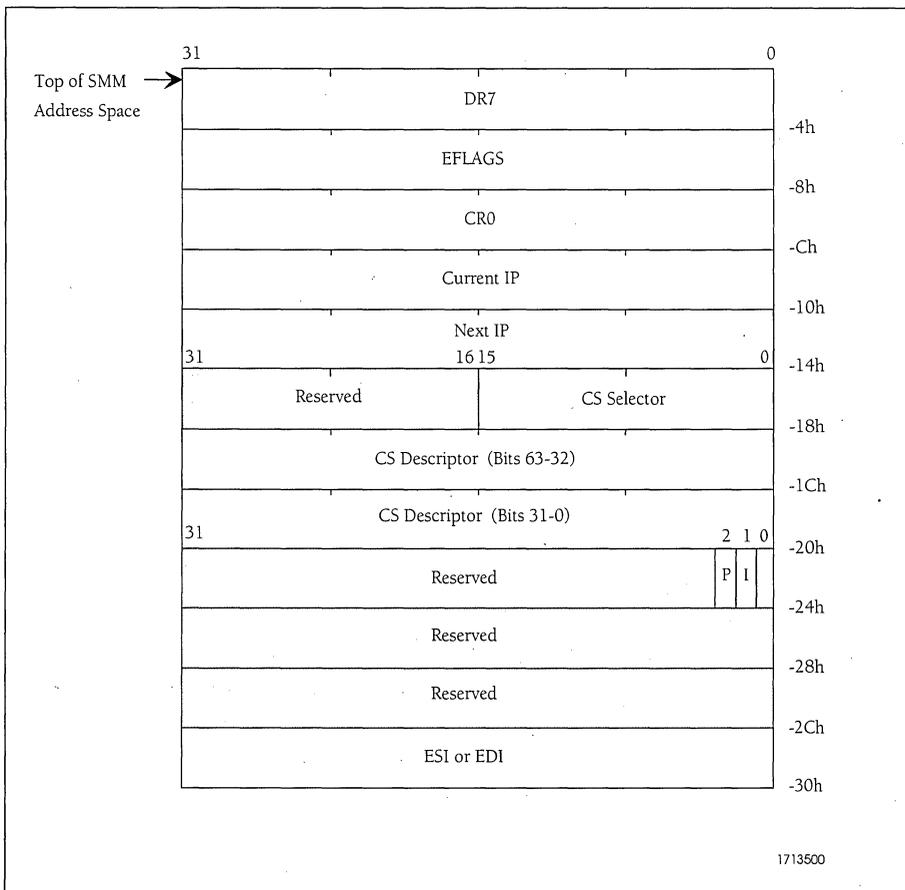


Figure 2-28. SMM Memory Space Header

to the instruction that will be executed after exiting SMM. Also saved are the contents of debug register 7 (DR7), the extended flags register (EFLAGS), and control register 0 (CR0). If SMM has been entered due to an I/O trap for a REP

INSx or REP OUTSx instruction, the Current IP and Next IP fields (Table 2-21) contain the same addresses and the I and P field contain valid information.

Table 2-21. SMM Memory Space Header

NAME	DESCRIPTION	SIZE
DR7	The contents of the debug register 7.	4 Bytes
EFLAGS	The contents of the extended flag register.	4 Bytes
CR0	The contents of the control register 0.	4 Bytes
Current IP	The address of the instruction executed prior to servicing the SMI interrupt.	4 Bytes
Next IP	The address of the next instruction that will be executed after exiting the SMM mode.	4 Bytes
CS Selector	Code segment register selector for the current code segment.	2 Bytes
CS Descriptor	Code segment register descriptor for the current code segment.	8 Bytes
P	REP INSx/OUTSx Indicator P=1 if current instruction has a REP prefix. P=0 if current instruction does not have REP prefix.	1 Bit
I	IN, INSx, OUT, or OUTSx Indicator I=1 if current instruction performed is an I/O WRITE. I=0 if current instruction performed is an I/O READ.	1 Bit
ESI or EDI	Restored ESI or EDI value. Used when it is necessary to repeat a REP OUTSx or REP INSx instruction when one of the I/O cycles caused an SMI# trap.	4 Bytes

Note: INSx = INS, INSB, INSW or INSD instruction.

Note: OUTSx = OUTS, OUTSB, OUTSW and OUTSD instruction.

2.6.4 SMM Instructions

The Cx486SLC/e automatically saves the minimal amount of CPU state information when entering SMM which allows fast SMI service routine entry and exit. After entering the SMI service routine, the MOV, SVDC, SVLDT and SVTS instructions can be used to save the complete CPU state information. If the SMI service routine modifies more than what is automatically saved or forces the CPU to power down, the complete CPU state information must be saved. Since the Cx486SLC/e is a static device, its internal state is retained when the input clock is stopped. Therefore, an entire CPU state save is not necessary prior to stopping the input clock.

The new SMM instructions, listed in Table 2-22, can only be executed if: (a) the Current Privilege Level (CPL) = 0 and the SMAC bit (CCR1, bit 2) is set; or (b) CPL = 0 and the CPU is in an SMI service routine (SMI# = 0). If both these conditions are not met and an attempt is made to execute an SVDC, RSDC, SVLDT, RSLDT, SVTS, RSTS or RSM instruction, an invalid opcode exception is generated. These instructions can be executed outside of defined SMM space provided the above conditions are met. All of the SMM instructions (except RSM) save or restore 80 bits of data allowing the saved values to include the hidden portion of the register contents.

Table 2-22 SMM Instruction Set

INSTRUCTION	OPCODE	FORMAT	DESCRIPTION
SVDC	0F 78 [mod sreg3 r/m]	SVDC mem80, sreg3	<i>Save Segment Register and Descriptor</i> Saves reg (DS, ES, FS, GS, or SS) to mem80.
RSDC	0F 79 [mod sreg3 r/m]	RSDC sreg3, mem80	<i>Restore Segment Register and Descriptor</i> Restores reg (DS, ES, FS, GS, or SS) from mem80. (CS is automatically restored with RSM.)
SVLDT	0F 7A [mod 000 r/m]	SVLDT mem80	<i>Save LDTR and Descriptor</i> Saves Local Descriptor Table (LDTR) to mem80.
RSLDT	0F 7B [mod 000 r/m]	RSLDT mem80	<i>Restore LDTR and Descriptor</i> Restores Local Descriptor Table (LDTR) from mem80.
SVTS	0F 7C [mod 000 r/m]	SVTS mem80	<i>Save TSR and Descriptor</i> Saves Task State Register (TSR) to mem80.
RSTS	0F 7D [mod 000 r/m]	RSTS mem80	<i>Restore TSR and Descriptor</i> Restores Task State Register (TSR) from mem80.
RSM	0F AA	RSM	<i>Resume Normal Mode</i> Exits SMM mode. The CPU state is restored using the SMM memory space header and execution resumes at interrupted point.

Note: mem80 = 80-bit memory location.

2.6.5 SMM Memory Space

SMM memory space is defined by assigning Address Region 4 to SMM memory space. This assignment is made by setting bit 7 (SM4) in the on-chip CCR1 register. ARR4, also an on-chip configuration register, specifies the base address and size of the SMM memory space. The base address must be a multiple of the SMM memory space size. For example, a 32 KByte SMM memory space must be located at a 32 KByte address boundary. The memory space size can range from 4 KBytes to 16 MBytes.

SMM memory space accesses can use address pipelining, and are always non-cacheable. SMM accesses ignore the state of the A20M# input pin and drive the A20 address bit to the unmasked value.

Access to the SMM memory space can be made while not in SMM mode by setting the System Management Access (SMAC) bit in the CCR1 register. This feature may be used to initialize the SMM memory space.

While in SMM mode, SMADS# address strobes are generated instead of ADS# for SMM memory accesses. Any memory accesses outside the defined SMM space result in normal memory accesses and ADS# strobes. Data (non-code) accesses to main memory that overlap with defined SMM memory space are allowed if bit 3 in CCR1 (MMAC) is set. In this case, ADS# strobes are generated for data accesses only and SMADS# strobes continue to be generated for code accesses.

2.6.6 SMI Service Routine Execution

Upon entry into SMM after the SMM header has been saved, the CR0, EFLAGS, and DR7 registers are set to their reset values. The Code Segment (CS) register is loaded with the base and limits defined by the ARR4 register and the SMI service routine begins execution at the SMM base address in real mode.

The programmer must then save the value of any registers that may be changed by the SMI service routine. For data accesses immediately after entering the SMI service routine, the programmer must use CS as a segment override. I/O port access is possible during the routine but care must be taken to save registers modified by the I/O instructions. Before using a segment register, the register and the register's descriptor cache contents should be saved using the SVDC instruction. While executing in the SMM space, execution flow can transfer to normal memory locations.

Hardware interrupts, (INTRs and NMIs), may be serviced during an SMI service routine. If interrupts are to be serviced while executing in the SMM memory space, the SMM memory space must be within the 0 to 1 MByte address range to guarantee proper return to the SMI service routine after handling the interrupt. INTRs are automatically disabled when entering SMM since the IF flag is set to its reset value. However, NMIs remain enabled. If it is desired to disable NMI, it should be done immediately after entering the SMI service routine by the system hardware logic.

Within the SMI service routine, protected mode may be entered and exited as required, and real or protected mode device drivers can be called.

To exit the SMI service routine, a Resume (RSM) instruction, rather than an IRET, is executed. The RSM instruction causes the Cx486SLC/e to restore the CPU state using the SMM header information and resume execution at the interrupted point. If the full CPU state was saved by the programmer, the stored values should be reloaded prior to executing the RSM instruction using the MOV and the RSDC, RSLDT and RSTS instructions.

CPU States Related to SMM and Suspend Mode

The state diagram shown in Figure 3-29 illustrates the various CPU states associated with SMM and suspend mode. While in the SMI service routine, the Cx486SLC/e can enter suspend mode either by (1) executing a HALT instruction or (2) by asserting the SUSP# input.

During SMM operations and while in SUSP# initiated suspend mode, an occurrence of either NMI or INTR is latched. (In order for INTR to be latched, the IF flag must have been set.) The INTR or NMI is serviced after exiting suspend mode.

If suspend mode is entered via a HALT instruction from the operating system or application software, the reception of an SMI# interrupt causes the CPU to exit suspend mode and enter SMM. If suspend mode is entered via the hardware (SUSP# = 0) while the operating system or application software is active, the CPU latches one occurrence of INTR, NMI and SMI#.

2.7 Shutdown and Halt

The **halt instruction** (HLT) stops program execution and prevents the processor from using the local bus until restarted. The Cx486SLC/e then enters a low-power suspend mode. SMI, NMI, INTR with interrupts enabled (IF bit in EFLAGS=1), or RESET forces the CPU out of the halt state. If interrupted, the saved code segment and instruction pointer specify the instruction following the HLT.

Shutdown occurs when a severe error is detected that prevents further processing. An NMI input can bring the processor out of shutdown if the IDT limit is large enough to contain the NMI interrupt vector (at least 000Fh) and the stack has enough room to contain the vector and flag information (i.e., stack pointer is greater than 0005h). Otherwise, shutdown can only be exited by a processor reset.

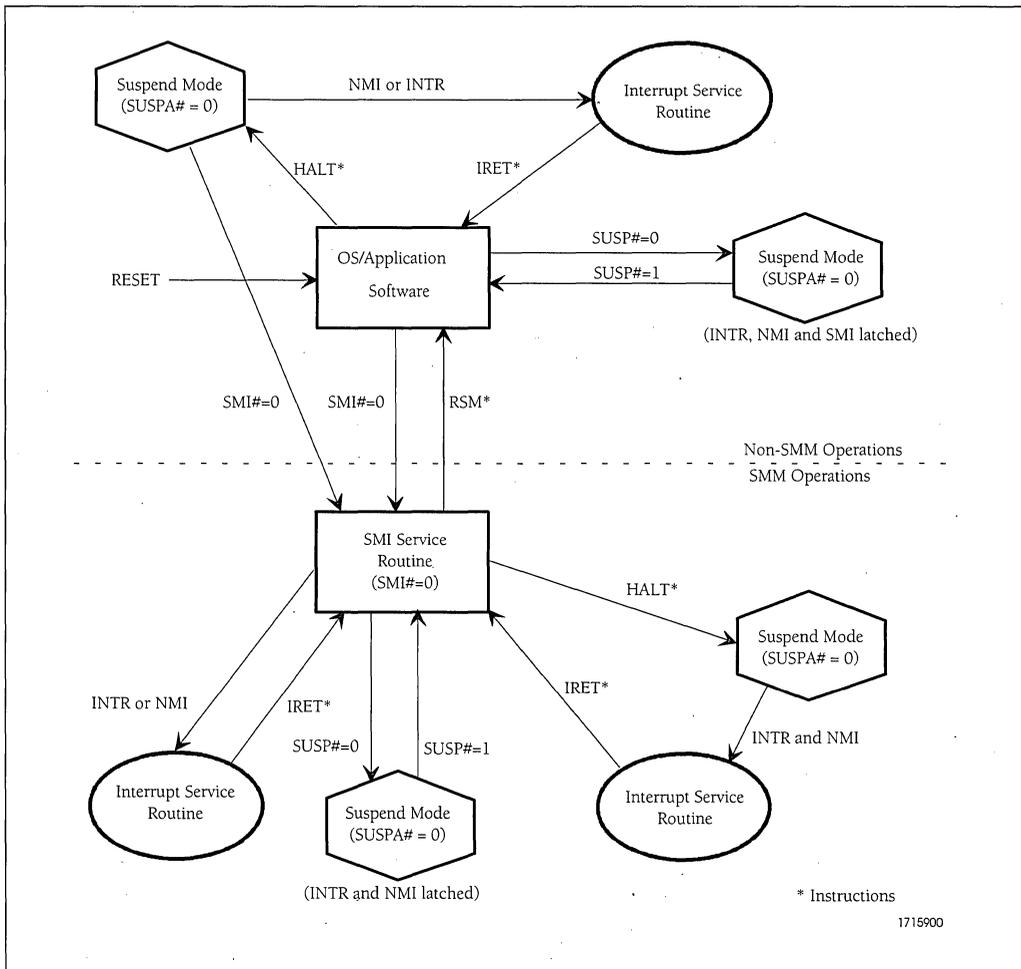


Figure 2-29. SMM and Suspend Mode Flow Diagram

2.8 Protection

Segment protection and page protection are safeguards built into the Cx486SLC/e protected mode architecture which deny unauthorized or incorrect access to selected memory addresses. These safeguards allow multitasking programs to be isolated from each other and from the operating system. Page protection is discussed earlier in this chapter in section 2.4. This section concentrates on segment protection.

Selectors and descriptors are the key elements in the segment protection mechanism. The segment base address, size, and privilege level are established by a segment descriptor. Privilege levels control the use of privileged instructions, I/O instructions and access to segments and segment descriptors. Selectors are used to locate segment descriptors.

Segment accesses are divided into two basic types, those involving code segments (e.g., control transfers) and those involving data accesses. The ability of a task to access a segment depends on:

- the segment type
- the instruction requesting access
- the type of descriptor used to define the segment
- the associated privilege levels (described below).

Data stored in a segment can be accessed only by code executing at the same or a more privileged level. A code segment or procedure can only be called by a task executing at the same or a less privileged level.

2.8.1 Privilege Levels

The values for privilege levels range between 0 and 3. Level 0 is the highest privilege level (most privileged), and level 3 is the lowest privilege level (least privileged). The privilege level in real mode is effectively 0.

The **Descriptor Privilege Level (DPL)** is the privilege level defined for a segment in the segment descriptor. The DPL field specifies the minimum privilege level needed to access the memory segment pointed to by the descriptor.

The **Current Privilege Level (CPL)** is defined as the current task's privilege level. The CPL of an executing task is stored in the hidden portion of the code segment register and essentially is the DPL for the current code segment.

The **Requested Privilege Level (RPL)** specifies a selector's privilege level and is used to distinguish between the privilege level of a routine actually accessing memory (the CPL), and the privilege level of the original requestor (the RPL) of the memory access. The lesser of the RPL and CPL is called the effective privilege level (EPL). Therefore, if RPL = 0 in a segment selector, the effective privilege level is always determined by the CPL. If RPL = 3, the effective privilege level is always 3 regardless of the CPL.

For a memory access to succeed, the effective privilege level (EPL) must be at least as privileged as the descriptor privilege level ($EPL \leq DPL$). If the EPL is less privileged than the DPL ($EPL > DPL$), a general protection fault is generated. For example, if a segment has a DPL = 2, an instruction accessing the segment only succeeds if executed with an $EPL \leq 2$.

2.8.2 I/O Privilege Levels

The **I/O Privilege Level** (IOPL) allows the operating system executing at CPL=0 to define the least privileged level at which IOPL-sensitive instructions can unconditionally be used. The IOPL-sensitive instructions include CLI, IN, OUT, INS, OUTS, REP INS, REP OUTS, and STI. Modification of the IF bit in the EFLAGS register is also sensitive to the I/O privilege level.

The IOPL is stored in the EFLAGS register. An I/O permission bit map is available as defined by the 32-bit Task State Segment (TSS). Since each task can have its own TSS, access to individual I/O ports can be granted through separate I/O permission bit maps.

If $CPL \leq IOPL$, IOPL-sensitive operations can be performed. If $CPL > IOPL$, a general protection fault is generated if the current task is associated with a 16-bit TSS. If the current task is associated with a 32-bit TSS and $CPL > IOPL$, the CPU consults the I/O permission bitmap in the TSS to determine on a port-by-port basis whether or not I/O instructions (IN, OUT, INS, OUTS, REP INS, REP OUTS) are permitted, and the remaining IOPL-sensitive operations generate a general protection fault.

2.8.3 Privilege Level Transfers

A task's CPL can be changed only through inter-segment control transfers using gates or task switches to a code segment with a different privilege level. Control transfers result from exception and interrupt servicing and from execution of the CALL, JMP, INT, IRET and RET instructions.

There are five types of control transfers that are summarized in Table 2-23. Control transfers can be made only when the operation causing the control transfer references the correct descriptor type. Any violation of these descriptor usage rules causes a general protection fault.

Table 2-23. Descriptor Types Used for Control Transfer

TYPE OF CONTROL TRANSFER	OPERATION TYPES	DESCRIPTOR REFERENCED	DESCRIPTOR TABLE
Intersegment within the same privilege level.	JMP, CALL, RET, IRET*	Code Segment	GDT or LDT
Intersegment to the same or a more privileged level. Interrupt within task (could change CPL level).	CALL	Call Gate	GDT or LDT
	Interrupt Instruction, Exception, External Interrupt	Trap or Interrupt Gate	IDT
Intersegment to a less privileged level (changes task CPL).	RET, IRET*	Code Segment	GDT or LDT
Task Switch via TSS	CALL, JMP	Task State Segment	GDT
Task Switch via Task Gate	CALL, JMP	Task Gate	GDT or LDT
	IRET**, Interrupt Instruction, Exception, External Interrupt	Task Gate	IDT

* NT (Nested Task bit in EFLAGS) = 0

** NT (Nested Task bit in EFLAGS) = 1

Any control transfer that changes the CPL within a task results in a change of stack. The initial values for the stack segment (SS) and stack pointer (ESP) for privilege levels 0, 1, and 2 are stored in the TSS. During a JMP or CALL control transfer, the SS and ESP are loaded with the new stack pointer and the previous stack pointer is saved on the new stack. When returning to the original privilege level, the RET or IRET instruction restores the less-privileged stack.

2.8.3.1 Gates

Gate descriptors provide protection for privilege transfers among executable segments. Gates are used to transition to routines of the same or a more privileged level. Call gates, interrupt gates and trap gates are used for privilege transfers within a task. Task gates are used to transfer between tasks.

Gates conform to the standard rules of privilege. In other words, gates can be accessed by a task if the effective privilege level (EPL) is the same or more privileged than the gate descriptor's privilege level (DPL).

2.8.4 Initialization and Transition to Protected Mode

The Cx486SLC/e microprocessor switches to real mode immediately after RESET. While operating in real mode, the system tables and registers should be initialized. The GDTR and IDTR must point to a valid GDT and IDT, respectively. The size of the IDT should be at least 256 bytes, and the GDT must contain descriptors which describe the initial code and data segments.

The processor can be placed in protected mode by setting the PE bit in the CR0 register. After enabling protected mode, the CS register should be loaded and the instruction decode queue should be flushed by executing an intersegment JMP. Finally, all data segment registers should be initialized with appropriate selector values.

2.9 Virtual 8086 Mode

Both real mode and virtual 8086 (V86) mode are supported by the Cx486SLC/e CPU allowing execution of 8086 application programs and 8086 operating systems. V86 Mode allows the execution of 8086-type applications, yet still permits use of the Cx486SLC/e protection mechanism. V86 tasks run at privilege level 3. Upon entry, all segment limits are set to FFFFh (64K) as in real mode.

2.9.1 Memory Addressing

While in V86 mode, segment registers are used in an identical fashion to real mode. The contents of the segment register are multiplied by 16 and added to the offset to form the segment base linear address. The Cx486SLC/e CPU permits the operating system

to select which programs use the V86 address mechanism and which programs use protected mode addressing for each task.

The Cx486SLC/e also permits the use of paging when operating in V86 mode. Using paging, the 1-MByte address space of the V86 task can be mapped to anywhere in the 4-GByte linear address space of the Cx486SLC/e CPU. As in real mode, linear addresses that exceed 1 MByte cause a segment limit overrun exception.

The paging hardware allows multiple V86 tasks to run concurrently, and provides protection and operating system isolation. The paging hardware must be enabled to run multiple V86 tasks or to relocate the address space of a V86 task to physical address space greater than 1 MByte.

2.9.2 Protection

All V86 tasks operate with the least amount of privilege (level 3) and are subject to all of the Cx486SLC/e protected mode protection checks. As a result, any attempt to execute a privileged instruction within a V86 task results in a general protection fault.

In V86 mode, a slightly different set of instructions are sensitive to the I/O privilege level (IOPL) than in protected mode. These instructions are: CLI, INT n, IRET, POPF, PUSHF, and STI. The INT3, INTO and BOUND variations of the INT instruction are not IOPL sensitive.

2.9.3 Interrupt Handling

To fully support the emulation of an 8086-type machine, interrupts in V86 mode are handled as follows. When an interrupt or exception is serviced in V86 mode, program execution transfers to the interrupt service routine at privilege level 0 (i.e., transition from V86 to protected mode occurs) and the VM bit in the EFLAGS register is cleared. The protected mode interrupt service routine then determines if the interrupt came from a protected mode or V86 application by examining the VM bit in the EFLAGS image stored on the stack. The interrupt service routine may then choose to allow the 8086 operating system to handle the interrupt or may emulate the function of the interrupt handler. Following completion of the interrupt service routine, an IRET instruction restores the EFLAGS register (restores VM=1) and segment selectors and control returns to the interrupted V86 task.

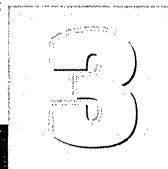
2.9.4 Entering and Leaving V86 Mode

V86 mode is entered from protected mode by either executing an IRET instruction at CPL = 0 or by task switching. If an IRET is used, the stack must contain an EFLAGS image with VM=1. If a task switch is used, the TSS must contain an EFLAGS image containing a 1 in the VM bit position. The POPF instruction cannot be used to enter V86 mode since the state of the VM bit is not affected. V86 mode can only be exited as the result of an interrupt or exception. The transition out must use a 32-bit trap or interrupt gate which must point to a non-conforming privilege level 0 segment (DPL = 0), or a 32-bit TSS. These restrictions are required to permit the trap handler to IRET back to the V86 program.



CYRIX Cx486SLC/e™ MICROPROCESSOR

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Bus Interface

3. BUS INTERFACE

3.1 Overview

The following sections describe the Cx486SLC/e input and output signals. The signals are described in the same order as they are listed in Figure 3-1. The discussion of these signals is arranged by functional groups as shown in Figure 3-1 and Table 3-1.

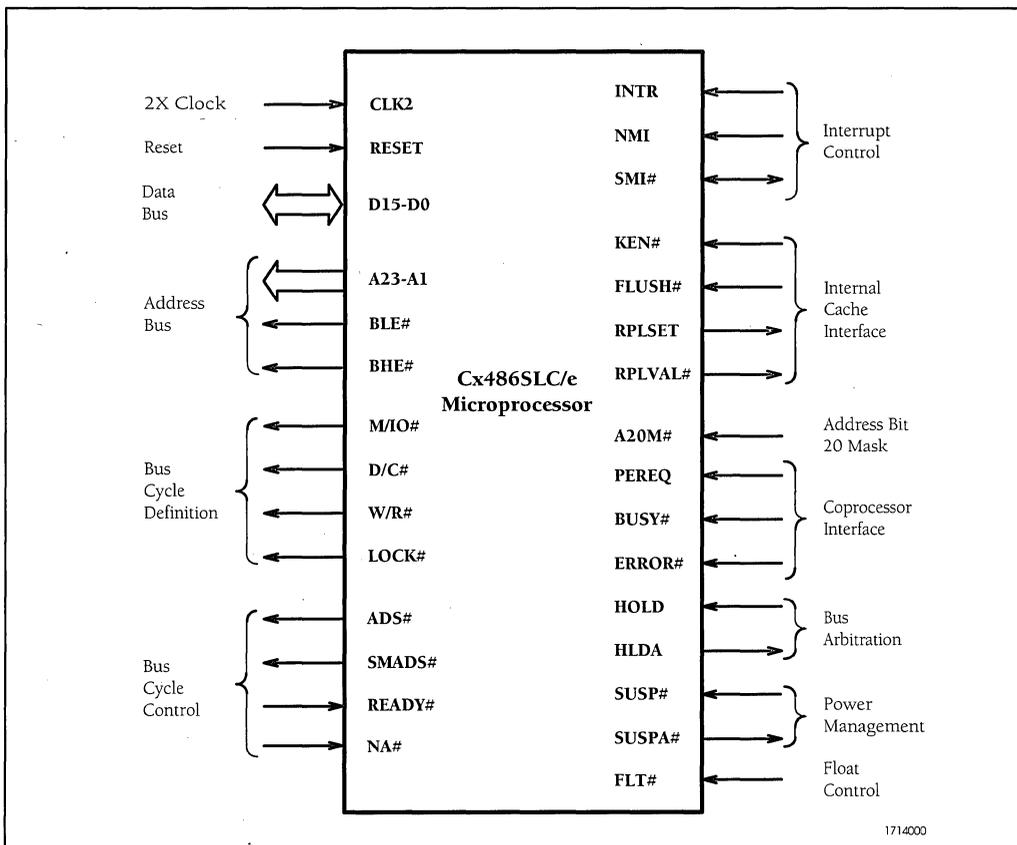


Figure 3-1. Cx486SLC/e Functional Signal Groupings

Table 3-1. Cx486SLC/e Signal Summary

SIGNAL	SIGNAL NAME	SIGNAL GROUP
A20M#	ADDRESS BIT 20 MASK	
A23-A1	ADDRESS BUS LINES	Address Bus
ADS#	ADDRESS STROBE	Bus Cycle Control
BHE#	BYTE HIGH ENABLE	Address Bus
BLE#	BYTE LOW ENABLE	Address Bus
BUSY#	PROCESSOR EXTENSION BUSY	Coprocessor Interface
CLK2	2X CLOCK INPUT	
D15-D0	DATA BUS	
D/C#	DATA/CONTROL	Bus Cycle Definition
ERROR#	PROCESSOR EXTENSION ERROR	Coprocessor Interface
FLT#	FLOAT	
FLUSH#	CACHE FLUSH	Internal Cache Interface
HLDA	HOLD ACKNOWLEDGE	Bus Arbitration
HOLD	HOLD REQUEST	Bus Arbitration
INTR	MASKABLE INTERRUPT REQUEST	Interrupt Control
KEN#	CACHE ENABLE	Internal Cache Interface
LOCK#	BUS LOCK	Bus Cycle Definition
M/O#	MEMORY/INPUT-OUTPUT	Bus Cycle Definition
NA#	NEXT ADDRESS REQUEST	Bus Cycle Control
NMI	NON-MASKABLE INTERRUPT REQUEST	Interrupt Control
PEREQ	PROCESSOR EXTENSION REQUEST	Coprocessor Interface
READY#	BUS READY	Bus Cycle Control
RESET	RESET	
RPLSET	REPLACEMENT SET	Internal Cache Interface
RPLVAL#	REPLACEMENT SET VALID	Internal Cache Interface
SMADS#	SMM ADDRESS STROBE	Bus Cycle Control
SMI#	SYSTEM MANAGEMENT INTERRUPT	Interrupt Control
SUSP#	SUSPEND REQUEST	Power Management
SUSPA#	SUSPEND ACKNOWLEDGE	Power Management
W/R#	WRITE/READ	Bus Cycle Definition

The pound symbol "#" following a signal name indicates that when the signal is in its active (asserted) state, the signal is at a logic low level. When the "#" is not present at the end of a signal name, the logic high level represents the active

state. The following two sections describe the signals and their functional timing characteristics. Additional signal information may be found in Chapter 4, Electrical Specifications. Chapter 4 documents the DC and AC characteristics for the

signals including voltage levels, propagation delays, setup times and hold times. Specified setup and hold times must be met for proper operation of the Cx486SLC/e.

3.2 Signal Descriptions

3.2.1 2X Clock Input

The **2X Clock Input (CLK2)** signal is the basic timing reference for the Cx486SLC/e microprocessor. The CLK2 input is internally divided by two to generate the internal processor clock. The external CLK2 is synchronized to a known phase of the internal processor clock by the falling edge of the RESET signal. External timing parameters are defined with respect to the rising edge of CLK2.

3.2.2 Reset

Reset is an active high input signal that, when asserted, suspends all operations in progress and places the Cx486SLC/e into a reset state. RESET is a level-sensitive synchronous input and must meet specified setup and hold times to be properly recognized by the Cx486SLC/e. The Cx486SLC/e begins executing instructions at physical address location FF FFF0h approximately 400 CLK2's after RESET is driven inactive (low). While RESET is active all other input pins, except FLT#, are ignored. The remaining signals are initialized to their reset state during the internal processor reset sequence. The reset signal states for the Cx486SLC/e are shown in Table 3-2.

Table 3-2. Signal States During Reset

SIGNAL NAME	SIGNAL STATE DURING RESET
A20M#	Ignored
A23-A1	1
ADS#	1
BHE#, BLE#	0
BUSY#	Initiates Self Test
D15-D0	Float
D/C#	1
ERROR#	Ignored
FLT#	Input Recognized
FLUSH#	Ignored
HLDA	0
HOLD	Ignored
INTR	Ignored
KEN#	Ignored
LOCK#	1
MIO#	0
NA#	Ignored
NMI	Ignored
PEREQ	Ignored
READY#	Ignored
RESET	Input Recognized
RPLSET	Float
RPLVAL#	Float
SMADS#	Float
SMI#	Ignored
SUSP#	Ignored
SUSPA#	Float
W/R#	0

3.2.3 Data Bus

The **Data Bus (D15-D0)** signals are three-state bidirectional signals which provide the data path between the Cx486SLC/e and external memory and I/O devices. The data bus inputs data during memory read, I/O read and interrupt acknowledge cycles and outputs data during memory and I/O write cycles. Data read operations require that specified data setup and hold times be met for correct operation. The data bus signals are high active and float while the CPU is in a hold acknowledge or float state.

3.2.4 Address Bus

The **Address Bus (A23-A1)** signals are three-state outputs that provide addresses for physical memory and I/O ports. All address lines can be used for addressing physical memory allowing a 16 MByte address space (00 0000h to FF FFFFh). During I/O port accesses, A23-A16 are driven low (except for coprocessor accesses). This permits a 64 KByte I/O address space (00 0000h to 00 FFFFh).

During all coprocessor I/O accesses address lines A22-A16 are driven low and A23 is driven high. This allows A23 to be used by external logic to generate a coprocessor select signal. Coprocessor command transfers occur with address 80 00F8h and coprocessor data transfers occur with addresses 80 00FCh and 80 00FEh. A23-A1 float while the CPU is in a hold acknowledge or float state.

Byte Low Enable (BLE#) and **Byte High Enable (BHE#)** are three-state outputs that indicate which byte(s) of the 16-bit data bus will be selected for data transfer during the current bus cycle (Table 3-3). BLE# selects the low byte (D7-D0) and BHE# selects the high byte (D15-D8).

When BHE# and BLE# are asserted, both bytes (all 16 bits) of the data bus are selected. BLE# and BHE# float while the CPU is in a hold acknowledge or float state.

Table 3-3. Byte Enable Definitions

BHE#	BLE#	FUNCTION
0	0	Word transfer - D15-D0
0	1	Upper byte transfer - D15-D8
1	0	Lower byte transfer - D7-D0
1	1	Never occurs during a bus cycle

3.2.5 Bus Cycle Definition

The bus cycle definition signals (M/IO#, D/C#, W/R#, LOCK#) consist of four three-state outputs which define the bus cycle type to be performed.

Memory/IO (M/IO#) is low during I/O read and write cycles and is high during memory cycles.

Data/Control (D/C#) is low during control cycles and is high during data cycles. Control cycles are issued during functions such as a halt instruction, interrupt servicing and code fetching. Data bus cycles include data access from either memory or I/O.

Write/Read (W/R#) is low during read cycles (data is read from memory or I/O) and is high during write bus cycles (data is written to memory or I/O).

LOCK# is asserted to deny control of the CPU bus to other bus masters. The LOCK# signal may be explicitly activated during bus operations by including the LOCK prefix on certain instructions. LOCK# is always asserted during descriptor and

page table updates, interrupt acknowledge sequences and when executing the XCHG instruction. The Cx486SLC/e does not enter the hold acknowledge state in response to HOLD while the LOCK# input is active.

The possible states for the bus cycle definition signals are listed in Table 3-4. The primary bus cycle definition signals (M/IO#, D/C# and W/R#) are driven valid when ADS# (Address Strobe) is asserted.

During non-pipelined cycles, the LOCK# output is driven valid along with M/IO#, D/C# and W/R#. During pipelined addressing, LOCK# is driven at the beginning of the bus cycle, which is after ADS# is asserted for that cycle. The bus cycle definition signals float while the Cx486SLC/e is in a hold acknowledge or float state.

3.2.6 Bus Cycle Control

The bus cycle control signals (ADS#, SMADS#, READY#, NA#) allow the Cx486SLC/e to indicate the beginning of a bus cycle and allow system hardware to control address pipelining and bus cycle termination timing.

Address Strobe (ADS#) is a three-state output which indicates that the Cx486SLC/e has driven a valid address (A23-A1, BHE#, BLE#) and bus cycle definition (M/IO#, D/C#, W/R#) on the appropriate Cx486SLC/e output pins. During non-pipelined bus cycles, ADS# is active for the first clock of the bus cycle. During address pipelining, ADS# is asserted during the previous bus cycle and remains asserted until READY# is returned for that cycle. ADS# floats while the Cx486SLC/e is in a hold acknowledge or float state.

Table 3-4. Bus Cycle Types

M/IO#	D/C#	W/R#	LOCK#	BUS CYCLE TYPE
0	0	0	0	Interrupt Acknowledge
0	0	0	1	--
0	0	1	X	--
0	1	X	0	--
0	1	0	1	I/O Data Read
0	1	1	1	I/O Data Write
1	0	X	0	--
1	0	0	1	Memory Code Read
1	0	1	1	Halt: A23-A1 = 2h, BHE# = 1 and BLE# = 0 Shutdown: A23-A1 = 0h, BHE# = 1 and BLE# = 0
1	1	0	0	Locked Memory Data Read
1	1	0	1	Memory Data Read
1	1	1	0	Locked Memory Data Write
1	1	1	1	Memory Data Write

X = don't care, -- = does not occur

SMM Address Strobe (SMADS#) is asserted instead of the ADS# during SMM bus cycles and indicates that SMM memory is being accessed. SMADS# floats while the CPU is in a hold acknowledge or float state. The SMADS# output is disabled (floated) following reset and can be enabled using the SMI bit in the CCR1 configuration register.

Ready (READY#) is an input generated by the system hardware that indicates that the current bus cycle can be terminated. During a read cycle, assertion of READY# indicates that the system hardware has presented valid data to the CPU. When READY# is sampled active, the Cx486SLC/e latches the input data and terminates the cycle. During a write cycle, READY# assertion indicates that the system hardware has accepted the Cx486SLC/e output data. READY# must be asserted to terminate every bus cycle, including halt and shutdown indication cycles.

Next Address Request (NA#) is an input used to request address pipelining by the system hardware. When asserted, the system indicates that it is prepared to accept new bus cycle definition and address signals (M/IO#, D/C#, W/R#, A23-A1, BHE#, and BLE#) from the microprocessor even if the current bus cycle has not been terminated by assertion of READY#. If the Cx486SLC/e has an internal bus request pending and the NA# input is sampled active, the next bus cycle definition and address signals are driven onto the bus.

3.2.7 Interrupt Control

The interrupt control input signals (INTR, NMI, SMI#) allow the execution of the Cx486SLC/e's current instruction stream to be interrupted and suspended.

Maskable Interrupt Request (INTR) is a level-sensitive input which causes the processor to suspend execution of the current instruction stream and begin execution of an interrupt service routine. The INTR input can be masked (ignored) through the Flags Register IF bit. When unmasked, the Cx486SLC/e responds to the INTR input by issuing two locked interrupt acknowledge cycles. To assure recognition of the INTR request, INTR must remain active until the start of the first interrupt acknowledge cycle.

Non-maskable Interrupt Request (NMI) is a rising-edge sensitive input which causes the processor to suspend execution of the current instruction stream and begin execution of an NMI interrupt service routine. The NMI interrupt service request cannot be masked by the software. Asserting NMI causes an interrupt which internally supplies interrupt vector 2h to the CPU core. External interrupt acknowledge cycles are not necessary since the NMI interrupt vector is supplied internally.

The Cx486SLC/e samples NMI at the beginning of each phase 2. To assure recognition, NMI must be inactive for at least eight CLK2 periods and then be active for at least eight CLK2 periods. Additionally, specified setup and hold times must be met to guarantee recognition at a particular clock edge.

System Management Interrupt (SMI#) is a bidirectional signal and level sensitive interrupt with higher priority than the NMI interrupt. SMI# must be active for at least four CLK2 clock periods to be recognized by the Cx486SLC/e. After the SMI# interrupt is acknowledged, the SMI# pin is driven low by the Cx486SLC/e for the duration of the SMI service routine. The SMI# input is

ignored following reset and can be enabled using the SMI bit in the CCR1 configuration register.

3.2.8 Internal Cache Interface

The internal cache interface signals (KEN#, FLUSH#, RPLSET, RPLVAL#) indicate cache status and control caching activity.

Cache Enable (KEN#) is an input which indicates that the data being returned during the current cycle is cacheable. When KEN# is active and the Cx486SLC/e is performing a cacheable code fetch or memory data read cycle, the cycle is transformed into a cache fill. Use of the KEN# input to control cacheability is optional. The non-cacheable region registers can also be used to control cacheability. Memory addresses specified by the non-cacheable region registers are not cacheable regardless of the state of KEN#. I/O accesses, locked reads, SMM address space accesses, and interrupt acknowledge cycles are never cached.

During cached code fetches, two contiguous read cycles are performed to completely fill the 4-byte cache line. KEN# must be asserted during both read cycles in order to cause a cache line fill. During cached data reads, the Cx486SLC/e performs only those bus cycles necessary to supply the required data to complete the current operation. Valid bits are maintained for each byte in the cache line, thus allowing data operands of less than 4 bytes to reside in the cache.

During any cache fill cycle with KEN# asserted, the Cx486SLC/e ignores the state of the byte enables (BHE# and BLE#) and always writes two bytes of data into the cache. The KEN# input is ignored following reset and can be enabled using the KEN bit in the CCR0 configuration register.

Cache Flush (FLUSH#) is an input which invalidates (flushes) the entire cache. Use of FLUSH# to maintain cache coherency is optional. The cache may also be invalidated during each hold acknowledge cycle by setting the BARB bit in the CCR0 configuration register. The FLUSH# input is ignored following reset and can be enabled using the FLUSH bit in the CCR0 configuration register.

Replacement Set (RPLSET) is an output indicating which set in the cache is currently undergoing a line replacement. This signal is meaningful only when the internal cache is configured as two-way set associative. The RPLSET output is disabled (three-state) following reset and can be enabled using the RPL bit in the CCR1 configuration register. RPLSET floats during CPU hold acknowledge and float states.

Replacement Set Valid (RPLVAL#) is an output driven during a cache fill cycle to indicate that RPLSET is valid for the current cycle. RPLVAL# and RPLSET provide external hardware the capability of monitoring the cache LRU replacement algorithm. The RPLVAL# output is disabled (three-state) following reset and can be enabled using the RPL bit in the CCR1 configuration register. RPLVAL# floats during CPU hold acknowledge and float states.

3.2.9 Address Bit 20 Mask

Address Bit 20 Mask (A20M#) is an active low input which causes the Cx486SLC/e to mask (force low) physical address bit 20 when driving the external address bus or performing an internal cache access. When the processor is in real mode, asserting A20M# emulates the 1 MByte address wrap around that occurs on the 8086. The A20 signal is never masked when paging is enabled regardless of the state of the A20M# input. The A20M# input is ignored following reset and can be enabled using the A20M bit in the CCRO configuration register.

3.2.10 Coprocessor Interface

The data bus, address bus and bus cycle definition signals, as well as the coprocessor interface signals (PEREQ, BUSY#, ERROR#), are used to control communication between the Cx486SLC/e and a coprocessor. Coprocessor or ESC opcodes are decoded by the Cx486SLC/e and the opcode and operands are then transferred to the coprocessor via I/O port accesses to addresses 80 00F8h, 80 00FCh or 80 00FEh. 80 00F8h functions as the control port address and 80 00FCh and 80 00FEh are used for operand transfers. Additional handshaking is provided using the three dedicated control signals described below.

Coprocessor Request (PEREQ) is an active high input which indicates the coprocessor is ready to transfer data to or from the CPU. The coprocessor may assert PEREQ in the process of executing a coprocessor instruction. The Cx486SLC/e internally stores the current coprocessor opcode and performs the correct data transfers to support coprocessor operations using PEREQ to synchro-

nize the transfer of required operands. PEREQ is internally connected to a pull-down resistor to prevent this signal from floating active when left unconnected.

Coprocessor Busy (BUSY#) is an active low input from the coprocessor which indicates to the Cx486SLC/e that the coprocessor is currently executing an instruction and is not yet able to accept another opcode. When the Cx486SLC/e processor encounters a WAIT instruction or any coprocessor instruction which operates on the coprocessor stack (e.g. load, pop, arithmetic operation), BUSY# is sampled. BUSY# is continually sampled and must be recognized as inactive before the CPU will supply the coprocessor with another instruction. However, the following coprocessor instructions are allowed to execute even if BUSY# is active since these instructions are used for coprocessor initialization and exception clearing:

FNINIT
FNCLEX.

BUSY# is internally connected to a pull-up resistor to prevent it from floating active when left unconnected.

Coprocessor Error (ERROR#) is an active low input used to indicate that the coprocessor generated an error during execution of a coprocessor instruction. ERROR# is sampled by the Cx486SLC/e processor whenever a coprocessor instruction is executed. If ERROR# is sampled active, the processor generates exception 16 which is then serviced by the exception handling software.

Certain coprocessor instructions do not generate an exception 16 even if ERROR# is active. These instructions, which involve clearing

coprocessor error flags and saving the coprocessor state, are listed below:

FNINIT
FNCLEX
FNSTSW
FNSTCW
FNSTENV
FNSAVE

ERROR# is internally connected to a pull-up resistor to prevent it from floating active when left unconnected.

3.2.1.1 Bus Arbitration

The bus arbitration (HOLD, HLDA) signals allow the Cx486SLC/e to relinquish control of its local bus when requested by another bus master device. Once the processor has relinquished its bus (three-stated), the bus master device can then drive the local bus signals.

Hold Request (HOLD) is an active high input used to indicate that another bus master requests control of the local bus. After recognizing the HOLD request and completing the current bus cycle or sequence of locked bus cycles, the Cx486SLC/e responds by floating the local bus and asserting the hold acknowledge (HLDA) output.

Once HLDA is asserted, the bus remains granted to the requesting bus master until HOLD becomes inactive. When the Cx486SLC/e recognizes HOLD is inactive, it simultaneously drives the local bus and drives HLDA inactive. External pull-up resistors may be required on some of the Cx486SLC/e three-state outputs to guarantee that they remain inactive while in a hold acknowledge state.

The HOLD input is not recognized while RESET is active. If HOLD is asserted while RESET is active, RESET has priority and the Cx486SLC/e places the bus into an idle state instead of a hold acknowledge state. The HOLD input is also recognized during suspend mode provided the CLK2 input has not been stopped. HOLD is level-sensitive and must meet specified setup and hold times for correct operation.

Hold Acknowledge (HLDA) is an active high output which indicates that the Cx486SLC/e is in a hold acknowledge state and has relinquished control of its local bus. While in the hold acknowledge state, the Cx486SLC/e drives HLDA active and continues to drive SUSPA#, if enabled. The other Cx486SLC/e outputs are in a high-impedance state allowing the requesting bus master to drive these signals. If the on-chip cache can satisfy bus requests, the Cx486SLC/e continues to operate during hold acknowledge states. A20M# is internally recognized during this time.

The processor deactivates HLDA when the HOLD request is driven inactive. The Cx486SLC/e stores one NMI rising edge during a hold acknowledge state for processing after HOLD is inactive. The FLUSH# input is also recognized during a hold acknowledge state. If SUSP# is asserted during a hold acknowledge state, the Cx486SLC/e may or may not enter suspend mode depending on the state of the internal execution pipeline. Table 3-5 summarizes the state of the Cx486SLC/e signals during hold acknowledge.

Table 3-5. Signal States During Hold Acknowledge

SIGNAL NAME	SIGNAL STATE DURING HOLD ACKNOWLEDGE
A20M#	Input Recognized
A23-A1	Float
ADS#	Float
BHE#, BLE#	Float
BUSY#	Ignored
D15-D0	Float
D/C#	Float
ERROR#	Ignored
FLT#	Input Recognized
FLUSH#	Input Recognized
HLDA	1
HOLD	Input Recognized
INTR	Input Recognized
KEN#	Ignored
LOCK#	Float
M/IO#	Float
NA#	Ignored
NMI	Input Recognized
PEREQ	Ignored
READY#	Ignored
RESET	Input Recognized
RPLSET	Float
RPLVAL#	Float
SMADS#	Float
SMI#	Input Recognized
SUSP#	Input Recognized
SUSPA#	Driven
W/R#	Float

3.2.12 Power Management Interface

The power management signals allows the Cx486SLC/e to enter suspend mode. Suspend mode can also be entered as the result of executing a

HALT instruction. Suspend mode circuitry allows the Cx486SLC/e to consume minimal power while maintaining the entire internal CPU state.

Suspend Request (SUSP#) is an active low input which requests that the Cx486SLC/e enter suspend mode. After recognizing SUSP# active, the processor completes execution of the current instruction, any pending decoded instructions and associated bus cycles. In addition, the Cx486SLC/e waits for the coprocessor to indicate a not busy status (BUSY# = 1) before entering suspend mode and asserting suspend acknowledge (SUSPA#). During suspend mode, internal clocks are stopped and only the logic associated with monitoring RESET, HOLD and FLUSH# remains active. With SUSPA# asserted, the CLK2 input to the Cx486SLC/e can be stopped in either phase. Stopping the CLK2 input further reduces current consumption of the Cx486SLC/e.

To resume operation, the CLK2 input is restarted (if stopped), followed by negation of the SUSP# input. The processor then resumes instruction fetching and begins execution in the instruction stream at the point it had stopped. The SUSP# input is level sensitive and must meet specified setup and hold times to be recognized at a particular clock edge. The SUSP# input is ignored following reset and can be enabled using the SUSP bit in the CCR0 configuration register.

The **Suspend Acknowledge (SUSPA#)** output indicates that the Cx486SLC/e has entered the suspend mode as a result of SUSP# assertion or execution of a HALT instruction. If SUSPA# is asserted and the CLK2 input is switching, the Cx486SLC/e continues to recognize FLT#, RESET, HOLD and FLUSH#. If suspend mode was entered as the result of a HALT instruction, the Cx486SLC/e also continues to monitor the

NMI, SMI# and unmasked INTR inputs. Detection of an unmasked INTR, NMI or SMI# forces the Cx486SLC/e to exit suspend mode and begin execution of the appropriate interrupt service routine. The CLK2 input to the processor may be stopped after SUSPA# has been asserted to further reduce the current consumption of the

Cx486SLC/e. The SUSPA# output is disabled (floated) following reset and can be enabled using the SUSP bit in the CCR0 configuration register.

Table 3-6 shows the state of the Cx486SLC/e signals when the device is in suspend mode.

Table 3-6. Signal States During Suspend Mode

SIGNAL NAME	SIGNAL STATE DURING SUSP# INITIATED SUSPEND MODE	SIGNAL STATE DURING HALT INITIATED SUSPEND MODE
A20M#	Ignored	Ignored
A23-A1	1	1
ADS#	1	1
BHE#, BLE#	0	0
BUSY#	Ignored	Ignored
D15-D0	Float	Float
D/C#	1	1
ERROR#	Ignored	Ignored
FLT#	Input Recognized	Input Recognized
FLUSH#	Input Recognized	Input Recognized
HLDA	0	0
HOLD	Input Recognized	Input Recognized
INTR	Latched	Input Recognized
KEN#	Ignored	Ignored
LOCK#	1	1
M/IO#	0	0
NA#	Ignored	Ignored
NMI	Latched	Input Recognized
PEREQ	Ignored	Ignored
READY#	Ignored	Ignored
RESET	Input Recognized	Input Recognized
RPLSET	Driven	Driven
RPLVAL#	Driven	Driven
SMADS#	1	1
SMI#	Latched	Input Recognized
SUSP#	Input Recognized	Ignored
SUSPA#	0	0
W/R#	0	0

3.2.13 Float Control (FLT#)

Float (FLT#) is an active low input which forces all bidirectional and output signals to a tri-state condition. Floating the signals allows the Cx486SLC/e signals to be externally driven without physically removing the device from the circuit. The Cx486SLC/e CPU must be reset following assertion or deassertion of FLT#. It is recommended that FLT# be used only for test purposes.

3.3 Functional Timing

3.3.1 Reset Timing and Internal Clock Synchronization

RESET is the highest priority input signal and is capable of interrupting any processor activity when it is asserted. When RESET is asserted, the Cx486SLC/e aborts any bus cycle. Idle, hold acknowledge and suspend states are also discontinued and the reset state is established. RESET is used when the Cx486SLC/e microprocessor is

powered up to initialize the CPU to a known valid state and to synchronize the internal CPU clock with external clocks.

RESET must be asserted for at least 15 CLK2 periods to ensure recognition by the Cx486SLC/e microprocessor. If the self-test feature is to be invoked, RESET must be asserted for at least 80 CLK2 periods. RESET pulses less than 15 CLK2 periods may not have sufficient time to propagate throughout the Cx486SLC/e and may not be recognized. RESET pulses less than 80 CLK2 periods followed by a self-test request may incorrectly report a self-test failure when no true failure exists.

Provided the RESET falling edge meets specified setup and hold times, the internal processor clock phase is synchronized as illustrated in Figure 3-2. The internal processor clock is half the frequency of the CLK2 input and each CLK2 cycle corresponds to an internal CPU clock phase. Phase 2 of the internal clock is defined to be the second rising edge of CLK2 following the falling edge of RESET.

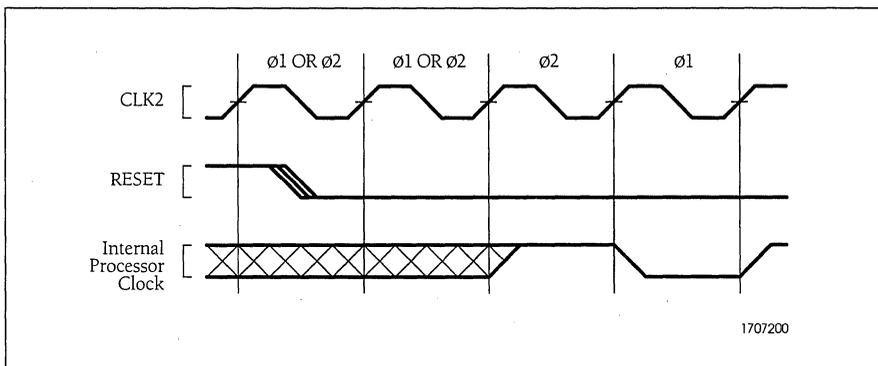


Figure 3-2. Internal Processor Clock Synchronization

Following the falling edge of RESET (and after self-test if it was requested), the Cx486SLC/e microprocessor performs an internal initialization sequence for approximately 400 CLK2 periods. The Cx486SLC/e self-test feature is invoked if the BUSY# input is an active low state when RESET falls inactive. The self-test sequence requires approximately $(2^{20} + 60)$ CLK2 periods to complete. Even if the self-test indicates a problem, the Cx486SLC/e microprocessor attempts to proceed

with the reset sequence. Figure 3-3 illustrates the bus activity and timing during the Cx486SLC/e reset sequence.

Upon completion of self-test, the EAX register contains 0000 0000h if the Cx486SLC/e microprocessor passed its internal self-test with no problems detected. Any non-zero value in the EAX register indicates that the microprocessor is faulty.

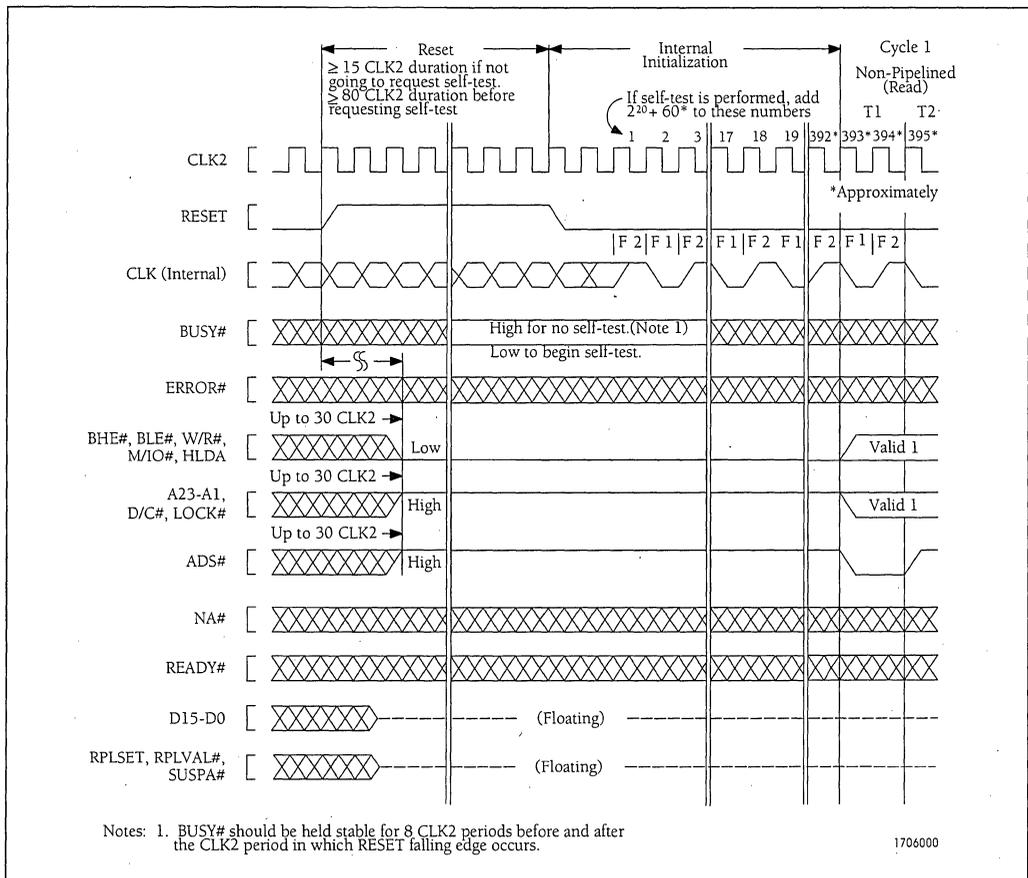


Figure 3-3. Bus Activity from RESET until First Code Fetch

3.3.2 Bus Operation

The Cx486SLC/e microprocessor communicates with the external system through separate, parallel buses for data and address. This is commonly called a demultiplexed address/data bus. This demultiplexed bus eliminates the need for address latches required in multiplexed address/data bus configurations where the address and data are presented on the same pins at different times.

Cx486SLC/e instructions can act on memory data operands consisting of 8-bit bytes, 16-bit words or 32-bit double words. The Cx486SLC/e bus architecture allows for bus transfers of these operands without restrictions on physical address alignment. Any byte boundary alignment is permissible. Operands not aligned on a word boundary may require more than one bus cycle to transfer the operand. This feature is transparent to the programmer.

The Cx486SLC/e data bus (D15-D0) is a 16-bit wide bidirectional bus. The Cx486SLC/e drives the data bus during write bus cycles and the external system hardware drives the data bus during read bus cycles. The address bus provides a 24-bit value using 23 signals for the 23 upper-order address bits (A23-A1), defining which 16-bit word is being accessed, and two byte enable signals (BHE# and BLE#) to directly indicate which of the two bytes within the word are active.

Every bus cycle begins with the assertion of the address strobe (ADS#). ADS# indicates that the Cx486SLC/e has issued a new address and new bus cycle definition signals. A bus cycle is defined by four signals: M/I/O#, W/R#, D/C# and LOCK#. M/I/O# defines if a memory or I/O operation is

occurring, W/R# defines the cycle to be read or write, and D/C# indicates whether a data or control cycle is in effect. LOCK# indicates that the current cycle is a locked bus cycle. Every bus cycle completes when the system hardware returns READY# asserted.

The Cx486SLC/e performs the following bus cycle types:

- Memory Read
- Locked Memory Read
- Memory Write
- Locked Memory Write
- I/O Read (or coprocessor read)
- I/O Write (or coprocessor write)
- Interrupt Acknowledge (always locked)
- Halt/Shutdown

When the Cx486SLC/e microprocessor has no pending bus requests, the bus enters the idle state. There is no encoding of the idle state on the bus cycle definition signals, however, the idle state can be identified by the absence of further assertions of ADS# following a completed bus cycle.

3.3.2.1 Bus Cycles using Non-Pipelined Addressing

Non-Pipelined Bus States

The shortest time unit of bus activity is a bus state, commonly called T states. A bus state is one internal processor clock period (two CLK2 periods) in duration. A complete data transfer occurs during a bus cycle, composed of two or more bus states.

The first state of a non-pipelined bus cycle is called T1. During phase one (first CLK2) of T1, the address bus and bus cycle definition signals are driven valid and, to signal their availability, address strobe (ADS#) is simultaneously asserted. The second bus state of a non-pipelined cycle is called T2. T2 terminates a bus cycle with the assertion of the READY# input and valid data is

either input or output depending on the bus cycle type. The fastest Cx486SLC/e microprocessor bus cycle requires only these two bus states. READY# is ignored at the end of the T1 state.

Three consecutive bus read cycles, each consisting of two bus states, are shown in Figure 3-4.

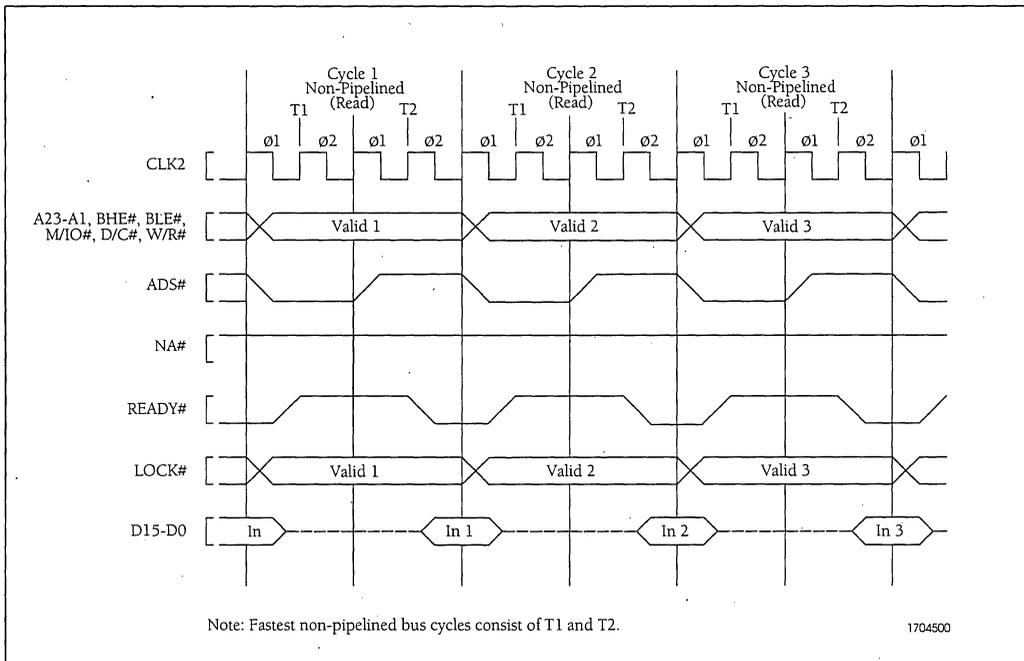


Figure 3-4. Fastest Non-Pipelined Read Cycles

Non-Pipelined Read and Write Cycles

Any bus cycle may be performed with non-pipelined address timing. Figure 3-5 shows a mixture of read and write cycles with non-pipelined address timing. When a read cycle is performed, the Cx486SLC/e microprocessor floats its data bus and the externally addressed device then drives the data. The Cx486SLC/e microprocessor requires that all data bus pins be driven to a valid logic state (high or low) at the end of each read cycle, when READY# is asserted. When a

read cycle is acknowledged by READY# asserted in the T2 bus state, the Cx486SLC/e CPU latches the information present at its data pins and terminates the cycle.

When a write cycle is performed, the data bus is driven by the Cx486SLC/e CPU beginning in phase two of T1. When a write cycle is acknowledged, the Cx486SLC/e write data remains valid throughout phase one of the next bus state to provide write data hold time.

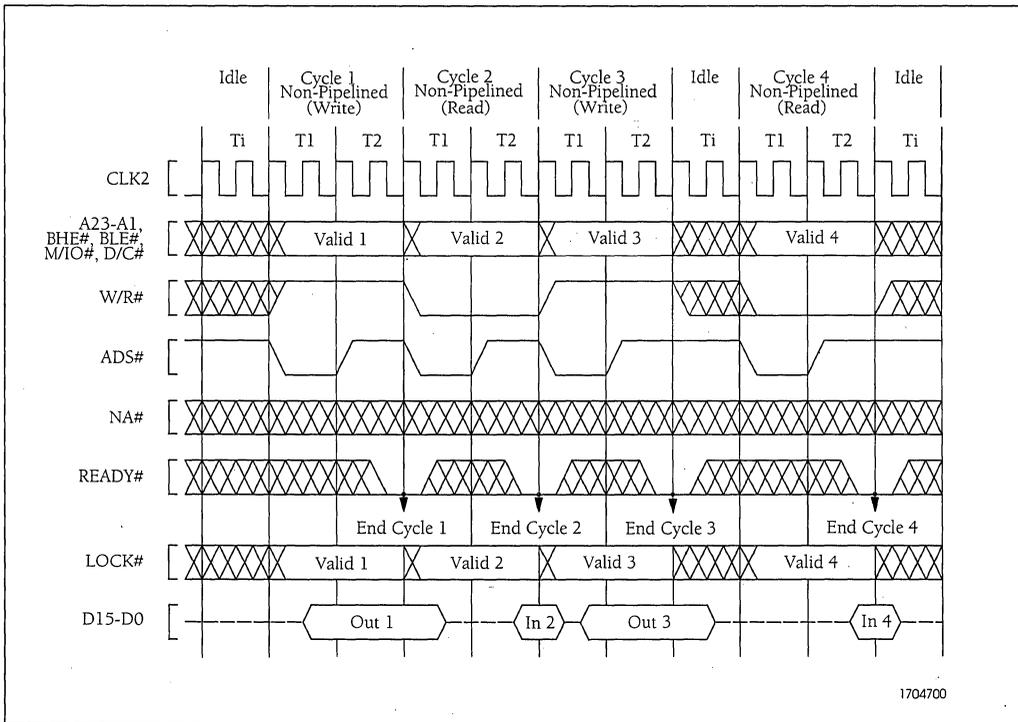


Figure 3-5. Various Non-Pipelined Bus Cycles (no wait states)

Non-Pipelined Wait States

Once a bus cycle begins, it continues until acknowledged by the external system hardware using the READY# input. Acknowledging the bus cycle at the end of the first T2 results in the shortest possible bus cycle, requiring only T1 and T2. If READY# is not immediately asserted however, T2 states are repeated indefinitely until the READY# input is sampled active. These intermediate T2 states are referred to as wait states. If the external system hardware is not able to receive or deliver data in two bus states, it

withholds the READY# signal and at least one wait state is added to the bus cycle. Thus, on an address by address basis the system is able to define how fast a bus cycle completes.

Figure 3-6 illustrates non-pipelined bus cycles with one wait state added to cycles 2 and 3. READY# is sampled inactive at the end of the first T2 state in cycles 2 and 3. Therefore, the T2 state is repeated until READY# is sampled active at the end of the second T2 and the cycle is then terminated. The Cx486SLC/e ignores the READY# input at the end of the T1 state.

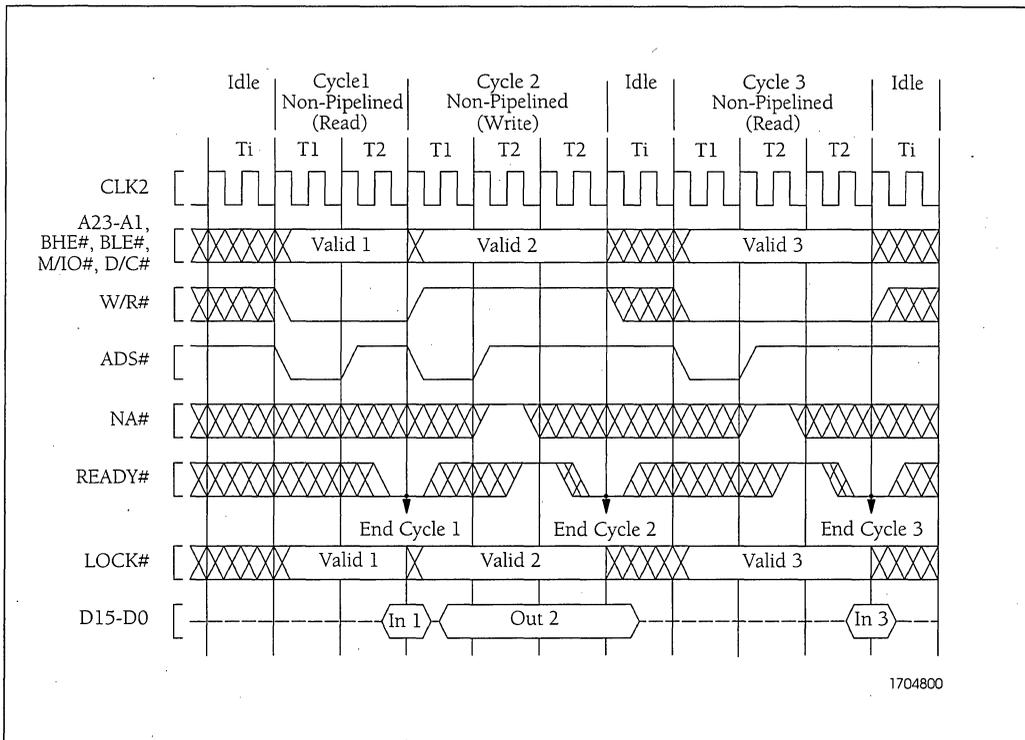


Figure 3-6. Various Non-Pipelined Bus Cycles with Different Numbers of Wait States

Initiating and Maintaining Non-Pipelined Cycles

The bus states and transitions for non-pipelined addressing are illustrated in Figure 3-7. The bus transitions between four possible states: T1, T2, Ti, and Th. Active bus cycles consist of T1 and T2 states, with T2 being repeated for wait states. Bus cycles always begin with a single T1 state. T1 is always followed by a T2 state. If a bus cycle is not acknowledged during a given T2 and NA# is inactive, T2 is repeated resulting in a wait state. When a cycle is acknowledged during T2, the following state is T1 of the next bus cycle if a bus request is pending internally. If no internal bus request is pending, the Ti state is entered. If the HOLD input is asserted and the Cx486SLC/e is ready to enter the hold acknowledged state, the Th state is entered.

Due to the demultiplexed nature of the bus, the address pipelining option provides a mechanism for the external hardware to have an additional T state worth of access time without inserting a wait state. After the reset sequence and following any idle bus state, the processor always uses non-pipelined address timing. Pipelined or non-pipelined address timing is then determined on a cycle-by-cycle basis using the NA# input. When address pipelining is not used, the address and bus cycle definition remain valid during all wait states. When wait states are added and it is desirable to maintain non-pipelined address timing, it is necessary to negate NA# during each T2 state of the bus cycle except the last one.

3.3.2.2 Bus Cycles using Pipelined Addressing

The address pipelining option allows the system to request the address and bus cycle definition of the next internally pending bus cycle before the current bus cycle is acknowledged with READY# asserted. If address pipelining is used, the external system hardware has an extra T state of access time to transfer data. The address pipelining option is controlled on a cycle-by-cycle basis by the state of the NA# input.

Pipelined Bus States

Pipelined addressing is always initiated by asserting NA# during a non-pipelined bus cycle. Within the non-pipelined bus cycle, NA# is sampled at the beginning of phase 2 of each T2 state and is only acknowledged by the Cx486SLC/e during wait states. When address pipelining is acknowledged, the address (BHE#, BLE#, and A23-A1) and bus cycle definition (W/R#, D/C#, and M/IO#) of the next bus cycle are driven before the end of the non-pipelined cycle. The address strobe output (ADS#) is asserted simultaneously to indicate validity of the above signals. Once in effect, address pipelining is maintained in successive bus cycles by continuing to assert NA# during the pipelined bus cycles.

As in non-pipelined bus cycles, the fastest bus cycles using pipelined address require only two bus states. Figure 3-8 illustrates the fastest read cycles using pipelined address timing. The two bus states for pipelined addressing are T1P and

T2P or T1P and T2I. The T1P state is entered following completion of the bus cycle in which the pipelined address and bus cycle definition information was made available and is the first bus state of every pipelined bus cycle.

cycle definition for the next pending bus request is made available. If no pending bus request exists, the T1P state is followed by a T2I state regardless of the state of NA# and no new address or bus cycle information is driven.

Within the pipelined bus cycle, NA# is sampled at the beginning of phase 2 of the T1P state. If the Cx486SLC/e has an internally pending bus request and NA# is asserted, the T1P state is followed by a T2P state and the address and bus

The pipelined bus cycle is terminated in either the T2P or T2I state with the assertion of the READY# input and valid data is either input or output depending on the bus cycle type. READY# is ignored at the end of the T1P state.

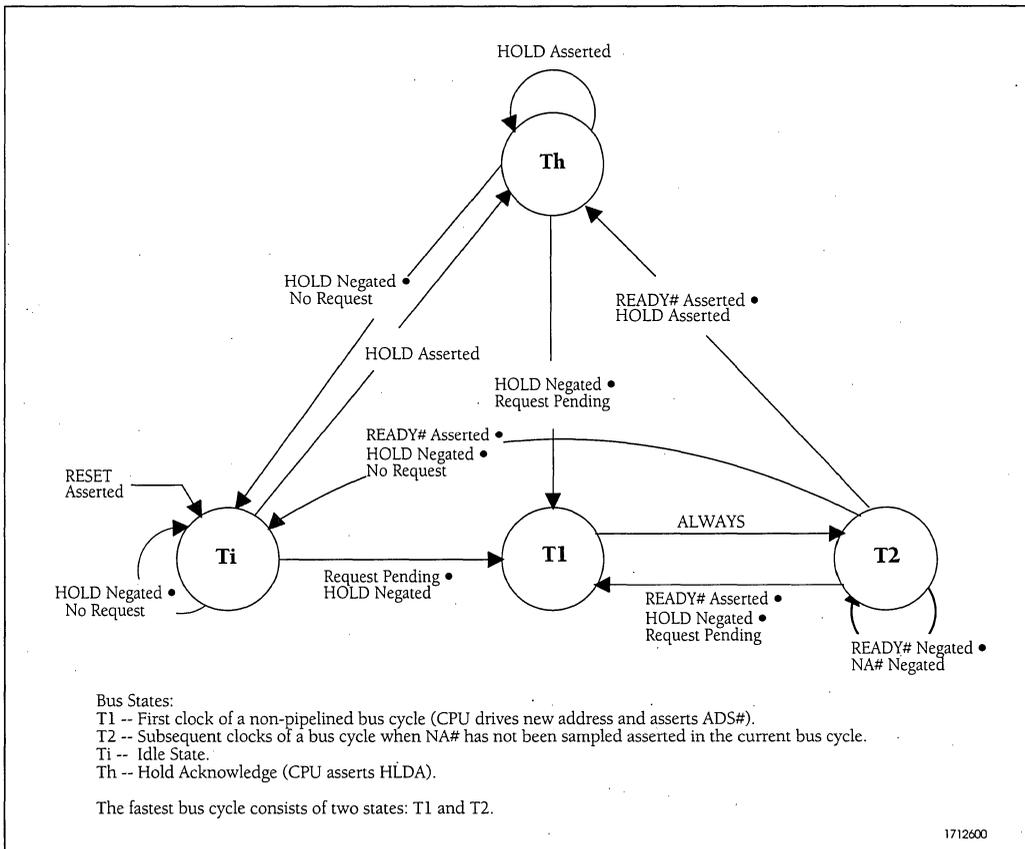


Figure 3-7. Non-Pipelined Bus States

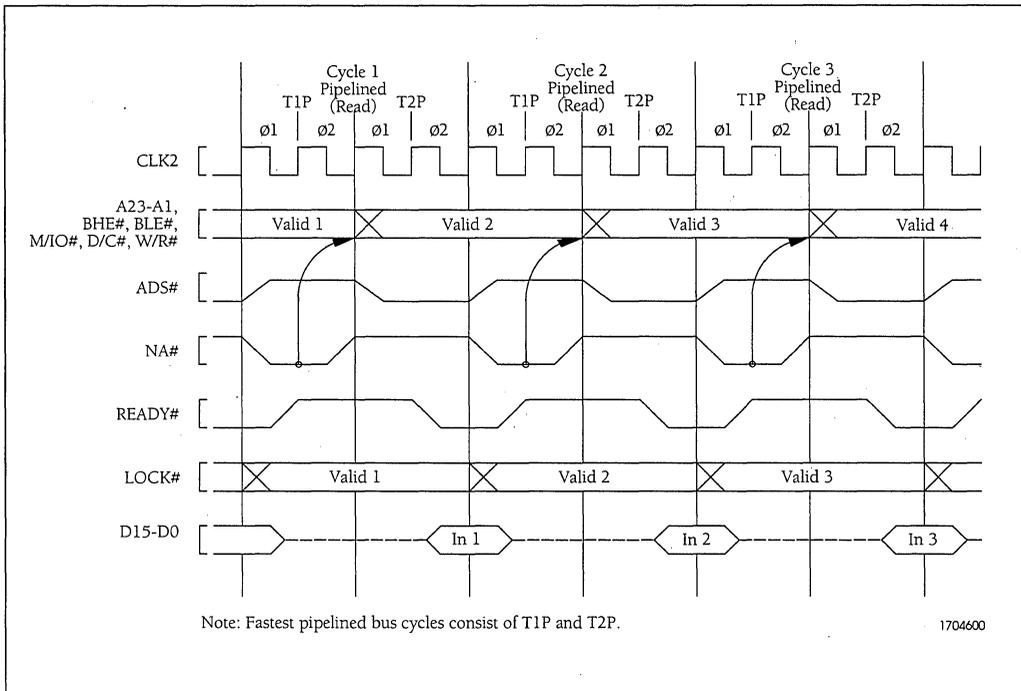


Figure 3-8. Fastest Pipelined Read Cycles

Pipelined Read and Write Cycles

Any bus cycle may be performed with pipelined address timing. When a read cycle is performed, the Cx486SLC/e CPU floats its data bus and the externally addressed device then drives the data. When a read cycle is acknowledged by READY# asserted in either the T2P or T2I bus state, the CPU latches the information present at its data pins and terminates the cycle.

When a write cycle is performed, the data bus is driven by the CPU beginning in phase two of T1P. When a write cycle is acknowledged, the CPU write data remains valid throughout phase one of the next bus state to provide write data hold time.

Wait States for Pipelined Cycles

Once a pipelined bus cycle begins, it continues until acknowledged by the external system hardware using the Cx486SLC/e READY# input. Acknowledging the bus cycle at the end of the first T2P or T2I state results in the shortest possible pipelined bus cycle. If READY# is not immediately asserted, however, T2P or T2I states are repeated indefinitely until the READY# input is sampled active. Additional T2P or T2I states are referred to as wait states.

Figure 3-9 illustrates pipelined bus cycles with one wait state added to cycles 1 through 3. Cycle 1 is a pipelined cycle with NA# asserted during T1P and a pending bus request. READY# is sampled

inactive at the end of the first T2P state in cycle 1. Therefore, the T2P state is repeated until READY# is sampled active at the end of the second T2P and the cycle is then terminated. The Cx486SLC/e ignores the READY# input at the end of the T1P state. Note that ADS#, the address and the bus cycle definition signals for the pending bus cycle are all valid during each of the T2P states. Also, asserting NA# more than once during the cycle has no additional effects. Pipelined addressing can only output information for the very next bus cycle.

Cycle 2 in Figure 3-9 illustrates a pipelined cycle, with one wait state, where NA# is not asserted until the second bus state in the cycle. In this case, the CPU enters the T2 state following T1P because NA# is not asserted. During the T2 state, the Cx486SLC/e samples NA# asserted. Because a bus request is pending internally and READY# is not active, the CPU enters the T2P state and asserts ADS#, valid address and bus cycle definition information for the pending bus cycle. The cycle

is then terminated by an active READY# at the end of the T2P state.

Cycle 3 of Figure 3-9 illustrates the case where no internal bus request exists until the last state of a pipelined cycle with wait states. In cycle 3, NA# is asserted in T1P requesting the next address. Because the CPU does not have an internal bus request pending, the T2I state is entered. However, by the end of the T2I state, a bus request exists. Because READY# is not asserted, a wait state is added. The CPU then enters the T2P state and asserts ADS#, valid address and bus cycle definition information for the pending bus cycle. As long as the CPU enters the T2P state at some point during the bus cycle, pipelined addressing is maintained. NA# need only be asserted once during the bus cycle to request pipelined addressing.

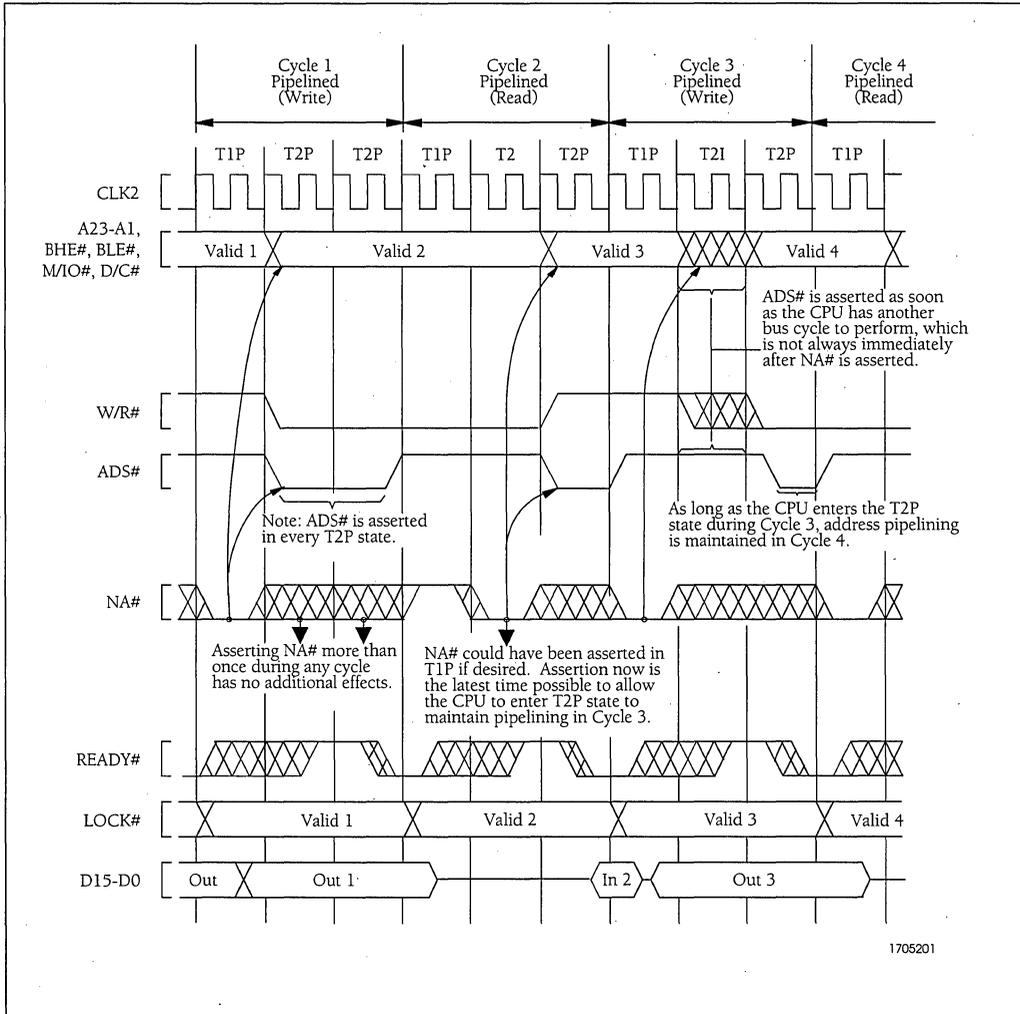


Figure 3-9. Various Pipelined Cycles (one wait state)

Initiating and Maintaining Pipelined Cycles

Pipelined addressing is always initiated by asserting NA# during a non-pipelined bus cycle with at least one wait state. The first bus cycle following RESET, an idle bus or a hold acknowledge state is always non-pipelined. Therefore, the Cx486SLC/e always issues at least one non-pipelined bus cycle following RESET, idle or hold acknowledge before pipelined addressing takes effect.

Once a bus cycle is in progress and the current address has been valid for one entire bus state, the NA# input is sampled at the end of every phase one until the bus cycle is acknowledged. Once

NA# is sampled active, the Cx486SLC/e micro-processor is free to drive a new address and bus cycle definition on the bus as early as the next bus state and as late as the last bus state in the cycle.

Figure 3-10 illustrates the fastest transition possible to pipelined addressing following an idle bus state. In Cycle 1, the next address is driven during state T2P. Thus, Cycle 1 makes the transition to pipelined address timing, since it begins with T1 but ends with T2P. Because the address for Cycle 2 is available before Cycle 2 begins, Cycle 2 is called a pipelined bus cycle and it begins with a T1P state. Cycle 2 begins as soon as READY# asserted terminates Cycle 1.

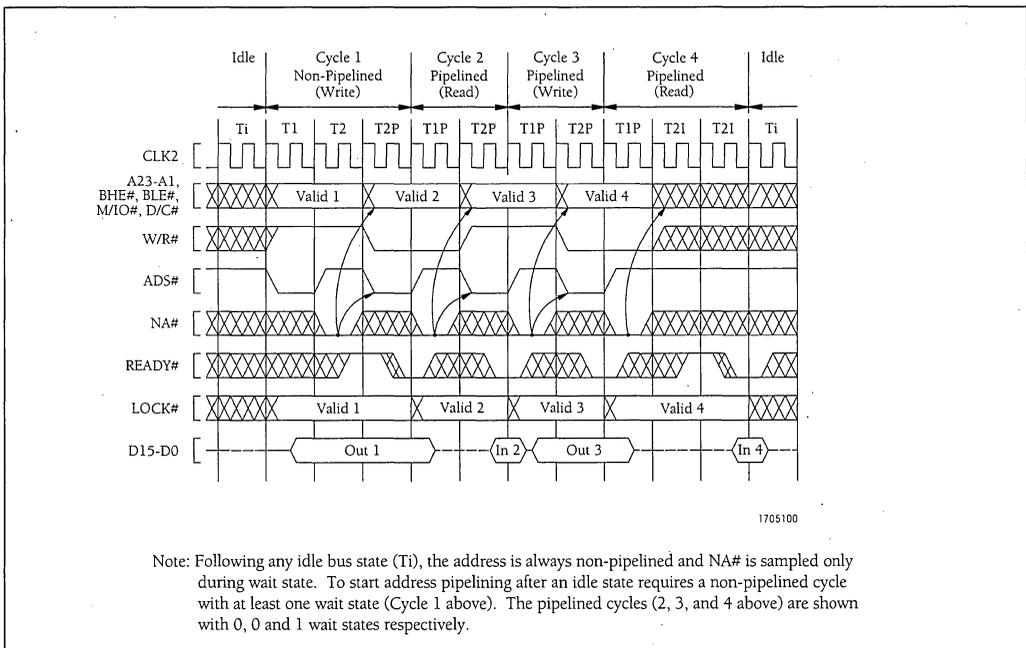


Figure 3-10. Fastest Transition to Pipelined Address Following Idle Bus State

Figure 3-11 illustrates transitioning to pipelined addressing during a burst of bus cycles. Cycle 2 makes the transition to pipelined addressing. Comparing Cycle 2 to Cycle 1 of Figure 3-10 illustrates that a transition cycle is the same whenever it occurs consisting of at least T1, T2 (NA# is asserted at that time), and T2P (provided

the Cx486SLC/e microprocessor has an internal bus request already pending). T2P states are repeated if wait states are added to the cycle. Cycles 2, 3, and 4 in Figure 3-11 show that once address pipelining is achieved it can be maintained with two-state bus cycles consisting only of T1P and T2P.

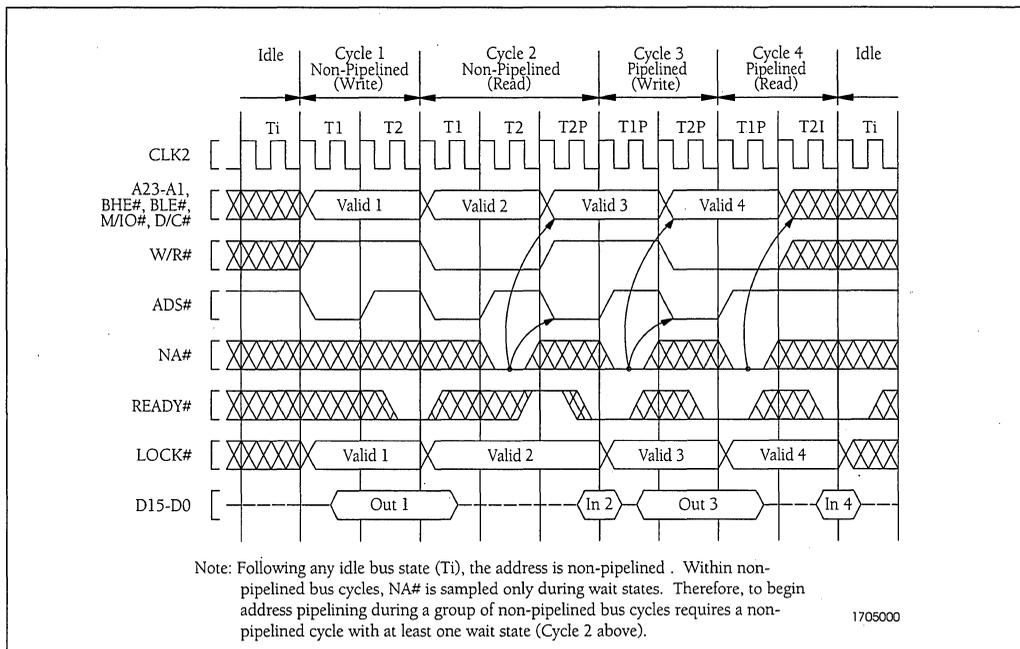


Figure 3-11. Transitioning to Pipelined Address During Burst of Bus Cycles

Once a pipelined bus cycle is in progress, pipelined timing is maintained for the next cycle by asserting NA# and detecting that the Cx486SLC/e microprocessor enters T2P during the current bus cycle. The current bus cycle must end in state T2P for pipelining to be maintained in the next cycle. T2P is identified by the assertion of ADS#. Figures 3-10 and 3-11 each show pipelining ending after Cycle 4. This occurred because the

Cx486SLC/e CPU did not have an internal bus request prior to the acknowledgment of Cycle 4.

The complete bus state transition diagram, including operation with pipelined address is given in Figure 3-12. This is a superset of the diagram for non-pipelined address. The three additional bus states for pipelined address are shaded.

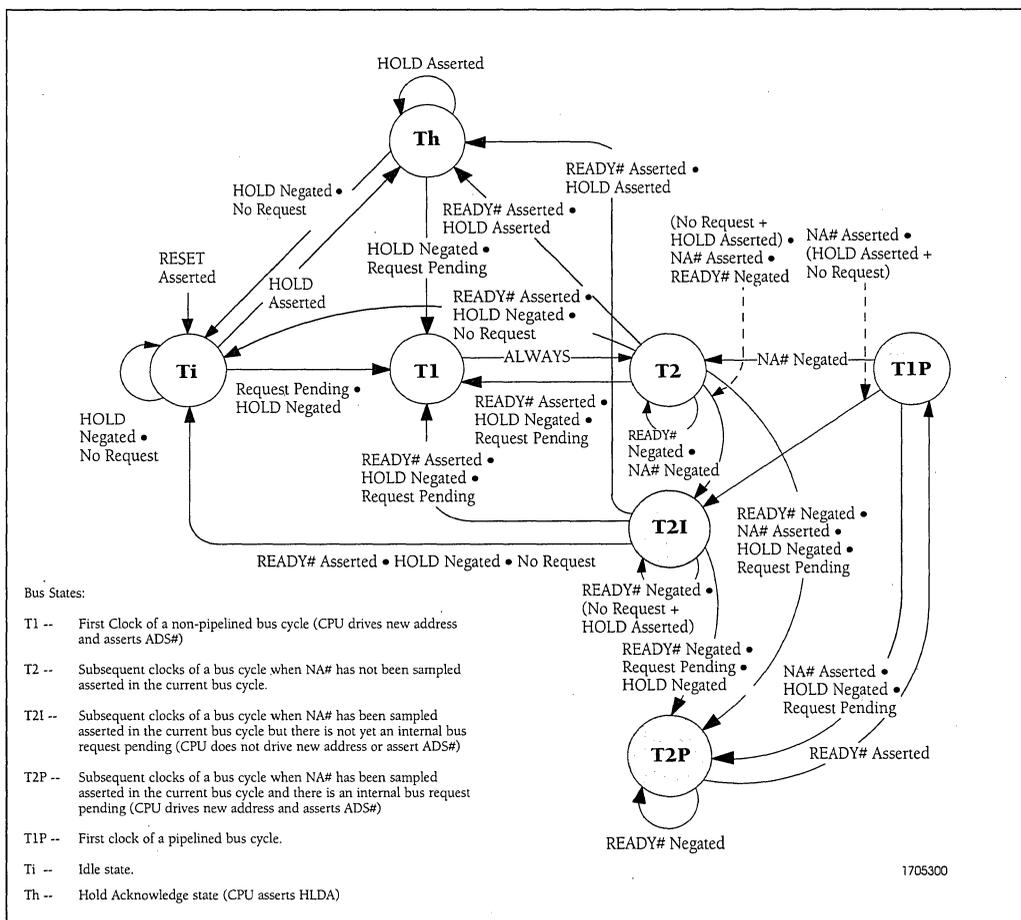


Figure 3-12. Complete Bus States

3.3.3 Locked Bus Cycles

When the LOCK# signal is asserted, the Cx486SLC/e microprocessor does not allow other bus master devices to gain control of the system bus. LOCK# is driven active in response to executing certain instructions with the LOCK prefix. The LOCK prefix allows indivisible read/modify/write operations on memory operands. LOCK# is also active during Interrupt Acknowledge Cycles.

LOCK# is activated on the CLK2 edge that begins the first locked bus cycle and is deactivated when READY# is returned at the end of the last locked bus cycle. When using non-pipelined addressing, LOCK# is asserted during phase 1 of T1. When using pipelined addressing, LOCK# is driven valid during phase 1 of T1P.

Figures 3-4 through 3-6 illustrate LOCK# timing during non-pipelined cycles and Figures 3-8 through 3-11 cover the pipelined address case.

3.3.4 Interrupt Acknowledge (INTA) Cycles

The Cx486SLC/e microprocessor is interrupted by an external source via an input request on the INTR input (when interrupts are enabled). The Cx486SLC/e microprocessor responds with two locked interrupt acknowledge cycles. These bus cycles are similar to read cycles. Each cycle is terminated by READY# sampled active as shown in Figure 3-13.

The state of A2 distinguishes the first and second interrupt acknowledge cycles. The address driven during the first interrupt acknowledge cycle is 4h (A23-A3, A1, BLE# = 0; A2, BHE# = 1). The address driven during the second interrupt acknowledge cycle is 0h (A23-A1, BLE# = 0 and BHE# = 1).

To assure that the interrupt acknowledge cycles are executed indivisibly, the LOCK# output is asserted from the beginning of the first interrupt acknowledge cycle until the end of the second interrupt acknowledge cycle. Four idle bus states (Ti) are always inserted by the Cx486SLC/e microprocessor between the two interrupt acknowledge cycles.

The interrupt vector is read at the end of the second interrupt cycle. The vector is read by the Cx486SLC/e microprocessor from D7-D0 of the data bus. The vector indicates the specific interrupt number (from 0-255) requiring service. Throughout the balance of the two interrupt cycles D15-D0 float. At the end of the first interrupt acknowledge cycle, any data presented to the Cx486SLC/e is ignored.

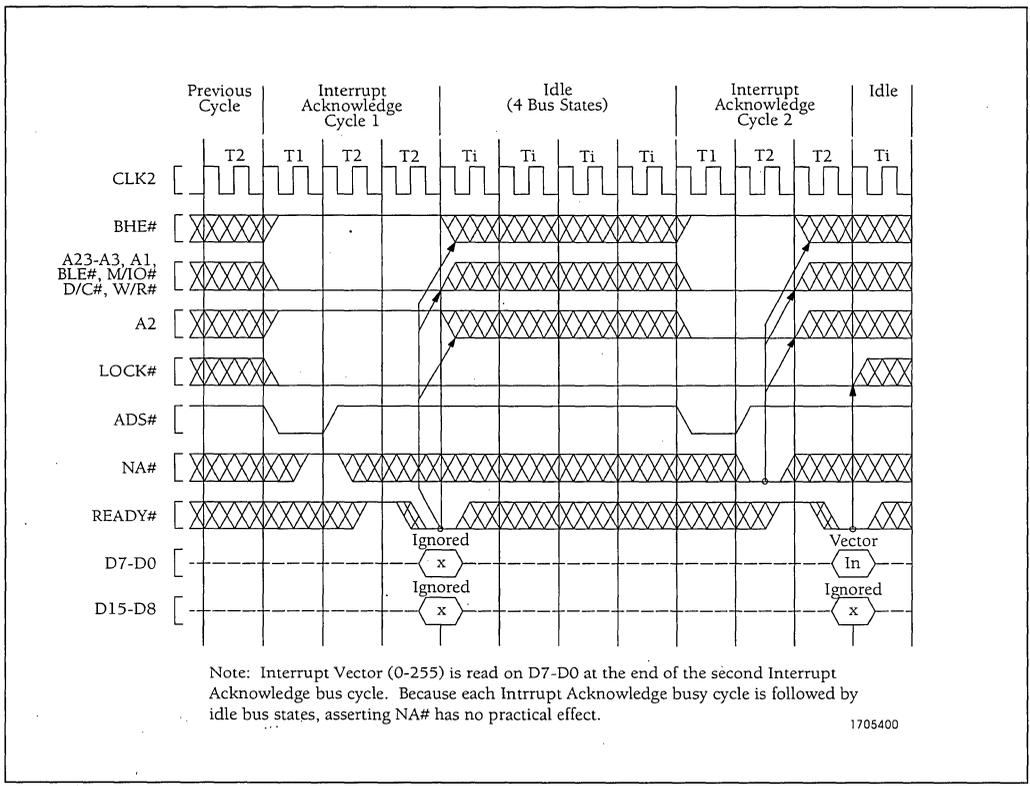


Figure 3-13. Interrupt Acknowledge Cycles

3.3.5 Halt and Shutdown Cycles

Halt Indication Cycle

Executing the HLT instruction causes the Cx486SLC/e execution unit to cease operation. Signaling its entrance into the halt state, a halt indication cycle is performed. The halt indication

cycle is identified by the state of the bus cycle definition signals (M/I/O#=1, D/C#=0, W/R#=1, LOCK#=1) and an address of 2h (A23-A2=0, A1=1, BHE#=1, BLE#=0). The halt indication cycle must be acknowledged by READY# asserted. A halted Cx486SLC/e microprocessor resumes execution when INTR (if interrupts are enabled), NMI, or RESET is asserted. Figure 3-14 illustrates a non-pipelined halt cycle.

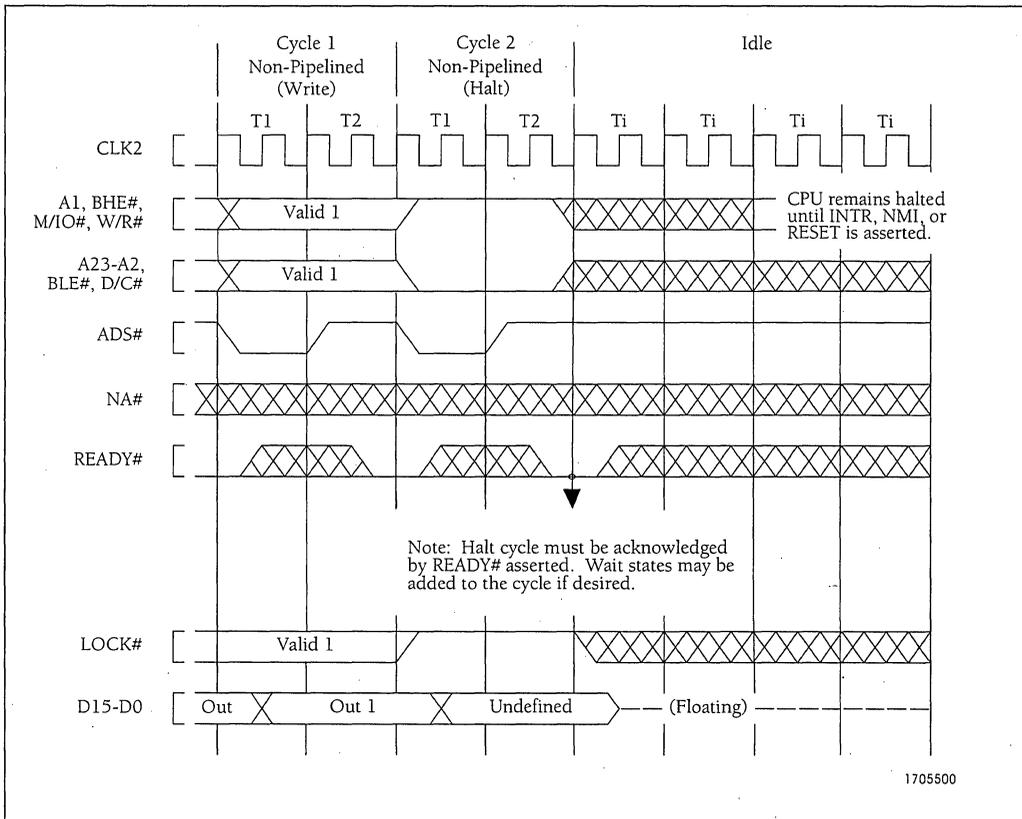


Figure 3-14. Non-pipelined Halt Cycle

Shutdown Indication Cycle

Shutdown occurs when a severe error is detected that prevents further processing. Signaling its entrance into the shutdown state, the CPU issues a shutdown indication cycle. The shutdown indication cycle is identified by the state of the bus cycle definition signals (M/I/O#=1, D/C#=0,

W/R#=1, LOCK=1) and an address of 0h (A23-A1 = 0, BHE# = 1, BLE#=0). The shutdown indication cycle must be acknowledged by READY# asserted. A shut down Cx486SLC/e microprocessor resumes execution only when NMI or RESET is asserted. Figure 3-15 illustrates a shutdown cycle using pipelined addressing.

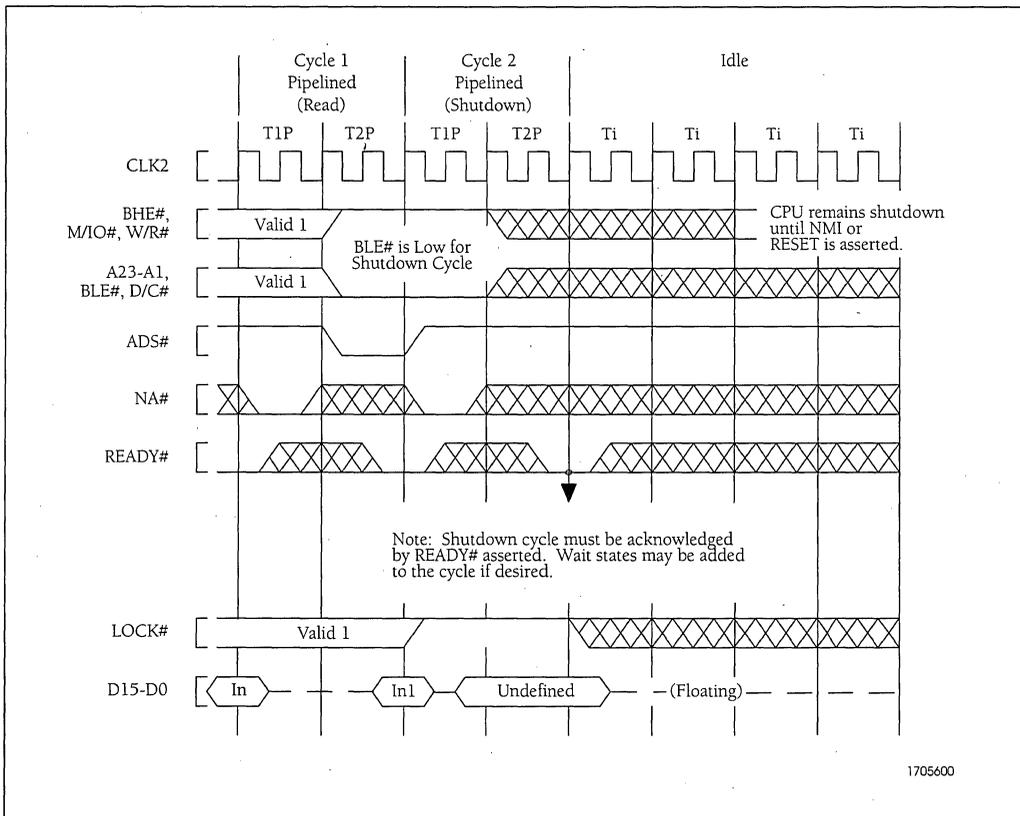


Figure 3-15. Pipelined Shutdown Cycle

3.3.6 Internal Cache Interface

3.3.6.1 Cache Fills

Any unlocked memory read cycle can be cached by the Cx486SLC/e. The Cx486SLC/e automatically does not cache accesses to memory addresses specified by the non-cacheable region registers. Additionally, the KEN# input can be used to enable caching of memory accesses on a cycle-by-cycle basis. The Cx486SLC/e acknowledges the KEN# input only if the KEN enable bit is set in the CCR0 configuration register.

As shown in Figures 3-16 and 3-17, the Cx486SLC/e samples the KEN# input one CLK2 before READY# is sampled active. If KEN# is asserted and the current address is not set as non-cacheable per the non-cacheable region registers, then the Cx486SLC/e fills two bytes of a line in the cache with the data present on the data bus pins. The states of BHE# and BLE# are ignored if KEN# is asserted for the cycle.

If the RPL bit in the CCR1 configuration register is set, then the RPLSET and RPLVAL# output signals are driven by the Cx486SLC/e during cache fill cycles. If the cache is configured as direct-mapped (CO bit in CCR0 configuration register), RPLSET is always driven low. If the cache is configured as two-way set associative, RPLSET indicates which set in the cache is undergoing a line replacement. RPLVAL# indicates that the Cx486SLC/e will perform a cache fill to the indicated set with the data present on the data bus pins at the time READY# is sampled active. However, if KEN# is enabled and sampled inactive, the data is not cached and the line in the set indicated by RPLSET is not overwritten.

Figures 3-16 and 3-17 illustrate RPLVAL# and RPLSET functional timing for both non-pipelined and pipelined cache fills. RPLVAL# is driven at the same time and for the same duration as the ADS# output for the cache fill cycle. RPLSET is driven one CLK2 after RPLVAL# is driven regardless of whether or not the current bus cycle is pipelined.

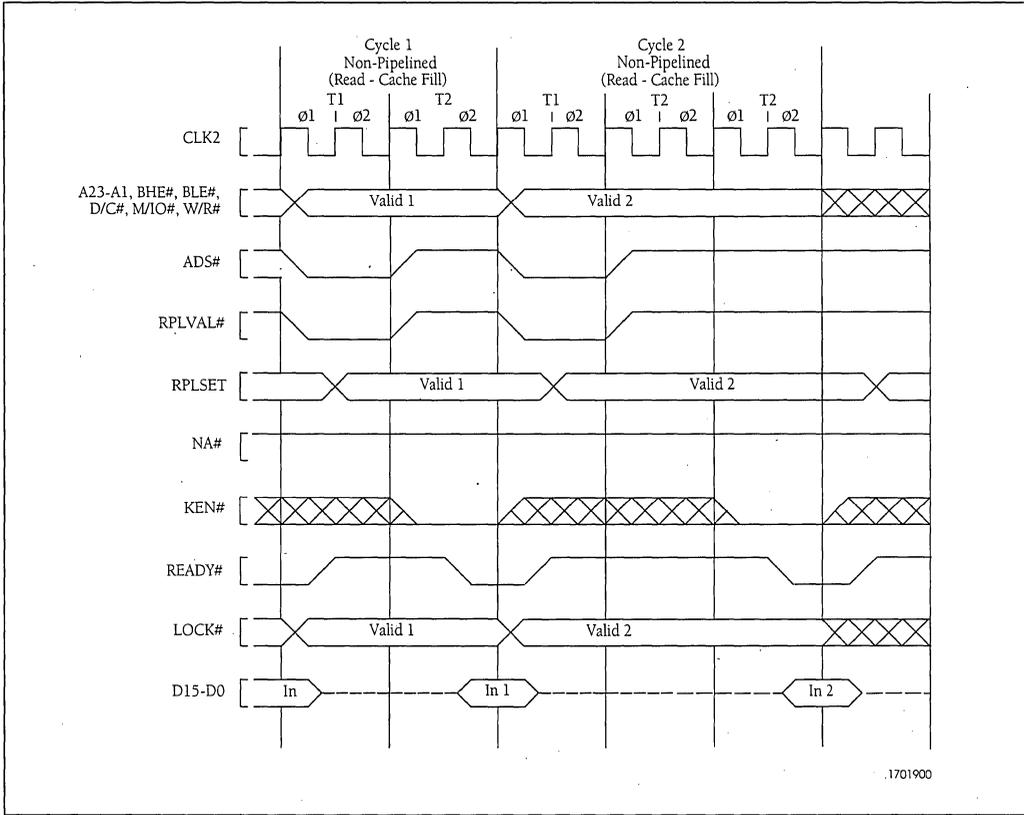


Figure 3-16. Non-Pipelined Cache Fills using KEN#

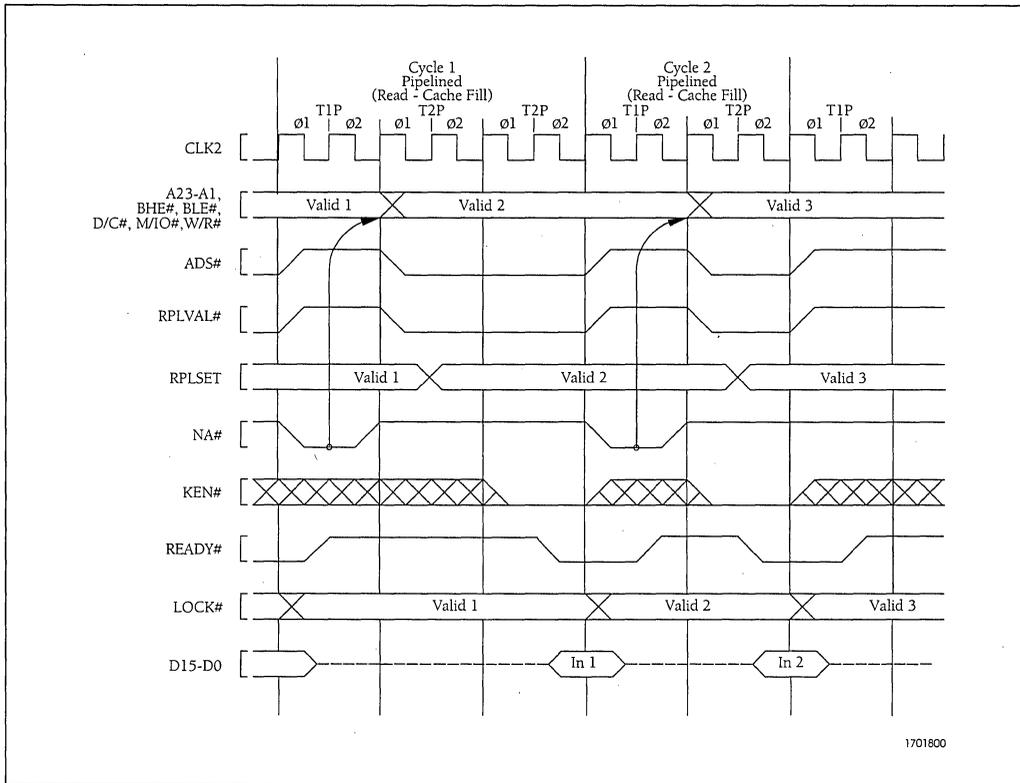


Figure 3-17. Pipelined Cache Fills using KEN#

3.3.6.2 Flushing the Cache

To maintain cache coherency with external memory, the Cx486SLC/e cache contents should be invalidated when previously cached data is modified in external memory by another bus master. The Cx486SLC/e invalidates the internal cache contents during execution of the INVD and WBINVD instructions, following assertion of HLDA if the BARB bit is set in the CCR0 configuration register, or following assertion of FLUSH# if the FLUSH bit is set in CCR0.

The Cx486SLC/e samples the FLUSH# input on the rising edge of CLK2 corresponding to the beginning of phase 2 of the internal processor clock. If FLUSH# is asserted, the Cx486SLC/e invalidates the entire contents of the internal cache. The actual point in time where the cache is invalidated depends upon the internal state of the execution pipeline. FLUSH# must be asserted for at least two CLK2 periods and must meet specified setup and hold times to be recognized on a specific CLK2 edge.

An alternative to using the A20M# pin is provided by the NCO bit in the CCR0 cache control configuration register. The Cx486SLC/e automatically does not cache accesses, to the first 64 KBytes and to the first 64 KBytes at each 1-MByte boundary, if the NCO bit is set. This prevents data within the wrap-around memory area from residing in the internal cache and thus eliminates the need for masking A20 to the internal cache.

3.3.8 Hold Acknowledge State

The hold acknowledge state provides the mechanism for an external device in a Cx486SLC/e system to acquire the Cx486SLC/e system bus while the Cx486SLC/e is held in an inactive bus state. This allows external "bus masters" to take control of the Cx486SLC/e bus and directly access system hardware in a shared manner with the Cx486SLC/e. The Cx486SLC/e continues to execute instructions out of the cache (if enabled) until a system bus cycle is required.

The hold acknowledge state (Th) is entered in response to assertion of the HOLD input. In the hold acknowledge state, the Cx486SLC/e microprocessor floats all output and bi-directional signals, except for HLDA and SUSPA#. HLDA is asserted as long as the Cx486SLC/e CPU remains in the hold acknowledge state and all inputs except HOLD, FLUSH#, FLT#, SUSP# and RESET are ignored.

Th may be entered directly from a bus idle state, as in Figure 3-19, or after the completion of the current physical bus cycle if the LOCK# signal is not asserted, as in Figures 3-20 and 3-21. The CPU samples the HOLD input on the rising edge of CLK2 corresponding to the beginning of phase 1 of the internal processor clock. HOLD must meet specified setup and hold times to be recognized at a given CLK2 edge.

The hold acknowledge state is exited in response to the HOLD input being negated. The next bus state is an idle state (Ti) if no bus request is pending, as in Figure 3-19. If a bus request is internally pending, as in Figures 3-20 and 3-21, the next bus state is T1. Th is also exited in response to RESET being asserted. If HOLD remains asserted when RESET goes inactive, the Cx486SLC/e enters the hold acknowledge state before performing any bus cycles provided HOLD is still asserted when the CPU is ready to perform its first bus cycle.

If a rising edge occurs on the edge-triggered NMI input while in the Th state, the event is remembered as a non-maskable interrupt 2 and is serviced when the Th state is exited.

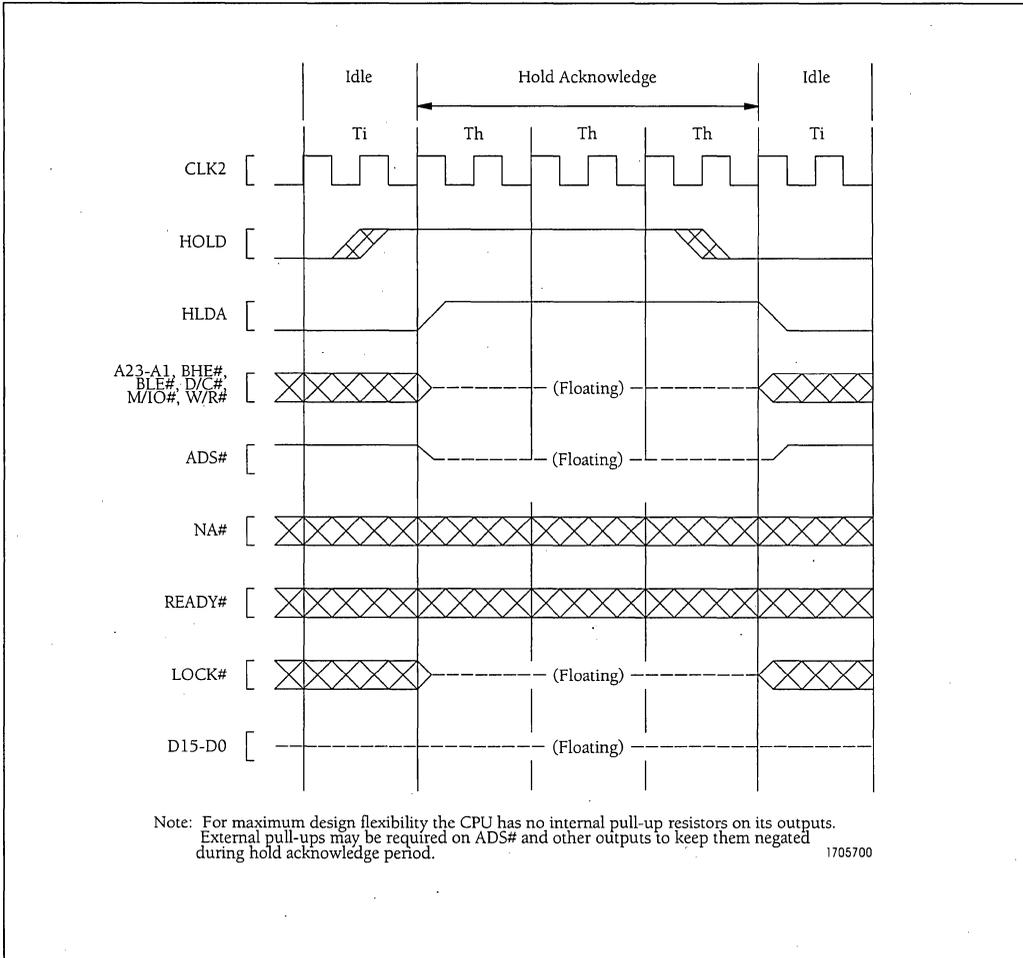


Figure 3-19. Requesting Hold from Idle Bus State

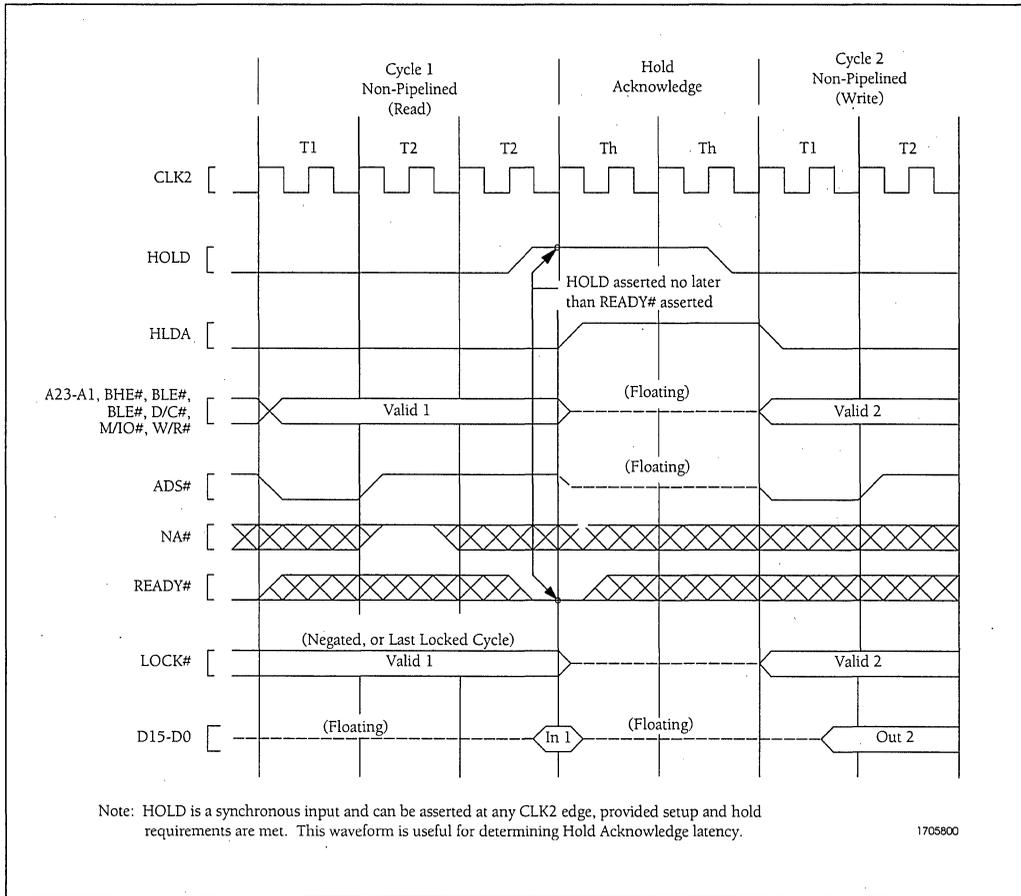


Figure 3-20. Requesting Hold from Active Non-Pipelined Bus

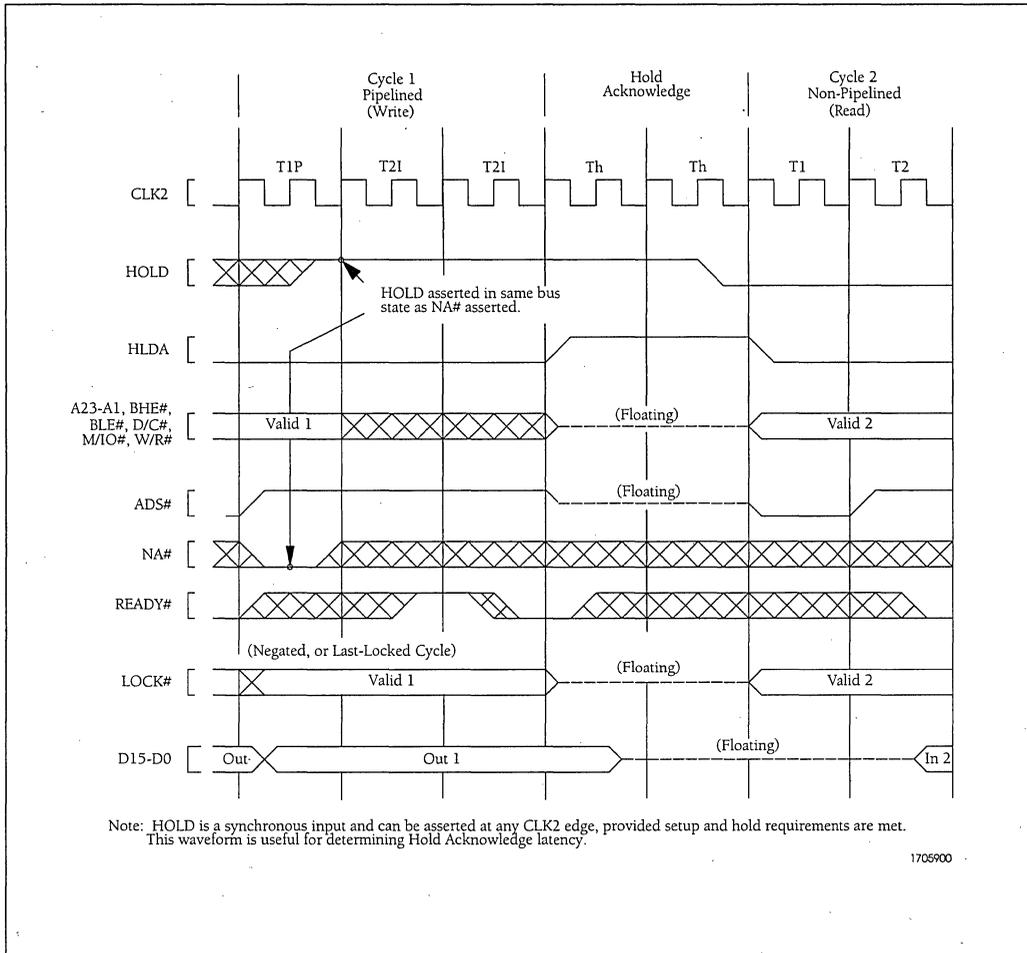


Figure 3-21. Requesting Hold from Active Pipelined Bus

3.3.9 Coprocessor Interface

The coprocessor interface consists of the data bus, address bus, bus cycle definition signals, and the coprocessor interface signals (BUSY#, ERROR# and PEREQ). The Cx486SLC/e automatically accesses dedicated coprocessor I/O addresses 80 00F8h, 80 00FCh and 80 00FEh to transfer opcodes and operands to/from the coprocessor whenever a coprocessor instruction is decoded. Coprocessor cycles can be either read or write and can be either non-pipelined or pipelined. Coprocessor cycles must be terminated by READY# and, as with any other bus cycle, can be terminated as early as the second bus state of the cycle.

BUSY#, ERROR# and PEREQ are asynchronous level-sensitive inputs used to synchronize CPU and coprocessor operation. All three signals are sampled at the beginning of phase 1 and must meet specified setup and hold times to be recognized at a given CLK2 edge.

3.3.10 SMM Interface

System Management Mode (SMM) uses two Cx486SLC/e pins, SMI# and SMADS#. The bi-directional SMI# pin is a non-maskable interrupt that is higher priority than the NMI input. SMI# must be active for at least four CLK2 periods to be recognized by the Cx486SLC/e. Once the Cx486SLC/e recognizes the active SMI# input, the CPU drives the SMI# pin low for the duration of the SMI service routine.

The SMADS# pin outputs the SMM Address Strobe which indicates that a SMM memory bus cycle is in progress and a valid SMM address is on the address bus. The SMADS# functional timing, output delay times and float delay times are identical to the main memory address strobe (ADS#) timing.

SMI Handshake

The functional timing for SMI# interrupt is shown in Figure 3-22. Five significant events take place during a Cx486SLC/e SMI# handshake:

- (a) The SMI# input pin is driven active (low) by the system logic.
- (b) The CPU samples SMI# active on the rising edge of CLK2 phase 1.
- (c) Four CLK2s after sampling the SMI# active, the CPU switches the SMI# pin to an output and drives SMI# low.
- (d) Following execution of the RSM instruction the CPU drives the SMI# pin high for two CLK2s indicating completion of the SMI service routine.
- (e) The CPU stops driving the SMI# pin high and switches the SMI# pin to an input in preparation for the next SMI interrupt. The system logic is responsible for maintaining the SMI# pin at an inactive (high) level after the pin has been changed to an input.

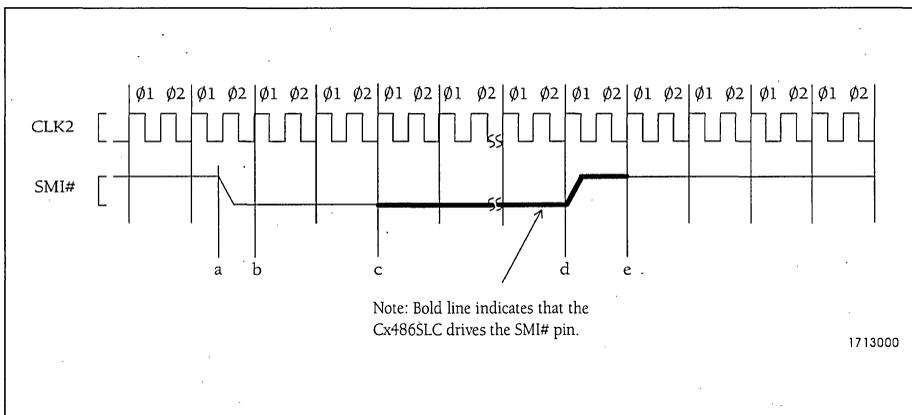


Figure 3-22. SMI# Timing

I/O Trapping

The Cx486SLC/e provides I/O trapping which can be used to facilitate power management of I/O peripherals. When an I/O bus cycle is issued, the I/O address is driven onto the address bus and can be decoded by external logic. If a trap to the SMI handler is required, the SMI# input should be activated at least three CLK2 edges prior

to returning the READY# input for the I/O cycle. The timing for creating an I/O trap via the SMI# input is shown in Figure 3-23. The Cx486SLC/e immediately traps to the SMI interrupt handler following execution of the I/O instruction, and no other instructions are executed between completion of the I/O instruction and entering the SMI service routine. The I/O trap mechanism is not active during coprocessor accesses.

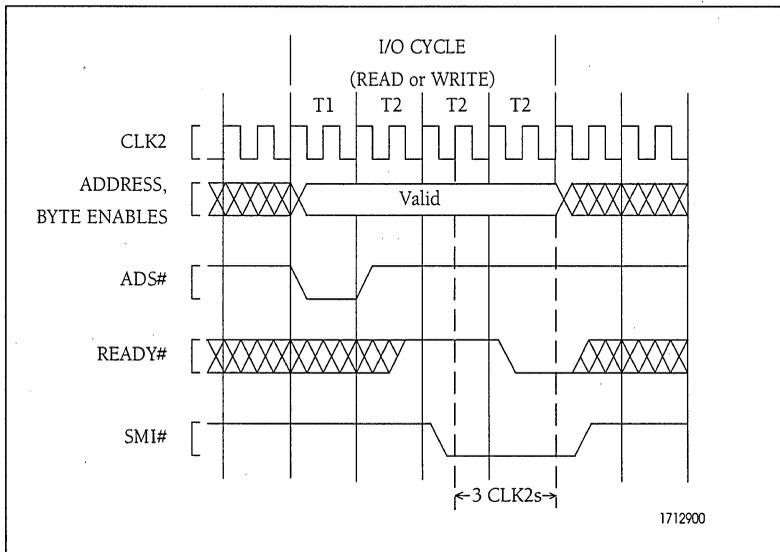


Figure 3-23. I/O Trap Timing

3.3.1.1 Power Management

SUSP# Initiated Suspend Mode

The Cx486SLC/e enters suspend mode when the SUSP# input is asserted and execution of the current instruction, any pending decoded instructions and associated bus cycles are completed. The Cx486SLC/e CPU also waits for the coprocessor not busy (BUSY# negated) prior to entering suspend mode (Figure 3-24). The SUSPA# output is asserted. The Cx486SLC/e responds to SUSP# and asserts SUSPA# only if the SUSP bit is set in the CCR0 configuration register.

SUSP# is sampled on the rising edge of phase 2 CLK2. SUSP# must meet specified setup and hold times to be recognized at a particular CLK2 edge. The time from assertion of SUSP# to activation of SUSPA# varies depending on which

instructions were decoded prior to assertion of SUSP#. The minimum time from SUSP# sampled active to SUSPA# asserted is two CLK2s. As a maximum, the CPU may execute up to two instructions and associated bus cycles prior to asserting SUSPA#. The time required for the CPU to deactivate SUSPA# once SUSP# has been sampled inactive is four CLK2s.

If the CPU is in a hold acknowledge state and SUSP# is asserted, the CPU may or may not enter suspend mode depending on the state of the CPU internal execution pipeline. If the CPU is in a SUSP# initiated suspend state and the CLK2 input is not stopped, the processor recognizes and acknowledges the HOLD input and stores the occurrence of FLUSH#, NMI, SMI# and INTR (if enabled) for execution once suspend mode is exited.

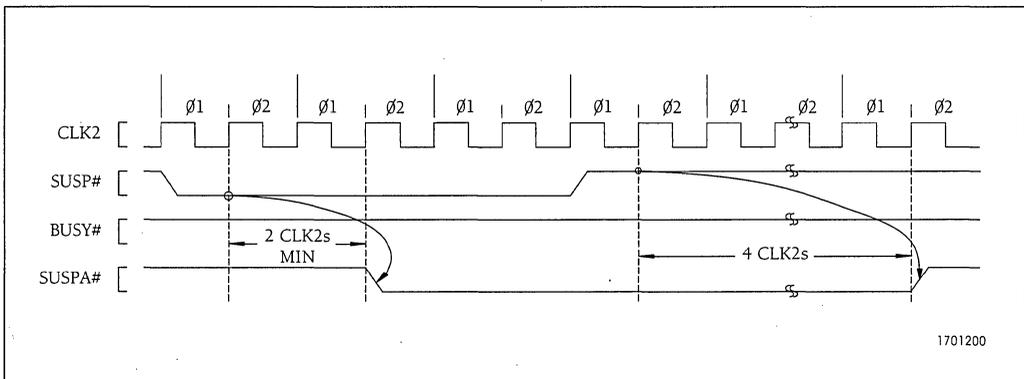


Figure 3-24. SUSP# Initiated Suspend Mode

HALT Initiated Suspend Mode

The Cx486SLC/e also enters suspend mode as a result of executing a HALT instruction. The SUSPA# output is asserted no more than 17 CLK2s following READY# sampled active for the HALT bus cycle as shown in Figure 3-25. Suspend mode is then exited upon recognition of an NMI

or an unmasked INTR. SUSPA# is deactivated 12 CLK2s after sampling of an active NMI or unmasked INTR. If the Cx486SLC/e is in a HALT initiated suspend mode and the CLK2 input is not stopped, the processor recognizes and acknowledges the HOLD input and stores the occurrence of FLUSH# for execution once suspend mode is exited.

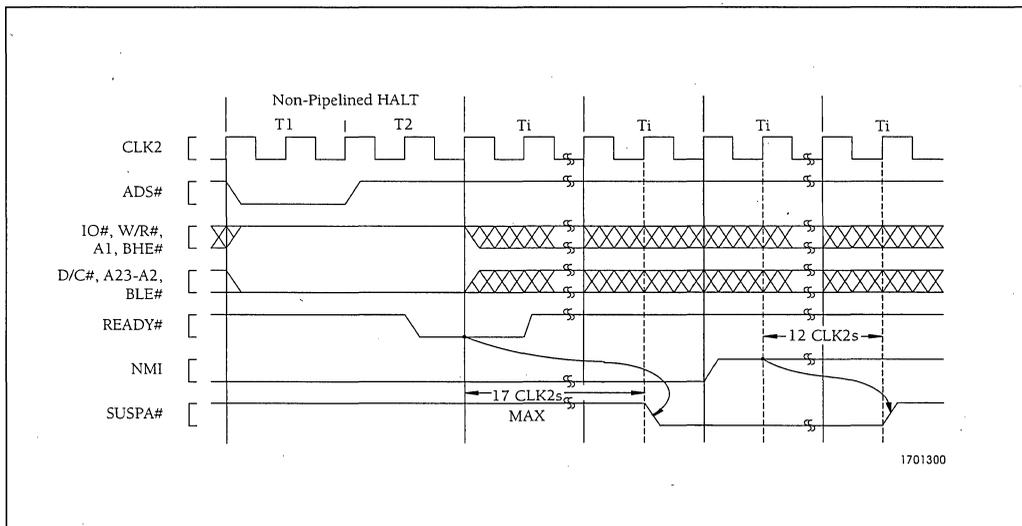


Figure 3-25. Halt Initiated Suspend Mode

Stopping the Input Clock

Because the Cx486SLC/e is a static device, the input clock (CLK2) can be stopped and restarted without loss of any internal CPU data. CLK2 can be stopped in either phase 1 or phase 2 of the clock and either in a logic high or logic low state. However, entering suspend mode prior to stopping CLK2 dramatically reduces the CPU current requirements. Therefore, the recommended sequence for stopping CLK2 is to initiate Cx486SLC/e suspend mode, wait for assertion of SUSPA# by the processor and then stop the input clock.

The Cx486SLC/e remains suspended until CLK2 is restarted and suspend mode is exited as described earlier. While CLK2 is stopped, the Cx486SLC/e can no longer sample and respond to any input stimulus including the HOLD, FLUSH#, NMI, INTR and RESET inputs.

Figure 3-26 illustrates the recommended sequence for stopping CLK2 using SUSP# to initiate suspend mode. CLK2 may be started prior to or following negation of the SUSP# input.

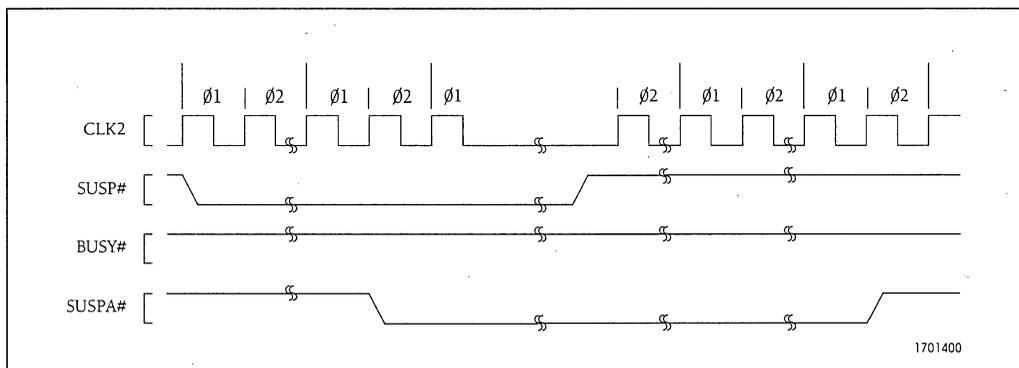


Figure 3-26. Stopping CLK2 During Suspend Mode

3.3.11 Float

Activating the FLT# input floats all Cx486SLC/e microprocessor bi-directional and output signals. Asserting FLT# electrically isolates the Cx486SLC/e microprocessor from the surrounding circuitry. This feature is useful in board-level test environments. As the Cx486SLC/e microprocessor is packaged in a surface mount PQFP, it is not usually socketed and cannot be removed from the motherboard when In-Circuit Emulation (ICE) is needed. Float capability allows connection of an emulator by clamping the emulator probe onto the Cx486SLC/e microprocessor PQFP without removing it from the circuit board.

FLT# is an asynchronous, active low input. It is recognized on the rising edge of CLK2. When

recognized, it aborts the current bus state and floats the outputs of the Cx486SLC/e microprocessor as shown in Figure 3-27. FLT# must be asserted for a minimum of 16 CLK2 cycles. To exit the float condition, RESET should be asserted and held asserted until after FLT# is deasserted.

Asserting the FLT# input unconditionally aborts the current bus cycle and forces the Cx486SLC/e microprocessor into the float mode. As a result, the Cx486SLC/e microprocessor is not guaranteed to enter float in a valid state. After deactivating FLT#, the Cx486SLC/e CPU is not guaranteed to exit float in a valid state. The Cx486SLC/e microprocessor RESET input must be asserted prior to exiting float to guarantee that the Cx486SLC/e is reset and that it returns to a valid state.

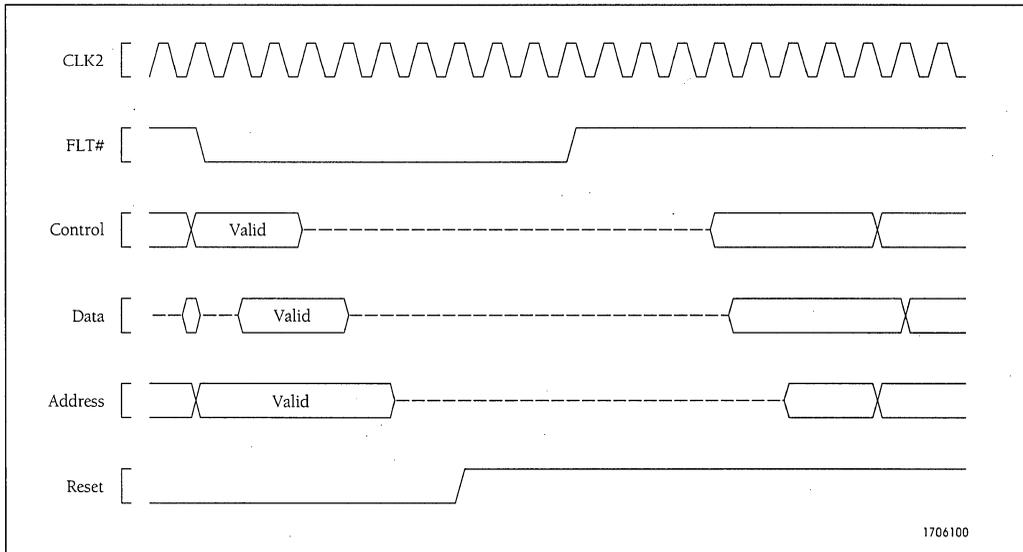


Figure 3-27. Entering and Exiting Float

CYRIX Cx486SLC/e™ MICROPROCESSOR

High-Performance 486-Class CPU with Advanced Power Management for Notebook and Battery-Powered Systems



Electrical Specifications

4. ELECTRICAL SPECIFICATIONS

4.1 Electrical Connections

4.1.1 Power and Ground Connections and Decoupling

Due to the high frequency of operation of the Cx486SLC/e, it is necessary to install and test this device using standard high frequency techniques. The high clock frequencies used in the Cx486SLC/e and its output buffer circuits can cause transient power surges when several output buffers switch output levels simultaneously. These effects can be minimized by filtering the DC power leads with low-inductance decoupling capacitors, using low impedance wiring, and by utilizing all of the 14 V_{CC} and 18 GND pins.

4.1.2 Pull-Up/Pull-Down Resistors

Table 4-1 lists the input pins which are internally connected to pull-up and pull-down resistors. The pull-up resistors are connected to V_{CC} and the pull-down resistors are connected to V_{SS} . When unused, these inputs do not require connection to external pull-up or pull-down resistors.

Table 4-1. Pins Connected to Internal Pull-Up and Pull-Down Resistors

SIGNAL	PIN	RESISTOR
A20M#	31	20-k Ω pull-up
BUSY#	34	20-k Ω pull-up
ERROR#	36	20-k Ω pull-up
FLT#	28	20-k Ω pull-up
FLUSH#	30	20-k Ω pull-up
KEN#	29	20-k Ω pull-up
PEREQ	37	20-k Ω pull-down
SMI#	47	20-k Ω pull-up
SUSP#	43	20-k Ω pull-up

It is recommended that the ADS# and LOCK# output pins be connected to pull-up resistors, as indicated in Table 4-2. The external pull-ups guarantee that the signals will remain negated during hold acknowledge states.

Table 4-2. Pins Requiring External Pull-Up Resistors

SIGNAL	PIN	EXTERNAL RESISTOR
ADS#	16	20-k Ω pull-up
LOCK#	26	20-k Ω pull-up

4.1.3 Unused Input Pins

All inputs not used by the system designer and not listed in Table 4-1 should be connected either to ground or to V_{CC} . Connect active-high inputs to ground through a 20 k Ω (\pm 10%) pull-down resistor and active-low inputs to V_{CC} through a 20 k Ω (\pm 10%) pull-up resistor to prevent possible spurious operation.

4.1.4 N/C Designated Pins

Pins designated N/C should be left disconnected. Connecting an N/C pin to a pull-up resistor, pull-down resistor, or an active signal could cause unexpected results and possible circuit malfunctions.

4.2 Absolute Maximum Ratings

The following table lists absolute maximum ratings for the Cx486SLC/e and Cx486SLC/e-V microprocessors. Stresses beyond those listed under Table 4-3 limits may cause permanent damage to the device. These are stress ratings only and do not imply that operation under any conditions other than those listed under "Recommended Operating Conditions" (Table 4-4) is possible. Exposure to conditions beyond Table 4-3 may (1) reduce device reliability and (2) result in premature failure even when there is no immediately apparent sign of failure. Prolonged exposure to conditions at or near the absolute maximum ratings (Table 4-3) may also result in reduced useful life and reliability.

Table 4-3. Absolute Maximum Ratings

PARAMETER	MIN	MAX	UNITS	NOTES
Case Temperature	-65°	+110°	C	Power Applied
Storage Temperature	-65°	+150°	C	No Bias
Supply Voltage, V_{CC}	-0.5	6.5	V	With Respect to V_{SS}
Voltage On Any Pin	-0.5	$V_{CC} + 0.5$	V	With Respect to V_{SS}
Input Clamp Current, I_{IK}		10	mA	Power Applied
Output Clamp Current, I_{OK}		25	mA	Power Applied

4.3 Recommended Operating Conditions

The following table presents the recommended operating conditions for the Cx486SLC/e and Cx486SLC/e-V devices. The Cx486SLC/e-V can be operated as a Cx486SLC/e.

Table 4-4. Recommended Operating Conditions

PARAMETER	Cx486SLC/e		Cx486SLC/e-V		UNITS	NOTES
	MIN	MAX	MIN	MAX		
T _C Case Temperature	0°	+100°	0°	+85°	C	Power Applied
V _{CC} Supply Voltage (-20, -25)	4.5	5.5	3.0	3.6	V	With Respect to V _{SS}
V _{CC} Supply Voltage (-33)	4.75	5.25			V	With Respect to V _{SS}
V _{IH} High Level Input	2.0	V _{CC} + 0.3	2.0	V _{CC} + 0.3	V	
V _{IL} Low Level Input	-0.3	0.8	-0.3	0.6	V	
V _{ILC} CLK2 Input LOW Voltage	-0.3	0.8	-0.3	0.5	V	
V _{IHC} CLK2 Input HIGH Voltage	3.7	V _{CC} + 0.3	V _{CC} - 0.5	V _{CC} + 0.3	V	
I _{OH} Output Current (High)		-1.0		-1.0	mA	V _{OH} = V _{OH(min)}
I _{OL} Output Current (Low)		5.0		3.0	mA	V _{OL} = V _{OL(max)}
I _{IK} Input Clamp Current		+10		+10	mA	V _{IN} < V _{SS} or V _{IN} > V _{CC}
I _{OK} Output Clamp Current		+25		+25	mA	V _{OUT} < V _{SS} or V _{OUT} > V _{CC}

4.4 DC Characteristics

Table 4-5. DC Characteristics (at Recommended Operating Conditions)

PARAMETER	Cx486SLC/e		Cx486SLC/e-V		UNITS	NOTES
	MIN	MAX	MIN	MAX		
V _{OL} Output Low Voltage I _{OL} = 3 mA I _{OL} = 5 mA		0.45		0.35	V	
V _{OH} Output High Voltage I _{OH} = -1 mA I _{OH} = -0.2 mA	2.4 V _{CC} - 0.5		V _{CC} - 0.4 V _{CC} - 0.4		V	
I _{II} Input Leakage Current For all pins except for pins using pull up/down resistors (see manual).		±15		±15	µA	0 < V _{IN} < V _{CC}
I _{IH} Input Leakage Current PEREQ		200		200	µA	V _{IN} = 2.4 Note 1
I _{IL} Input Leakage Current A20M#, BUSY#, ERROR#, FLT#, FLUSH#, KEN#, SUSP#		-400		-400	µA	V _{IL} = 0.45V Note 2
I _{CC} Active I _{CC} 20 MHz (CLK2 = 40 MHz) 25 MHz (CLK2 = 50 MHz) 33 MHz (CLK2 = 66 MHz)	Typical: 360 395 495	450 495 615	Typical: 185 225 -	235 285 -	mA	
I _{CCSM} Suspend Mode I _{CC} 20 MHz (CLK2 = 40 MHz) 25 MHz (CLK2 = 50 MHz) 33 MHz (CLK2 = 66 MHz)	Typical: 8.0 9.0 10.0	14.0 15.0 18.0	Typical 5.0 6.0 -	9.0 10.0 -	mA	Note 3 Note 3 Note 3
I _{CCSS} Standby I _{CC} 0 MHz (Suspended/CLK2 Stopped)	Typical: 0.4	2	Typical: 0.3	2	mA	Note 3
C _{IN} Input Capacitance		10		10	pF	f _c = 1 MHz (Note 4)
C _{OUT} Output or I/O Capacitance		12		12	pF	f _c = 1 MHz (Note 4)
C _{CLK} CLK2 Capacitance		20		20	pF	f _c = 1 MHz (Note 4)

- Notes: 1. PEREQ input has an internal pull-down resistor.
 2. A20M#, BUSY#, ERROR#, FLT#, FLUSH#, KEN#, and SUSP# inputs each have an internal pull-up resistor.
 3. All inputs at 0.4 or V_{CC}-0.4 (CMOS levels). All inputs held static (except CLK2 as indicated). All outputs unloaded (static I_{OUT} = 0 mA).
 4. Not 100% tested.

4.5 AC Characteristics

Tables 4-7 and 4-8 list the AC characteristics including output delays, input setup requirements, input hold requirements and output float delays. These measurements are based on the measurement points identified in Figures 4-1 and 4-2. The rising clock edge reference level V_{REFC} , and other reference levels are shown in Table 4-6 below for the Cx486SLC/e and Cx486SLC/e-V. Input or output signals must cross these levels during testing.

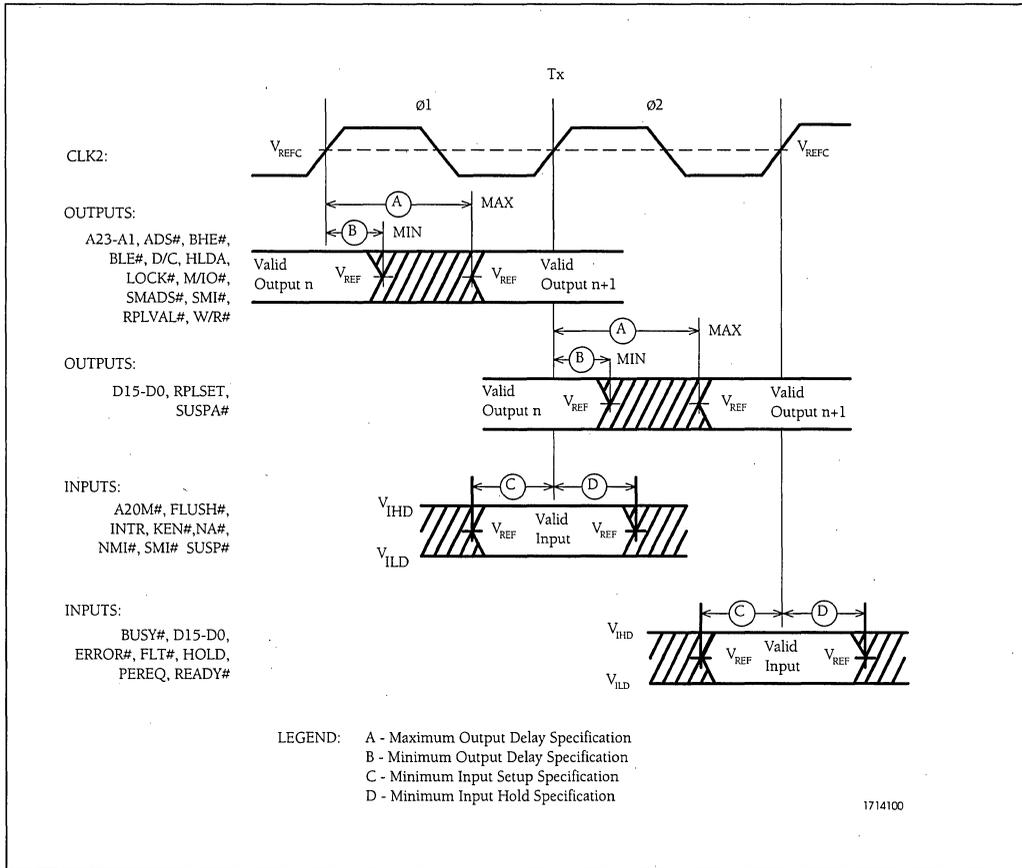
Figure 4-1 shows output delay (A and B) and input setup and hold times (C and D). Input setup and hold times (C and D) are specified minimums, defining the smallest acceptable sampling window a synchronous input signal must be stable for correct operation.

The outputs: A23-A1, ADS#, BHE#, BLE#, D/C#, HLDA, LOCK#, M/IO#, RPLVAL#, SMAD#, SMI# and W/R# change only at the beginning of phase one (Figure 4-1). D15-D0 (write cycles), RPLSET and SUSPA# change at the beginning of phase two.

The inputs: BUSY#, D15-D0 (read cycles), ERROR#, FLT#, HOLD, PEREQ, and READY# are sampled at the beginning of phase one (Figure 4-1). A20M#, FLUSH#, INTR, KEN#, NA#, NMI, SMI# and SUSP# are sampled at the beginning of phase two.

Table 4-6. Measurement Points for Switching Characteristics

SYMBOL	Cx486SLC/e	Cx486SLC/e-V	UNITS
V_{REFC}	2	1.5	V
V_{REF}	1.5	1.2	V
V_{IHC}	$V_{CC} - 0.8$	$V_{CC} - 0.5$	V
V_{ILC}	0.8	0.6	V
V_{IHD}	3	2.3	V
V_{ILD}	0	0	V



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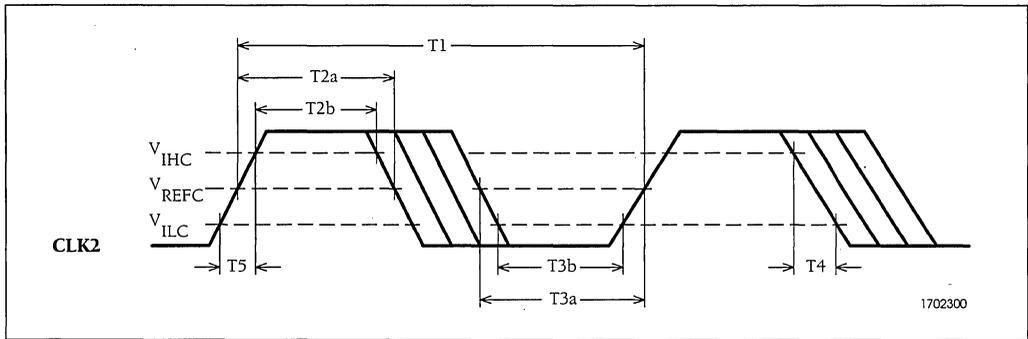


Figure 4-2. CLK2 Timing Measurement Points

Table 4-7. AC Characteristics for Cx486SLC/e-V20

 Cx486SLC/e-V20: $V_{CC} = 3.0$ to 3.6 V, $T_C = 0^\circ$ to 85° C

SYMBOL	PARAMETER	20 MHz		FIGURE	NOTES
		MIN (ns)	MAX (ns)		
T1	CLK2 Period	25		4-2	Note 1
T2a	CLK2 High Time	8		4-2	Note 2
T2b	CLK2 High Time	5		4-2	Note 2
T3a	CLK2 Low Time	8		4-2	Note 2
T3b	CLK2 Low Time	6		4-2	Note 2
T4	CLK2 Fall Time		8	4-2	Note 2
T5	CLK2 Rise Time		8	4-2	Note 2
T6	A23-A1, SMI# Valid Delay	4	30	4-4, 4-7	$C_L = 50$ pF
T7	A23-A1 Float Delay	4	32	4-7	Note 3
T8	BHE#, BLE#, LOCK# Valid Delay	4	30	4-4, 4-7	$C_L = 50$ pF
T9	BHE#, BLE#, LOCK# Float Delay	4	32	4-7	Note 3
T10	ADS#, D/C#, M/IO#, RPLVAL#, SMADS#, W/R# Valid Delay	4	26	4-4, 4-7	$C_L = 50$ pF
T11	ADS#, D/C#, M/IO#, RPLVAL#, SMADS#, W/R# Float Delay	4	30	4-7	Note 3
T12	D15-D0 Write Data, RPLSET, SUSPA# Valid Delay	4	38	4-4, 4-5	$C_L = 50$ pF, Note 5
T12a	D15-D0 Write Data Hold Time	4		4-6	
T13	D15-D0 Write Data, RPLSET, SUSPA# Float Delay	4	27	4-7	Note 3, Note 6
T14	HLDA Valid Delay	4	28	4-7	$C_L = 50$ pF
T15	NA#, SUSP#, FLUSH#, KEN#, A20M# Setup Time	5		4-3	
T16	NA#, SUSP#, FLUSH#, KEN#, A20M# Hold Time	12		4-3	
T19	READY# Setup Time	12		4-3	
T20	READY# Hold Time	4		4-3	
T21	D15-D0 Read Data Setup Time	9		4-3	
T22	D15-D0 Read Data Hold Time	6		4-3	
T23	HOLD Setup Time	17		4-3	
T24	HOLD Hold Time	5		4-3	
T25	RESET Setup Time	12		4-8	
T26	RESET Hold Time	4		4-8	
T27	INTR, NMI, SMI# Setup Time	16		4-3	Note 4
T28	INTR, NMI, SMI# Hold Time	16		4-3	Note 4
T29	PEREQ, ERROR#, BUSY# Setup Time	14		4-3	Note 4
T30	PEREQ, ERROR#, BUSY# Hold Time	5		4-3	Note 4

Note: Refer to AC Characteristics Notes on page 4-11.

Table 4-8. AC Characteristics for Cx486SLC/e-25, Cx486SLC/e-V25Cx486SLC/e-25: $V_{CC} = 5.0\text{ V} \pm 10\%$, $T_C = 0^\circ\text{ to }100^\circ\text{C}$ Cx486SLC/e-V25: $V_{CC} = 3.0\text{ to }3.6\text{ V}$, $T_C = 0^\circ\text{ to }85^\circ\text{C}$

SYMBOL	PARAMETER	25 MHz		FIGURE	NOTES
		MIN (ns)	MAX (ns)		
T1	CLK2 Period	20		4-2	Note 1
T2a	CLK2 High Time	7		4-2	Note 2
T2b	CLK2 High Time	4		4-2	Note 2
T3a	CLK2 Low Time	7		4-2	Note 2
T3b	CLK2 Low Time	5		4-2	Note 2
T4	CLK2 Fall Time		7	4-2	Note 2
T5	CLK2 Rise Time		7	4-2	Note 2
T6	A23-A1, SMI# Valid Delay	4	21	4-4, 4-7	$C_L = 50\text{ pF}$
T7	A23-A1 Float Delay	4	30	4-7	Note 3
T8	BHE#, BLE#, LOCK# Valid Delay	4	21	4-4, 4-7	$C_L = 50\text{ pF}$
T9	BHE#, BLE#, LOCK# Float Delay	4	30	4-7	Note 3
T10	ADS#, D/C#, M/IO#, SMADS# RPLVAL#, W/R# Valid Delay	4	21	4-4, 4-7	$C_L = 50\text{ pF}$
T11	ADS#, D/C#, M/IO#, SMADS# RPLVAL#, W/R# Float Delay	4	30	4-7	Note 3
T12	D15-D0 Write Data, RPLSET, SUSPA# Valid Delay	7	27	4-4, 4-5	$C_L = 50\text{ pF}$, Note 5
T12a	D15-D0 Write Data Hold Time	2		4-6	
T13	D15-D0 Write Data, RPLSET, SUSPA# Float Delay	4	22	4-7	Note 3, Note 6
T14	HLDA Valid Delay	4	22	4-7	$C_L = 50\text{ pF}$
T15	NA#, SUSP#, FLUSH#, KEN#, A20M# Setup Time	5		4-3	
T16	NA#, SUSP#, FLUSH#, KEN#, A20M# Hold Time	3		4-3	
T19	READY# Setup Time	9		4-3	
T20	READY# Hold Time	4		4-3	
T21	D15-D0 Read Data Setup Time	7		4-3	
T22	D15-D0 Read Data Hold Time	5		4-3	
T23	HOLD Setup Time	9		4-3	
T24	HOLD Hold Time	3		4-3	
T25	RESET Setup Time	8		4-8	
T26	RESET Hold Time	3		4-8	
T27	INTR, NMI, SMI# Setup Time	6		4-3	Note 4
T28	INTR, NMI, SMI# Hold Time	6		4-3	Note 4
T29	PEREQ, ERROR#, BUSY# Setup Time	6		4-3	Note 4
T30	PEREQ, ERROR#, BUSY# Hold Time	5		4-3	Note 4

Note: Refer to AC Characteristics Notes on page 4-11.



AC Characteristics

Table 4-9. AC Characteristics for Cx486SLC/e-33

Cx486SLC/e-33: $V_{CC} = 5.0 V \pm 5\%$, $T_C = 0^\circ$ to $100^\circ C$

SYMBOL	PARAMETER	33 MHz		FIGURE	NOTES
		MIN (ns)	MAX (ns)		
T1	CLK2 Period	15		4-2	Note 1
T2a	CLK2 High Time	6.25		4-2	Note 2
T2b	CLK2 High Time	4.5		4-2	Note 2
T3a	CLK2 Low Time	6.25		4-2	Note 2
T3b	CLK2 Low Time	4.5		4-2	Note 2
T4	CLK2 Fall Time		4	4-2	Note 2
T5	CLK2 Rise Time		4	4-2	Note 2
T6	A23-A1, SMI# Valid Delay	4	15	4-4, 4-7	$C_L = 50$ pF
T7	A23-A1 Float Delay	4	20	4-7	Note 3
T8	BHE#, BLE#, LOCK#, Valid Delay	4	15	4-4, 4-7	$C_L = 50$ pF
T9	BHE#, BLE#, LOCK#, Float Delay	4	20	4-7	Note 3
T10	ADS#, D/C#, M/IO#, RPLVAL#, SMADS#, W/R# Valid Delay	4	15	4-4, 4-7	$C_L = 50$ pF
T11	ADS#, D/C#, M/IO#, RPLVAL#, SMADS#, W/R# Float Delay	4	20	4-7	Note 3
T12	D15-D0 Write Data, RPLSET, SUSPA# Valid Delay	7	24	4-4, 4-5	$C_L = 50$ pF, Note 5
T12a	D15-D0 Write Data, Hold Time	2		4-6	
T13	D15-D0 Write Data, RPLSET, SUSPA# Float Delay	4	17	4-7	Note 3, Note 6
T14	HLDA Valid Delay	4	20	4-7	$C_L = 50$ pF
T15	A20#, FLUSH#, KEN#, NA#, SUSP# Setup Time	5		4-3	
T16	A20#, FLUSH#, KEN#, NA#, SUSP# Hold Time	3		4-3	
T19	READY# Setup Time	7		4-3	
T20	READY# Hold Time	4		4-3	
T21	D15-D0, Read Data Setup Time	5		4-3	
T22	D15-D0, Read Data Hold Time	3		4-3	
T23	HOLD Setup Time	11		4-3	
T24	HOLD Hold Time	2		4-3	
T25	RESET Setup Time	5		4-8	
T26	RESET Hold Time	2		4-8	
T27	NMI, INTR, SMI# Setup Time	5		4-3	Note 4
T28	NMI, INTR, SMI# Hold Time	5		4-3	Note 4
T29	PEREQ, ERROR#, BUSY# Setup Time	5		4-3	Note 4
T30	PEREQ, ERROR#, BUSY# Hold Time	4		4-3	Note 4

Note: Refer to AC Characteristics Notes on page 4-11.

AC Characteristics Notes for Tables 4-7 through 4-9:

1. Input clock can be stopped, therefore minimum CLK2 frequency is 0 MHz.
2. These parameters are not tested. They are guaranteed by design characterization.
3. Float condition occurs when maximum output current becomes less than I_{11} in magnitude. Float is not 100% tested.
4. These inputs are allowed to be asynchronous to CLK2. The setup and hold specifications are given for testing purposes, to assure recognition within a specific CLK2 period.
5. T12 minimum time is not 100% tested.
6. SUSPA# floats only in response to activation of FLT#. SUSPA# does not float during a hold acknowledge state.

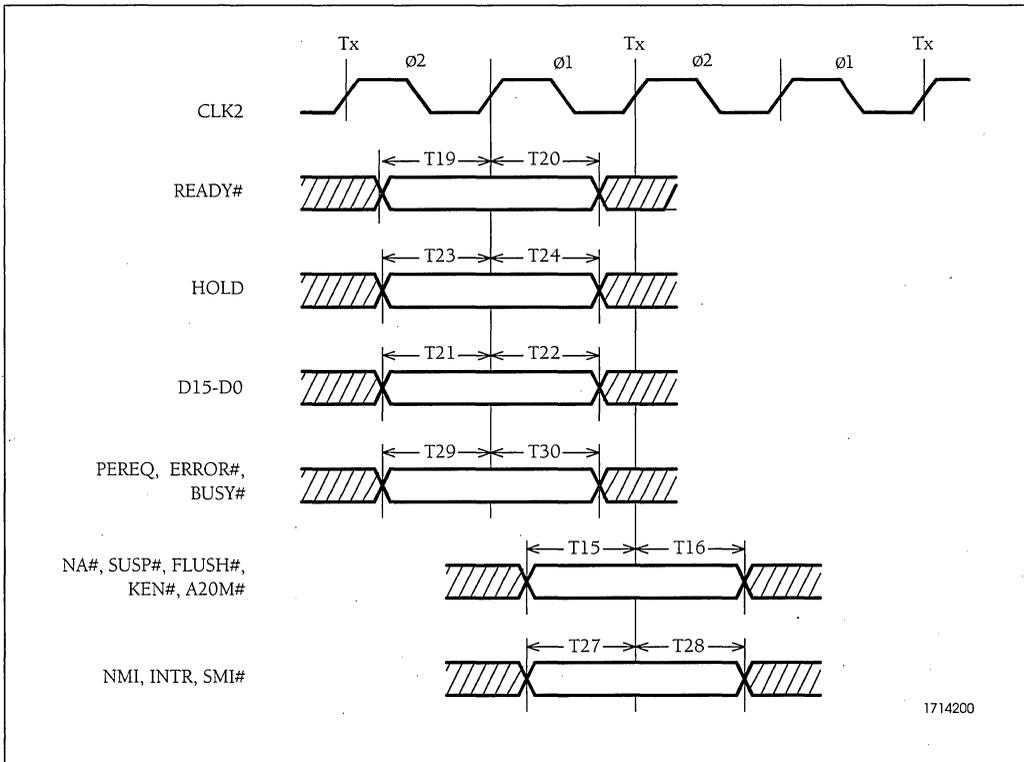


Figure 4-3. Input Signal Setup and Hold Timing

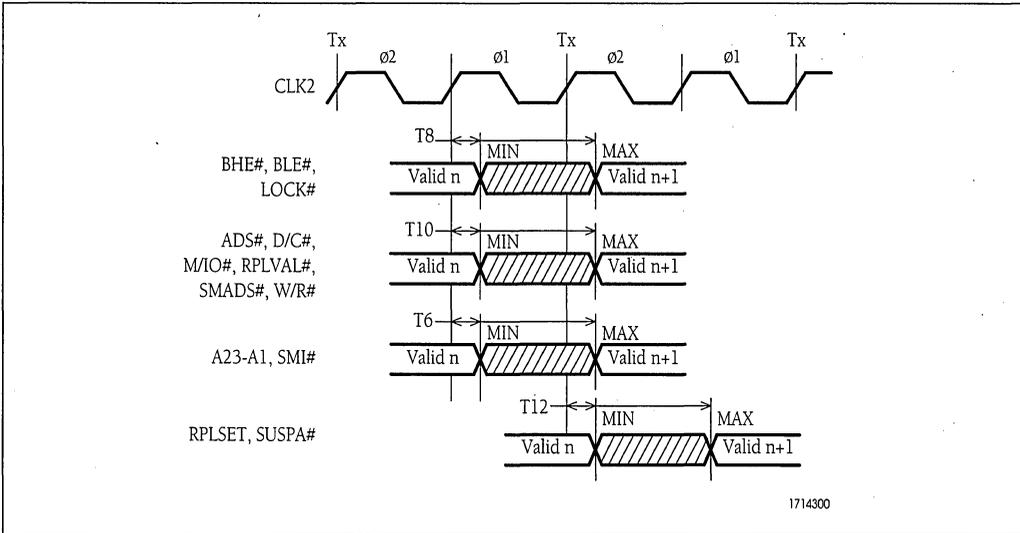


Figure 4-4. Output Signal Valid Delay Timing

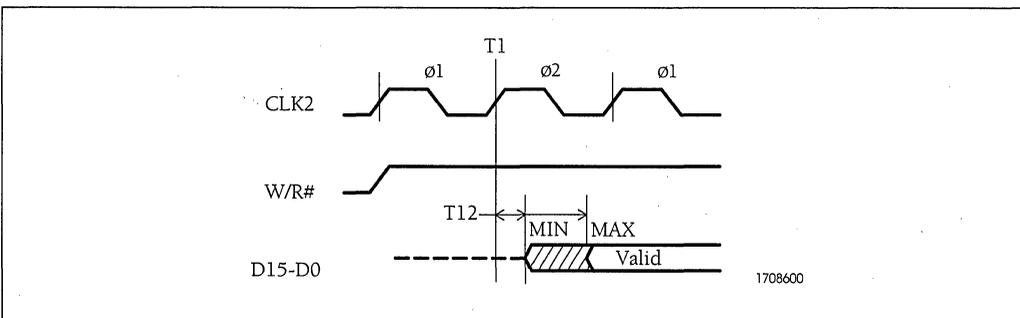


Figure 4-5. Data Write Cycle Valid Delay Timing

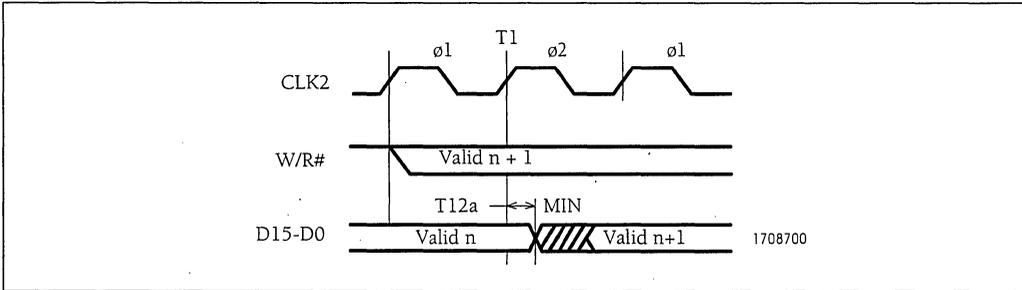


Figure 4-6. Data Write Cycle Hold Timing

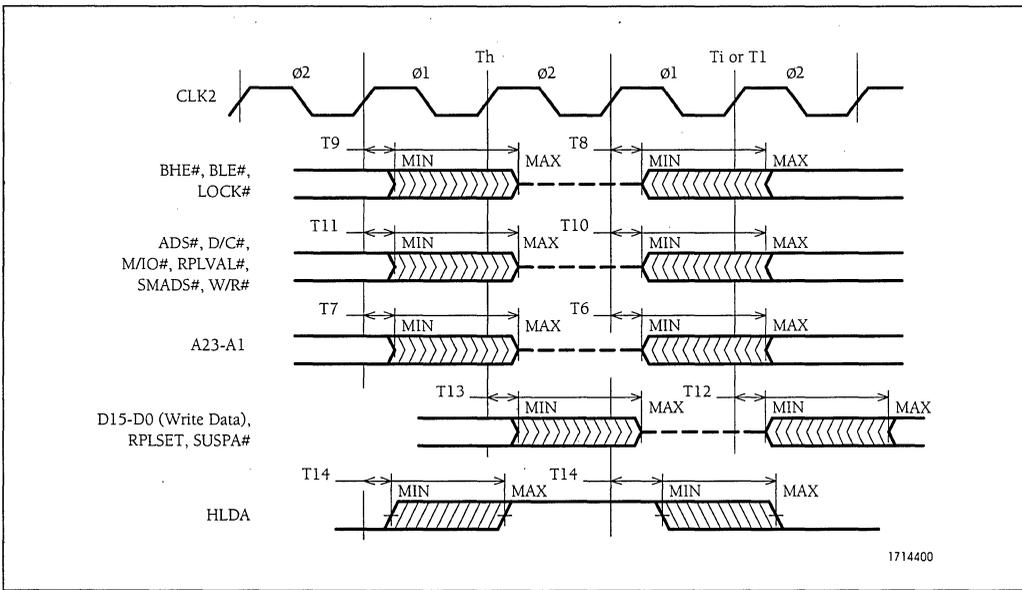


Figure 4-7. Output Signal Float Delay and HLDA Valid Delay Timing

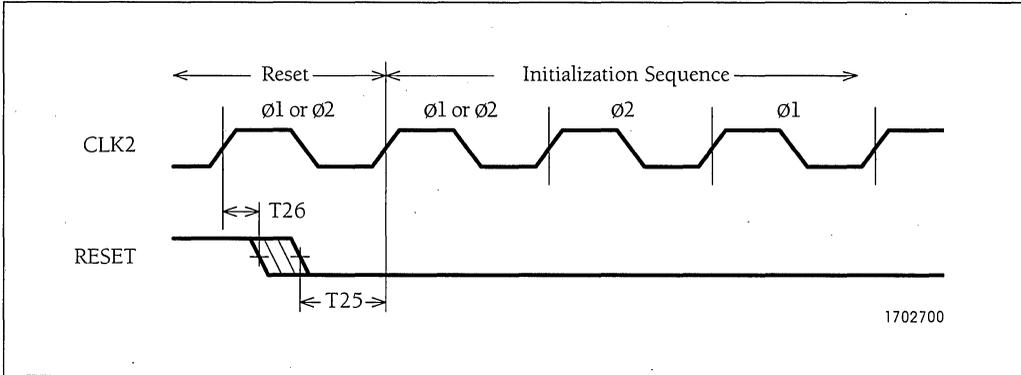
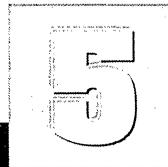


Figure 4-8. RESET Setup and Hold Timing

CYRIX Cx486SLC/e™ MICROPROCESSOR

High-Performance 486-Style CPU with Advanced Power Management for Notebook and Battery-Powered Systems



Mechanical Specifications

5. MECHANICAL SPECIFICATIONS

5.1 Pin Assignments

The pin assignments for the Cx486SLC/e are shown in Figure 5-1. The signal names are shown in Table 5-1 sorted by pin numbers and in Table 5-2 sorted by signal name.

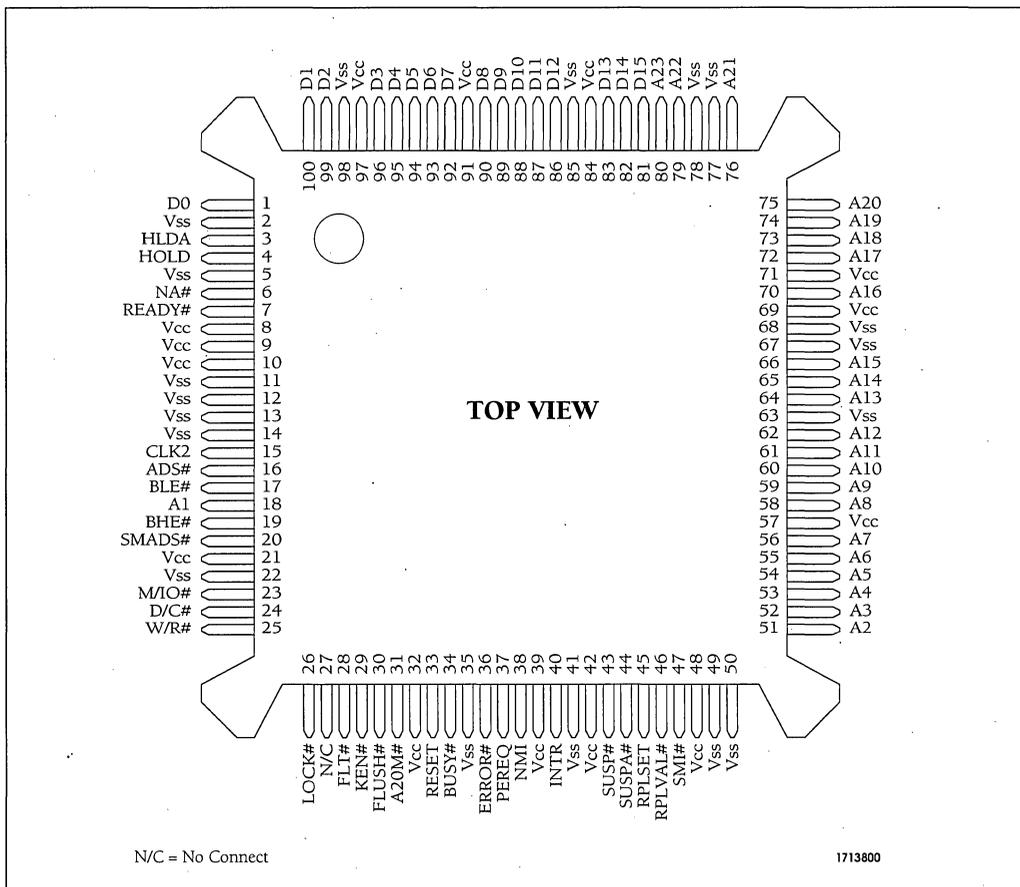


Figure 5-1. Pin Assignments

Table 5-1. Signal Names Sorted by Pin Number

PIN NO.	SIGNAL NAME								
1	D0	21	V _{CC}	41	V _{SS}	61	A11	81	D15
2	V _{SS}	22	V _{SS}	42	V _{CC}	62	A12	82	D14
3	HLDA	23	M/IO#	43	SUSP#	63	V _{SS}	83	D13
4	HOLD	24	D/C#	44	SUSPA#	64	A13	84	V _{CC}
5	V _{SS}	25	W/R#	45	RPLSET	65	A14	85	V _{SS}
6	NA#	26	LOCK#	46	RPLVAL#	66	A15	86	D12
7	READY#	27	N/C	47	SMI#	67	V _{SS}	87	D11
8	V _{CC}	28	FLT#	48	V _{CC}	68	V _{SS}	88	D10
9	V _{CC}	29	KEN#	49	V _{SS}	69	V _{CC}	89	D9
10	V _{CC}	30	FLUSH#	50	V _{SS}	70	A16	90	D8
11	V _{SS}	31	A20M#	51	A2	71	V _{CC}	91	V _{CC}
12	V _{SS}	32	V _{CC}	52	A3	72	A17	92	D7
13	V _{SS}	33	RESET	53	A4	73	A18	93	D6
14	V _{SS}	34	BUSY#	54	A5	74	A19	94	D5
15	CLK2	35	V _{SS}	55	A6	75	A20	95	D4
16	ADS#	36	ERROR#	56	A7	76	A21	96	D3
17	BLE#	37	PEREQ	57	V _{CC}	77	V _{SS}	97	V _{CC}
18	A1	38	NMI	58	A8	78	V _{SS}	98	V _{SS}
19	BHE#	39	V _{CC}	59	A9	79	A22	99	D2
20	SMADS#	40	INTR	60	A10	80	A23	100	D1

Table 5-2. Pin Numbers Sorted by Signal Name

SIGNAL NAME	PIN NO.	SIGNAL NAME	PIN NO.	SIGNAL NAME	PIN NO.	SIGNAL NAME	PIN NO.	SIGNAL NAME	PIN NO.
A1	18	A21	76	D11	87	RESET	33	V _{CC}	97
A2	51	A22	79	D12	86	RPLSET	45	V _{SS}	2
A3	52	A23	80	D13	83	RPLVAL#	46	V _{SS}	5
A4	53	ADS#	16	D14	82	SMADS#	20	V _{SS}	11
A5	54	A20M#	31	D15	81	SMI#	47	V _{SS}	12
A6	55	BHE#	19	D/C#	24	SUSP#	43	V _{SS}	13
A7	56	BLE#	17	ERROR#	36	SUSPA#	44	V _{SS}	14
A8	58	BUSY#	34	FLT#	28	V _{CC}	8	V _{SS}	22
A9	59	CLK2	15	FLUSH#	30	V _{CC}	9	V _{SS}	35
A10	60	D0	1	HOLD	4	V _{CC}	10	V _{SS}	41
A11	61	D1	100	HLDA	3	V _{CC}	21	V _{SS}	49
A12	62	D2	99	INTR	40	V _{CC}	32	V _{SS}	50
A13	64	D3	96	KEN#	29	V _{CC}	39	V _{SS}	63
A14	65	D4	95	LOCK#	26	V _{CC}	42	V _{SS}	67
A15	66	D5	94	M/IO#	23	V _{CC}	48	V _{SS}	68
A16	70	D6	93	NA#	6	V _{CC}	57	V _{SS}	77
A17	72	D7	92	N/C	27	V _{CC}	69	V _{SS}	78
A18	73	D8	90	NMI	38	V _{CC}	71	V _{SS}	85
A19	74	D9	89	PEREQ	37	V _{CC}	84	V _{SS}	98
A20	75	D10	88	READY#	7	V _{CC}	91	W/R#	25

5.2 Package Dimensions

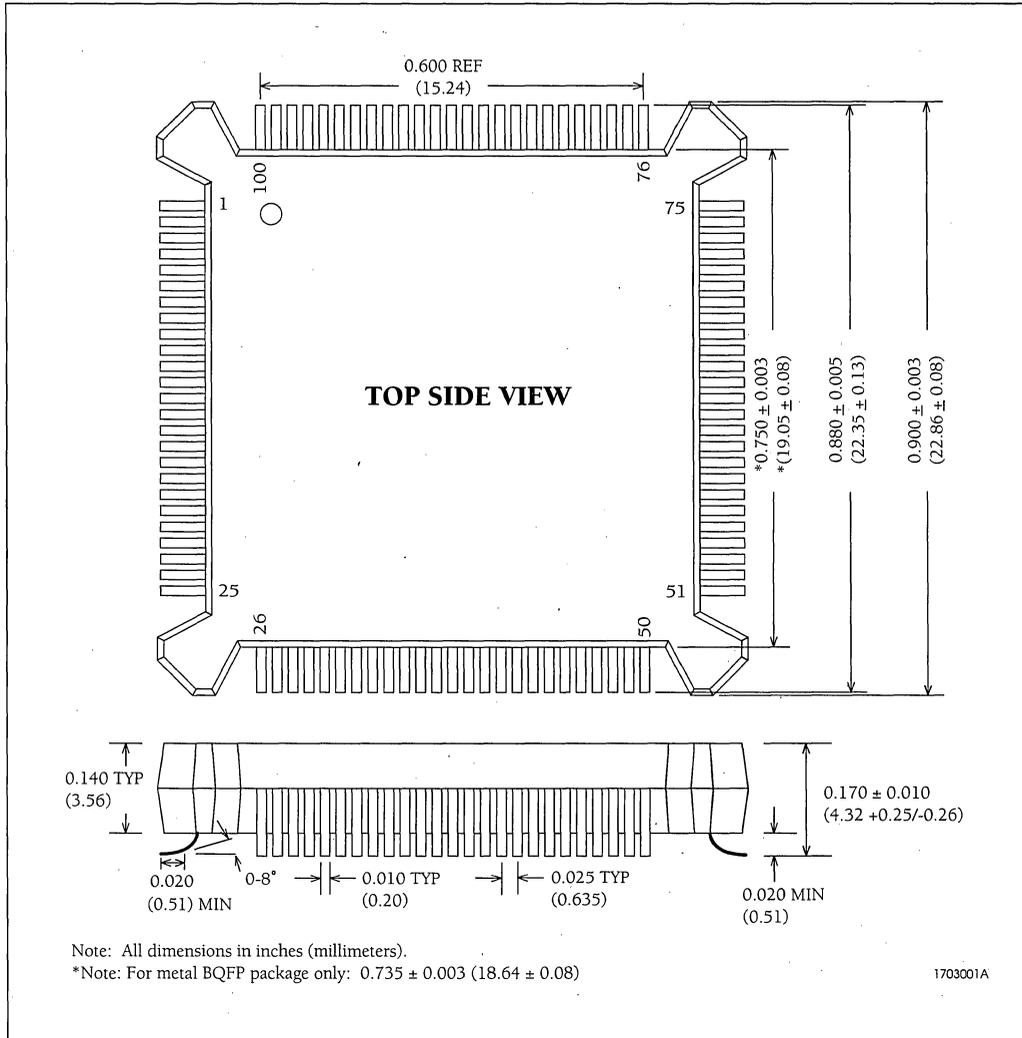


Figure 5-2. 100-Pin BQFP Package Dimensions

5.3 Thermal Characteristics

The Cx486SLC/e is designed to operate when case temperature is between 0° - 100°C and between 0° - 85° C for the Cx486SLC/e-V. The case temperature is measured on the top center of the package. The maximum die temperature ($T_{j\text{MAX}}$) and the maximum ambient temperature ($T_{a\text{MAX}}$) can be calculated using the following equations.

$$T_{j\text{MAX}} = T_c + (P_{\text{MAX}} \times \theta_{jc})$$

$$T_{a\text{MAX}} = T_j - (P_{\text{MAX}} \times \theta_{ja})$$

where:

- $T_{j\text{MAX}}$ = Maximum average junction temperature (°C)
- T_c = Case temperature at top center of package (°C)
- P_{MAX} = Maximum device power dissipation (W)
- θ_{jc} = Junction-to-case thermal resistance (°C/W)
- $T_{a\text{MAX}}$ = Maximum ambient temperature (°C)
- T_j = Average junction temperature (°C)
- θ_{ja} = Junction-to-ambient thermal resistance (°C/W)

The junction-to-ambient and junction-to-case thermal resistances of the 100-lead Bumped Quad Flat Pack (BQFP) package are listed in Table 5-3 for various airflows. Tables 5-4 and 5-5 list the maximum ambient temperatures permitted for various clock frequencies and airflows.

Table 5-3. Package Thermal Resistance and Airflow

AIRFLOW (FT/MIN)	THERMAL RESISTANCE (°C/W) 100-LEAD BQFP	
	θ_{ja}	θ_{jc}
0	21	2
100	19	2
250	16	2
500	13	2

Table 5-4. Cx486SLC/e Maximum Ambient Temperature (T_A) for Various Airflows and Clock Frequencies

f _{CLK} (MHZ)	AIRFLOW (ft/min)			
	0	100	250	500
20	67°C	71°C	76°C	79°C
25	60°C	65°C	71°C	75°C
33	50°C	56°C	63°C	69°C

Note: Table refers to temperature specifications only and does not necessarily reflect part availability.

Table 5-5. Cx486SLC/e-V Maximum Ambient Temperature (T_A) for Various Airflows and Clock Frequencies

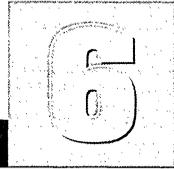
f _{CLK} (MHZ)	AIRFLOW (ft/min)			
	0	100	250	500
20	65°C	67°C	70°C	72°C
25	61°C	64°C	68°C	70°C
33	55°C	58°C	63°C	66°C

Note: Table refers to temperature specifications only and does not necessarily reflect part availability.



CYRIX Cx486SLC/e™ MICROPROCESSOR

High-Performance 486-Style CPU with Advanced Power Management for Notebook and Battery-Powered Systems



Instruction Set Summary

6. INSTRUCTION SET

This section summarizes the Cx486SLC/e instruction set and provides detailed information on the instruction encodings. All instructions are listed in the Instruction Set Summary Table (Table 6-16), which provides information on the instruction encoding, which flags are effected, and the instruction clock counts for each instruction. The clock count values are based on the assumptions described in section 6.3.

6.1 General Instruction Format

All of the Cx486SLC/e machine instructions follow the general instruction format shown in Figure 6-1. These instructions vary in length and can start at any byte address. An instruction consists of one or more bytes that can include: prefix byte(s), at least one opcode byte(s), mod r/m byte, s-i-b byte, address displacement byte(s) and immediate data byte(s). An instruction can be as short as one byte and as long as 15 bytes. If there are more than 15 bytes in the instruction a general protection fault (error code of 0) is generated.

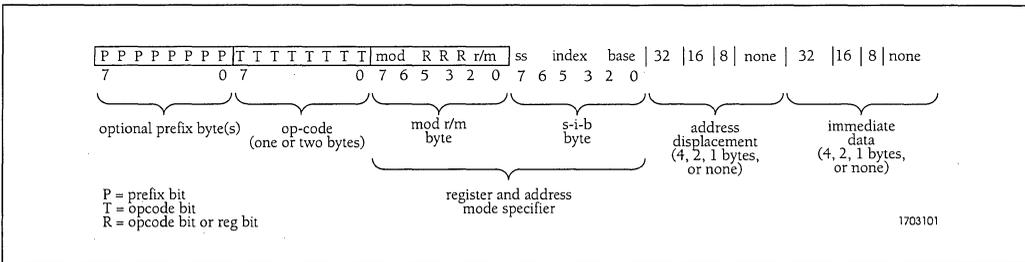


Figure 6-1. General Instruction Format

6.2 Instruction Fields

The general instruction format shows the larger fields that make up an instruction. Certain instructions have smaller encoding fields that vary according to the class of operation. These

fields define information such as the direction of the operation, the size of the displacements, register encoding and sign extension. All the fields are described in Table 6-1 and the subsequent paragraphs provide greater detail.

Table 6-1. Instruction Fields

FIELD NAME	DESCRIPTION	NUMBER OF BITS
Prefix	Specifies segment register override, address and operand size, repeat elements in string instruction, LOCK# assertion.	8 per byte
Opcode	Identifies instruction operation.	1 or 2 bytes
w	Specifies if data is byte or full size (full size is either 16 or 32 bits).	1
d	Specifies direction of data operation.	1
s	Specifies if an immediate data field must be sign-extended.	1
reg	General register specifier.	3
mod r/m	Address mode specifier.	2 for mod; 3 for r/m
ss	Scale factor for scaled index address mode.	2
index	General register to be used as index register.	3
base	General register to be used as base register.	2
sreg2	Segment register for CS, SS DS and ES.	2
sreg3	Segment register for CS, SS, DS ES FS and GS.	3
eee	Control, debug and test register specifier.	3
Address displacement	Address displacement operand.	1, 2 or 4 bytes
Immediate data	Immediate data operand.	1, 2 or 4 bytes

6.2.1 Prefixes

Prefix bytes can be placed in front of any instruction. The prefix modifies the operation of the next instruction only. When more than one prefix is used, the order is not important. There are five types of prefixes as follows:

1. Segment Override explicitly specifies which segment register an instruction will use.
2. Address Size switches between 16- and 32-bit addressing. Selects the inverse of the default.
3. Operand Size switches between 16- and 32-bit addressing. Selects the inverse of the default.
4. Repeat is used with a string instruction which causes the instruction to be repeated for each element of the string.
5. Lock is used to assert the hardware LOCK# signal during execution of the instruction.

Table 6-2 lists the encodings for each of the available prefix bytes. The operand size and address size prefixes allow the individual overriding of the default value for operand size and effective address size. The presence of these prefixes select the opposite (non-default) operand size and/or effective address size as the case may be.

Table 6-2. Instruction Prefix Summary

PREFIX	ENCODING	DESCRIPTION
ES:	26h	Override segment default, use ES for memory operand
CS:	2Eh	Override segment default, use CS for memory operand
SS:	36h	Override segment default, use SS for memory operand
DS:	3Eh	Override segment default, use DS for memory operand
FS:	64h	Override segment default, use FS for memory operand
GS:	65h	Override segment default, use GS for memory operand
Operand Size	66h	Make operand size attribute the inverse of the default
Address Size	67h	Make address size attribute the inverse of the default
LOCK	F0h	Assert LOCK# hardware signal.
REPNE	F2h	Repeat the following string instruction.
REP/REPE	F3h	Repeat the following string instruction.

6.2.2 Opcode Field

The opcode field is either one or two bytes in length and specifies the operation to be performed by the instruction. Some operations have more than one opcode, each specifying a different form of the operation. Some opcodes name instruction groups. For example, opcode 0x80 names a group of operations that have an

immediate operand, and a register or memory operand. The group opcodes use an opcode extension field of 3 bits in the following byte, called the MOD R/M byte, to resolve the operation type. Opcodes for the entire Cx486SLC/e instruction set are listed in the Instruction Set Summary Table. The opcodes are given in hex values unless shown within brackets ([]). Values shown in brackets are binary values.

6.2.3 w Field

The 1-bit w field indicates the operand size during 16- and 32-bit data operations.

Table 6-3. w Field Encoding

w FIELD	OPERAND SIZE 16-BIT DATA OPERATIONS	OPERAND SIZE 32-BIT DATA OPERATIONS
0	8 Bits	8 Bits
1	16 Bits	32 Bits

6.2.4 d Field

The d field determines which operand is taken as the source operand and which operand is taken as the destination.

Table 6-4. d Field Encoding

d FIELD	DIRECTION OF OPERATION	SOURCE OPERAND	DESTINATION OPERAND
0	Register --> Register/Memory Register/Memory --> Register	reg	mod r/m or mod ss-index-base
1		mod r/m or mod ss-index-base	reg

6.2.5 reg Field

The reg field determines which general registers are to be used. The selected register is dependent on whether 16- or 32-bit operation is current and the status of the "w" bit.

Table 6-5. reg Field Encoding

reg	16-BIT OPERATION w Field Not Present	32-BIT OPERATION w Field Not Present	16-BIT OPERATION w=0	16-BIT OPERATION w=1	32-BIT OPERATION w=0	32-BIT OPERATION w=1
000	AX	EAX	AL	AX	AL	EAX
001	CX	ECX	CL	CX	CL	ECX
010	DX	EDX	DL	DX	DL	EDX
011	BX	EBX	BL	BX	BL	EBX
100	SP	ESP	AH	SP	AH	ESP
101	BP	EBP	CH	BP	CH	EBP
110	SI	ESI	DH	SI	DH	ESI
111	DI	EDI	BH	DI	BH	EDI

6.2.6 mod and r/m Fields

The mod and r/m sub-fields, within the mod r/m byte, select the type of memory addressing to be used. Some instructions use a fixed addressing mode (e.g., PUSH or POP) and

therefore, these fields are not present.

Table 6-6 lists the addressing method when 16-bit addressing is used and a mod r/m byte is present. Some mod r/m field encodings are dependent on the w field and are shown in Table 6-6A.

Table 6-6. mod r/m Field Encoding

mod r/m	16-BIT ADDRESS MODE with mod r/m Byte	32-BIT ADDRESS MODE with mod r/m Byte and No s-i-b Byte Present
00 000	DS:[BX+SI]	DS:[EAX]
00 001	DS:[BX+DI]	DS:[ECX]
00 010	SS:[BP+SI]	DS:[EDX]
00 011	SS:[BP+DI]	DS:[EBX]
00 100	DS:[SI]	s-i-b is present (See 6.2.7)
00 101	DS:[DI]	DS:[d32]
00 110	DS:[d16]	DS:[ESI]
00 111	DS:[BX]	DS:[EDI]
01 000	DS:[BX+SI+d8]	DS:[EAX+d8]
01 001	DS:[BX+DI+d8]	DS:[ECX+d8]
01 010	SS:[BP+SI+d8]	DS:[EDX+d8]
01 011	SS:[BP+DI+d8]	DS:[EBX+d8]
01 100	DS:[SI+d8]	s-i-b is present (See 6.2.7)
01 101	DS:[DI+d8]	SS:[EBP+d8]
01 110	SS:[BP+d8]	DS:[ESI+d8]
01 111	DS:[BX+d8]	DS:[EDI+d8]
10 000	DS:[BX+SI+d16]	DS:[EAX+d32]
10 001	DS:[BX+DI+d16]	DS:[ECX+d32]
10 010	SS:[BP+SI+d16]	DS:[EDX+d32]
10 011	SS:[BP+DI+d16]	DS:[EBX+d32]
10 100	DS:[SI+d16]	s-i-b is present (See 6.2.7)
10 101	DS:[DI+d16]	SS:[EBP+d32]
10 110	SS:[BP+d16]	DS:[ESI+d32]
10 111	DS:[BX+d16]	DS:[EDI+d32]
11 000-11 111	See Table 6-6A	See Table 6-6A

Table 6-6A. mod r/m Field Encoding Dependent on w Field

mod r/m	16-BIT OPERATION w=0	16-BIT OPERATION w=1	32-BIT OPERATION w=0	32-BIT OPERATION w=1
11 000	AL	AX	AL	EAX
11 001	CL	CX	CL	ECX
11 010	DL	DX	DL	EDX
11 011	BL	BX	BL	EBX
11 100	AH	SP	AH	ESP
11 101	CH	BP	CH	EBP
11 110	DH	SI	DH	ESI
11 111	BH	DI	BH	EDI

6.2.7 mod and base Fields

In Table 6-6A, the note "s-i-b present" for certain entries forces the use of the mod and base field as listed in Table 6-7.

Table 6-7. mod base Field Encoding

mod base	32-BIT ADDRESS MODE with mod r/m and s-i-b Bytes Present
00 000	DS:[EAX+(scaled index)]
00 001	DS:[ECX+(scaled index)]
00 010	DS:[EDX+(scaled index)]
00 011	DS:[EBX+(scaled index)]
00 100	SS:[ESP+(scaled index)]
00 101	DS:[d32+(scaled index)]
00 110	DS:[ESI+(scaled index)]
00 111	DS:[EDI+(scaled index)]
01 000	DS:[EAX+(scaled index)+d8]
01 001	DS:[ECX+(scaled index)+d8]
01 010	DS:[EDX+(scaled index)+d8]
01 011	DS:[EBX+(scaled index)+d8]
01 100	SS:[ESP+(scaled index)+d8]
01 101	SS:[EBP+(scaled index)+d8]
01 110	DS:[ESI+(scaled index)+d8]
01 111	DS:[EDI+(scaled index)+d8]
10 000	DS:[EAX+(scaled index)+d32]
10 001	DS:[ECX+(scaled index)+d32]
10 010	DS:[EDX+(scaled index)+d32]
10 011	DS:[EBX+(scaled index)+d32]
10 100	SS:[ESP+(scaled index)+d32]
10 101	SS:[EBP+(scaled index)+d32]
10 110	DS:[ESI+(scaled index)+d32]
10 111	DS:[EDI+(scaled index)+d32]

6.2.8 ss Field

The ss field (Table 6-8) specifies the scale factor used in the offset mechanism for address calculation. The scale factor multiplies the index value to provide one of the components used to calculate the offset address.

Table 6-8. ss Field Encoding

ss FIELD	SCALE FACTOR
00	x1
01	x2
10	x4
11	x8

6.2.9 index Field

The index field (Table 6-9) specifies the index register used by the offset mechanism for offset address calculation. When no index register is used (index field = 100), the ss value must be 00 or the effective address is undefined.

Table 6-9. index Field Encoding

index FIELD	INDEX REGISTER
000	EAX
001	ECX
010	EDX
011	EBX
100	none
101	EBP
110	ESI
111	EDI

6.2.10 sreg2 Field

The sreg2 field (Table 6-10) is a 2-bit field that allows one of the four 286-type segment registers to be specified.

Table 6-10. sreg2 Field Encoding

sreg2 FIELD	SEGMENT REGISTER SELECTED
00	ES
01	CS
10	SS
11	DS

6.2.11 sreg3 Field

The sreg3 field (Table 6-11) is 3-bit field that is similar to the sreg2 field, but allows use of the FS and GS segment registers.

Table 6-11. sreg3 Field Encoding

sreg3 FIELD	SEGMENT REGISTER SELECTED
000	ES
001	CS
010	SS
011	DS
100	FS
101	GS
110	undefined
111	undefined

6.2.12 eee Field

The eee field is used to select the control, debug and test registers as indicated in Table 6-12. The values shown in Table 6-12 are the only valid encodings for the eee bits.

Table 6-12. eee Field Encoding

eee FIELD	REGISTER TYPE	BASE REGISTER
000	Control Register	CR0
010	Control Register	CR2
011	Control Register	CR3
000	Debug Register	DR0
001	Debug Register	DR1
010	Debug Register	DR2
011	Debug Register	DR3
110	Debug Register	DR6
111	Debug Register	DR7
011	Test Register	TR3
100	Test Register	TR4
101	Test Register	TR5
110	Test Register	TR6
111	Test Register	TR7

6.3 Flags

The Instruction Set Summary Table lists nine flags that are affected by the execution of instructions. The conventions shown in Table 6-13 are used to identify the different flags. Table 6-14 lists the conventions used to indicate what action the instruction has on the particular flag.

Table 6-13. Flag Abbreviations

ABBREVIATION	NAME OF FLAG
OF	Overflow Flag
DF	Direction Flag
IF	Interrupt Enable Flag
TF	Trap Flag
SF	Sign Flag
ZF	Zero Flag
AF	Auxiliary Flag
PF	Parity Flag
CF	Carry Flag

Table 6-14. Action of Instruction on Flag

INSTRUCTION TABLE SYMBOL	ACTION
x	Flag is modified by the instruction.
-	Flag is not changed by the instruction.
0	Flag is reset to "0".
1	Flag is set to "1".

6.4 Clock Counts

6.4.1 Assumptions

The following assumptions have been made in presenting the clock count values for the individual instructions:

1. The instruction has been prefetched, decoded and is ready for execution.
2. Bus cycles do not require wait states.
3. There are no local bus HOLD requests delaying processor access to the bus.
4. No exceptions are detected during instruction execution.
5. If an effective address is calculated, it does not use two general register components. One register, scaling and displacement can be used within the clock count shown. However, if the effective address calculation uses two general register components, add 1 clock to the clock count shown.
6. All clock counts assume aligned 16-bit memory/IO operands for cache miss counts.
7. If instructions access a misaligned 16-bit operand or a 32-bit operand on even address, add 2 clocks for read or write and add 4 clock counts for read and write.
8. If instructions access a 32-bit operand on odd addresses, add 4 clocks for read or write and add 8 clocks for read and write.

6.4.2 Abbreviations

The clock counts listed in the Instruction Set Summary Table are grouped by operating mode and whether there is a register/cache hit or a cache miss. In some cases, more than one clock count is shown in a column for a given instruction, or a variable is used in the clock count. The abbreviations used for these conditions are listed in Table 6-15.

Table 6-15. Clock Count Abbreviations

CLOCK COUNT SYMBOL	EXPLANATION
/	Register operand/memory operand.
n	Number of times operation is repeated.
L	Level of the stack frame.
	Conditional jump taken Conditional jump not taken. (e.g. "4 1" = 4 clocks if jump taken, 1 clock if jump not taken)
\	CPL ≤ IOPL \ CPL > IOPL (where CPL = Current Privilege Level, IOPL = I/O Privilege Level)

Table 6-16. Instruction Set Summary

INSTRUCTION	OPCODE	FLAGS OF DF IF TF SF ZF AF PF CF	REAL MODE CLOCK COUNT		PROTECTED MODE CLOCK COUNT		NOTES	
			Reg/ Cache Hit	Cache Miss	Reg/ Cache Hit	Cache Miss	Real Mode	Protected Mode
AAA ASCII Adjust AL after Add	37	- - - - - x - x	4		4			
AAD ASCII Adjust AX before Divide	D5 0A	- - - - x x - x -	4		4			
AAM ASCII Adjust AX after Multiply	D4 0A	- - - - x x - x -	16		16			
AAS ASCII Adjust AL after Subtract	3F	- - - - - x - x	4		4			
ADC Add with Carry Register to Register Register to Memory Memory to Register Immediate to Register/Memory Immediate to Accumulator	1 [00dw] [11 reg r/m] 1 [000w] [mod reg r/m] 1 [001w] [mod reg r/m] 8 [00sw] [mod 010 r/m]# 1 [010w]#	x - - - - x x x x x	1 3 3 1/3 1	 5 5 5	1 3 3 1/3 1	 5 5 5		b h
ADD Integer Add Register to Register Register to Memory Memory to Register Immediate to Register/Memory Immediate to Accumulator	0 [00dw] [11 reg r/m] 0 [000w] [mod reg r/m] 0 [001w] [mod reg r/m] 8 [00sw] [mod 000 r/m]# 0 [010w]#	x - - - - x x x x x	1 3 3 1/3 1	 5 5 5	1 3 3 1/3 1	 5 5 5		b h
AND Boolean AND Register to Register Register to Memory Memory to Register Immediate to Register/Memory Immediate to Accumulator	2 [00dw] [11 reg r/m] 2 [000w] [mod reg r/m] 2 [001w] [mod reg r/m] 8 [00sw] [mod 100 r/m]# 2 [010w]#	0 - - - - x x - x 0	1 3 3 1/3 1	 5 5 5	1 3 3 1/3 1	 5 5 5		b h
ARPL Adjust Requested Privilege Level From Register/Memory	63 [mod reg r/m]	- - - - - x - - -			6/10	10		a h

= immediate data ++ = 16-bit displacement x = modified
+ = 8-bit displacement +++ = 32-bit displacement (full) - = unchanged

INSTRUCTION	OPCODE	FLAGS	REAL MODE CLOCK COUNT		PROTECTED MODE CLOCK COUNT		NOTES	
		OF DF IF TF SF ZF AF PF CF	Reg/Cache Hit	Cache Miss	Reg/Cache Hit	Cache Miss	Real Mode	Protected Mode
BOUND <i>Check Array Boundaries</i> If Out of Range (Int 5) If In Range	62 [mod reg r/m]	- - - - -	11+int 11		11+int 11		b,e	g,h,j,k,r
BSF <i>Scan Bit Forward</i> Register/Memory, Register	0F BC [mod reg r/m]	- - - - - x - - -	5/7+n	9+n	5/7+n	9+n	b	h
BSR <i>Scan Bit Reverse</i> Register/Memory, Register	0F BC [mod reg r/m]	- - - - - x - - -	5/7+n	9+n	5/7+n	9+n	b	h
BSWAP <i>Byte Swap</i>	0F C [1 reg]	- - - - -	4		4			
BT <i>Test Bit</i> Register/Memory, Immediate Register/Memory, Register	0F BA [mod 100 r/m]# 0F A3 [mod reg r/m]	- - - - - - - - x	3/4 3/6	5 7	3/4 3/6	5 7	b	h
BTC <i>Test Bit and Complement</i> Register/Memory, Immediate Register/Memory, Register	0F BA [mod 111 r/m]# 0F BB [mod reg r/m]	- - - - - - - - x	4/5 5/8	6 9	4/5 5/8	6 9	b	h
BTR <i>Test Bit and Reset</i> Register/Memory, Immediate Register/Memory, Register	0F BA [mod 110 r/m]# 0F B3 [mod reg r/m]	- - - - - - - - x	4/5 5/8	6 9	4/5 5/8	6 9	b	h
BTS <i>Test Bit and Set</i> Register/Memory Register (short form)	0F BA [mod 101 r/m] 0F AB [mod reg r/m]	- - - - - - - - x	3/5 4/7	6 8	3/5 4/7	6 8	b	h

= immediate data ++ = 16-bit displacement x = modified
+ = 8-bit displacement +++ = 32-bit displacement (full) - = unchanged

INSTRUCTION	OPCODE	FLAGS	REAL MODE CLOCK COUNT		PROTECTED MODE CLOCK COUNT		NOTES	
			OF DF IF TF SF ZF AF PF CF	Reg/Cache Hit	Cache Miss	Reg/Cache Hit	Cache Miss	Real Mode
CMC <i>Complement the Carry Flag</i>	F5	- - - - - - - x		1		1		
CMP <i>Compare Integers</i> Register to Register Register to Memory Memory to Register Immediate to Register/Memory Immediate to Accumulator	3 [10dw] [11 reg r/m] 3 [101w] [mod reg r/m] 3 [100w] [mod reg r/m] 8 [00sw] [mod 111 r/m]# 3 [110w] #	x - - - - x x x x x		1 3 3 1/3 1		1 3 3 1/3 1		b h
CMPS <i>Compare String</i>	A [011w]	x - - - - x x x x x		7	8	7	8	b h
CMPXCHG <i>Compare and Exchange</i> Register1, Register2 Memory, Register	0F B [000w] [11 reg2 reg1] 0F B [000w] [mod reg r/m]	x - - - - x x x x x		5 7		5 7	8	
CWD <i>Convert Word to Doubleword</i>	99	- - - - - - - - -		1		1		
CWDE <i>Convert Word to Doubleword Extended</i>	98	- - - - - - - - -		3		3		
DAA <i>Decimal Adjust AL after Add</i>	27	- - - - - x x x x x		4		4		
DAS <i>Decimal Adjust AL after Subtract</i>	2F	- - - - - x x x x x		4		4		
DEC <i>Decrement by 1</i> Register/Memory Register (short form)	F [111w] [mod 001 r/m] 4 [1 reg]	x - - - - x x x x -		1/3 1	5	1/3 1	5	b h
DIV <i>Unsigned Divide</i> Accumulator by Register/Memory Divisor: Byte Word Doubleword	F [011w] [mod 110 r/m]	- - - - - - - - -		14/15 22/23 38/39	17 24 40	14/15 22/23 38/39	17 24 40	b,e e,h

= immediate data ++ = 16-bit displacement x = modified
+ = 8-bit displacement +++ = 32-bit displacement (full) - = unchanged



INSTRUCTION	OPCODE	FLAGS	REAL MODE CLOCK COUNT		PROTECTED MODE CLOCK COUNT		NOTES	
			OF DF IF TF SF ZF AF PF CF	Reg/ Cache Hit	Cache Miss	Reg/ Cache Hit	Cache Miss	Real Mode
ENTER <i>Enter New Stack Frame</i> Level = 0 Level = 1 Level (L) > 1	C8 ++ [8-bit Level]	- - - - -	7 10 6+4*L	Cache Miss	7 10 6+4*L	Cache Miss	b	h
HLT <i>Halt</i>	F4	- - - - -	3		3			1
IDIV <i>Integer (Signed) Divide</i> Accumulator by Register/Memory Divisor: Byte Word Doubleword	F [011w] [mod 111 r/m]	- - - - -	19/20 27/28 43/44	22 29 47	19/20 27/28 43/44	22 29 47	b,e	e,h
IMUL <i>Integer (Signed) Multiply</i> Accumulator by Register/Memory Multiplier: Byte Word Doubleword Register with Register/Memory Multiplier: Byte Word Doubleword Register/Memory with Immediate to Register2 Multiplier: Byte Word Doubleword	F [011w] [mod 101 r/m] OF AF. [mod reg r/m] 6 [10s1] [mod reg r/m] #	x - - - - - x	3/5 3/5 7/9 3/5 3/5 7/9 3/5 3/5 7/9	7 7 13 7 7 13 7 7 13	3/5 3/5 7/9 3/5 3/5 7/9 3/5 3/5 7/9	7 7 13 7 7 13 7 7 13	b	h
IN <i>Input from I/O Port</i> Fixed Port Variable Port	E [010w] [port number] E [110w]	- - - - -	16 16	16 16	6/19 6/19	6/20 6/20		m
INC <i>Increment by 1</i> Register/Memory Register (short form)	F [111w] [mod 000 r/m] 4 [0 reg]	x - - - - x x x x -	1/3 1	5 1	1/3 1	5 1	b	h

= immediate data ++ = 16-bit displacement x = modified
+ = 8-bit displacement +++ = 32-bit displacement (full) - = unchanged



INSTRUCTION	OPCODE	FLAGS	REAL MODE CLOCK COUNT		PROTECTED MODE CLOCK COUNT		NOTES	
			OF DF IF TF SF ZF AF PF CF	Reg/ Cache Hit	Cache Miss	Reg/ Cache Hit	Cache Miss	Real Mode
INT Software Interrupt (Continued) INTO If OF==0 If OF==1 (INT 4) Protected Mode: Interrupt or Trap to Same Privilege Interrupt or Trap to Different Privilege 16-bit Task to 16-bit TSS by Task Gate 16-bit Task to 32-bit TSS by Task Gate 16-bit Task to V86 by Task Gate 32-bit Task to 16-bit TSS by Task Gate 32-bit Task to 32-bit TSS by Task Gate 32-bit Task to V86 by Task Gate V86 to 16-bit TSS by Task Gate V86 to 32-bit TSS by Task Gate V86 to Privilege 0 by Trap Gate/Int Gate	CE	- - x 0 - - - - -	1 15	1 17	1 57 91 265 296 177 241 299 180 241 299 106	1 58 92 266 320 205 261 343 232 261 343 114	b,e	g,j,k,r
INVD Invalidate Cache	OF 08	- - - - -	4		4			
INVLPG Invalidate TLB Entry	OF 01 [mod 111 r/m]	- - - - -	4		4			
IRET Interrupt Return Real Mode Protected Mode: Within Task to Same Privilege Within Task to Different Privilege 16-bit Task to 16-bit Task 16-bit Task to 32-bit TSS 16-bit Task to V86 Task 32-bit Task to 16-bit TSS 32-bit Task to 32-bit TSS 32-bit Task to V86 Task	CF	x x x x x x x x x	14	14	35 74 259 290 173 235 295 176	37 78 260 314 203 255 339 226		g,h,j,k,r

= immediate data ++ = 16-bit displacement x = modified
+ = 8-bit displacement +++ = 32-bit displacement (full) - = unchanged

INSTRUCTION	OPCODE	FLAGS	REAL MODE CLOCK COUNT		PROTECTED MODE CLOCK COUNT		NOTES	
		OF DF IF TF SF ZF AF PF CF	Reg/ Cache Hit	Cache Miss	Reg/ Cache Hit	Cache Miss	Real Mode	Protected Mode
JB/JNAE/JC <i>Jump on Below/Not Above or Equal/Carry</i> 8-bit Displacement Full Displacement	72 + 0F 82 +++	- - - - -	4 1 4 1		6 1 6 1			r
JBE/JNA <i>Jump on Below or Equal/Not Above</i> 8-bit Displacement Full Displacement	76 + 0F 86 +++	- - - - -	4 1 4 1		6 1 6 1			r
JCXZ <i>Jump on CX Zero</i>	E3 +	- - - - -	7 3		7 3			r
JE/JZ <i>Jump on Equal/Zero</i> 8-bit Displacement Full Displacement	74 + 0F 84 +++	- - - - -	4 1 4 1		6 1 6 1			r
JECXZ <i>Jump on ECX Zero</i>	E3 +	- - - - -	7 3		7 3			r
JL/JNGE <i>Jump on Less/Not Greater or Equal</i> 8-bit Displacement Full Displacement	7C + 0F 8C +++	- - - - -	4 1 4 1		6 1 6 1			r
JLE/JNG <i>Jump on Less or Equal/Not Greater</i> 8-bit Displacement Full Displacement	7E + 0F 8E +++	- - - - -	4 1 4 1		6 1 6 1			r

= immediate data ++ = 16-bit displacement x = modified
 + = 8-bit displacement +++ = 32-bit displacement (full) - = unchanged

INSTRUCTION	OPCODE	FLAGS	REAL MODE CLOCK COUNT		PROTECTED MODE CLOCK COUNT		NOTES	
			OF DF IF TF SF ZF AF PF CF	Reg/ Cache Hit	Cache Miss	Reg/ Cache Hit	Cache Miss	Real Mode
JNLE/JG <i>Jump on Not Less or Equal/Greater</i> 8-bit Displacement Full Displacement	7F + 0F 8F +++	- - - - -	4 1 4 1		6 1 6 1			r
JNO <i>Jump on Not Overflow</i> 8-bit Displacement Full Displacement	71 + 0F 81 +++	- - - - -	4 1 4 1		6 1 6 1			r
JNP/JPO <i>Jump on Not Parity/Parity Odd</i> 8-bit Displacement Full Displacement	7B + 0F 8B +++	- - - - -	4 1 4 1		6 1 6 1			r
JNS <i>Jump on Not Sign</i> 8-bit Displacement Full Displacement	79 + 0F 89 +++	- - - - -	4 1 4 1		6 1 6 1			r
JO <i>Jump on Overflow</i> 8-bit Displacement Full Displacement	70 + 0F 80 +++	- - - - -	4 1 4 1		6 1 6 1			r
JP/JPE <i>Jump on Parity/Parity Even</i> 8-bit Displacement Full Displacement	7A + 0F 8A +++	- - - - -	4 1 4 1		6 1 6 1			r
JS <i>Jump on Sign</i> 8-bit Displacement Full Displacement	78 + 0F 88 +++	- - - - -	4 1 4 1		6 1 6 1			r
LAHF <i>Load AH with Flags</i>	9F	- - - - -	2		2			
LAR <i>Load Access Rights</i> From Register/Memory	0F 02 [mod reg r/m]	- - - - - x - - -			11/12	14	a	g,h,j,p

= immediate data ++ = 16-bit displacement x = modified
+ = 8-bit displacement +++ = 32-bit displacement (full) - = unchanged

INSTRUCTION	OPCODE	FLAGS OF DF IF TF SF ZF AF PF CF	REAL MODE CLOCK COUNT		PROTECTED MODE CLOCK COUNT		NOTES	
			Reg/ Cache Hit	Cache Miss	Reg/ Cache Hit	Cache Miss	Real Mode	Protected Mode
LDS Load Pointer to DS	C5 [mod reg r/m]	- - - - -	6	7	23	24	b	h,i,j
LEA Load Effective Address No Index Register With Index Register	8D [mod reg r/m]	- - - - -	2 3		2 3			
LEAVE Leave Current Stack Frame	C9	- - - - -	3	4	3	4	b	h
LES Load Pointer to ES	C4 [mod reg r/m]	- - - - -	6	7	23	24	b	h,i,j
LFS Load Pointer to FS	0F B4 [mod reg r/m]	- - - - -	6	7	23	24	b	h,i,j
LGDT Load GDT Register	0F 01 [mod 010 r/m]	- - - - -	9	9	9	9	b,c	h,l
LGS Load Pointer to GS	0F B5 [mod reg r/m]	- - - - -	6	7	23	24	b	h,i,j
LIDT Load IDT Register	0F 01 [mod 011 r/m]	- - - - -	9	9	9	9	b,c	h,l
LLDT Load LDT Register From Register/Memory	0F 00 [mod 010 r/m]	- - - - -			16/17	18	a	g,h,j,l
LMSW Load Machine Status Word From Register/Memory	0F 01 [mod 110 r/m]	- - - - -	5	8	5	8	b,c	h,l
LODS Load String	A [110w]	- - - - -	4	4	4	4	b	h
LOOP Offset Loop/No Loop	E2 +	- - - - -	7 4		9 3			r
LOOPNZ/LOOPNE Offset	E0 +	- - - - -	7 4		9 3			r

= immediate data ++ = 16-bit displacement x = modified
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INSTRUCTION	OPCODE	FLAGS	REAL MODE CLOCK COUNT		PROTECTED MODE CLOCK COUNT		NOTES	
			OF DF IF TF SF ZF AF PF CF	Reg/Cache Hit	Cache Miss	Reg/Cache Hit	Cache Miss	Real Mode
LOOPZ/LOOPE <i>Offset</i>	E1 +	- - - - -	7	14	9	3		r
LSL <i>Load Segment Limit</i> From Register/Memory	0F 03 [mod reg r/m]	- - - - - x - - - -			22/23	25	a	g,h,j,p
LSS <i>Load Pointer to SS</i>	0F B2 [mod reg r/m]	- - - - -	6	7	23	24	a	h,i,j
LTR <i>Load Task Register</i> From Register/Memory	0F 00 [mod reg r/m]	- - - - -			16/17	18	a	g,h,j,l
MOV <i>Move Data</i> Register to Register/Memory Register/Memory to Register Immediate to Register/Memory Immediate to Register (short form) Memory to Accumulator (short form) Accumulator to Memory (short form) Register/Memory to Segment Register Segment Register to Register/Memory	8 [100w] [mod reg r/m] 8 [101w] [mod reg r/m] C [011w] [mod 000 r/m] # B [w reg] # A [000w] +++ A [001w] +++ 8E [mod sreg3 r/m] 8C [mod reg r/m]	- - - - -	1/2 1/2 1/2 1 2 1/2 2/3 1/2	2 4 2 1 4 2 5 2	1/2 1/2 1/2 1 2 1/2 15/16 1/2	2 4 2 1 4 2 18 2	b	h,i,j
MOV <i>Move to/from Control/Debug/Test Regs</i> Register to CR0/CR2/CR3 CR0/CR2/CR3 to Register Register to DR0-DR3 DR0-DR3 to Register Register to DR6-DR7 DR6-DR7 to Register Register to TR3-5 TR3-5 to Register Register to TR6-TR7 TR6-TR7 to Register	0F 22 [11 eee reg] 0F 20 [11 eee reg] 0F 23 [11 eee reg] 0F 21 [11 eee reg] 0F 23 [11 eee reg] 0F 21 [11 eee reg] 0F 26 [11 eee reg] 0F 24 [11 eee reg] 0F 26 [11 eee reg] 0F 24 [11 eee reg]	- - - - -	11/3/3 1/3/3 1 3 1 3 5 5 1 3		11/3/3 1/3/3 1 3 1 3 5 5 1 3			l
MOVS <i>Move String</i>	A [010w]	- - - - -	5	5	5	5	b	h

= immediate data ++ = 16-bit displacement x = modified
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INSTRUCTION	OPCODE	FLAGS	REAL MODE CLOCK COUNT		PROTECTED MODE CLOCK COUNT		NOTES	
		OF DF IF TF SF ZF AF PF CF	Reg/ Cache Hit	Cache Miss	Reg/ Cache Hit	Cache Miss	Real Mode	Protected Mode
MOVSX Move with Sign Extension Register from Register/Memory	0F B [111w] [mod reg r/m]	- - - - -	1/3	5	1/3	5	b	h
MOVZX Move with Zero Extension Register from Register/Memory	0F B [011w] [mod reg r/m]	- - - - -	2/3	5	2/3	5	b	h
MUL Unsigned Multiply Accumulator with Register/Memory Multiplier - Byte - Word - Doubleword	F [011w] [mod 100 r/m]	x - - - - - x	3/5 3/5 7/9	7 7 13	3/5 3/5 7/9	7 7 13	b	h
NEG Negate Integer	F [011w] [mod 011 r/m]	x - - - x x x x x	1/3	5	1/3	5	b	h
NOP No Operation	90	- - - - -	3		3			
NOT Boolean Complement	F [011w] [mod 010 r/m]	- - - - -	1/3	5	1/3	5	b	h
OR Boolean OR Register to Register Register to Memory Memory to Register Immediate to Register/Memory Immediate to Accumulator	0 [10dw] [11 reg r/m] 0 [100w] [mod reg r/m] 0 [101w] [mod reg r/m] 8 [000w] [mod 001 r/m] # 0 [110w] #	0 - - - x x x x 0	1 3 3 1/3 1	5 5 5 5	1 3 3 1/3 1	5 5 5 5	b	h
OUT Output to Port Fixed Port Variable Port	E [011w] [port number] E [111w]	- - - - -	18 18	18 18	4\17 4\17	4\18 4\18		m
OUTS Output String	6 [111w]	- - - - -	20	20	6\19	6\19	b	h,m

= immediate data ++ = 16-bit displacement x = modified
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INSTRUCTION	OPCODE	FLAGS	REAL MODE CLOCK COUNT		PROTECTED MODE CLOCK COUNT		NOTES		
			OF DF IF TF SF ZF AF PF CF	Reg/Cache Hit	Cache Miss	Reg/Cache Hit	Cache Miss	Real Mode	Protected Mode
POP <i>Pop Value off Stack</i> Register/Memory Register (short form) Segment Register (ES, CS, SS, DS) Segment Register (ES, CS, SS, DS, FS, GS)	8F [mod 000 r/m] 5 [1 reg] [000 sreg2 110] 0F [10 sreg3 001]	- - - - -		3/5 3 4 4	4/5 4 5 5	3/5 3 18 18	4/5 4 19 19	b	h,i,j
POPA <i>Pop All General Registers</i>	61	- - - - -		18	18	18	18	b	h
POPF <i>Pop Stack into FLAGS</i>	9D	x x x x x x x x x		4	5	4	5	b	h,n
PREFIX BYTES Assert Hardware LOCK Prefix Address Size Prefix Operand Size Prefix Segment Override Prefix CS DS ES FS GS SS	F0 67 66 2E 3E 26 64 65 36	- - - - -							m
PUSH <i>Push Value onto Stack</i> Register/Memory Register (short form) Segment Register (ES, CS, SS, DS) Segment Register (ES, CS, SS, DS, FS, GS) Immediate	FF [mod 110 r/m] 5 [0 reg] [000 sreg2 110] 0F [10 sreg3 000] 6 [10s0] #	- - - - -		2/4 2 2 2 2	4 2 2 2 2	2/4 2 2 2 2	4 2 2 2 2	b	h
PUSHA <i>Push All General Registers</i>	60	- - - - -		17	17	17	17	b	h
PUSHF <i>Push FLAGS Register</i>	9C	- - - - -		2	2	2	2	b	h

= immediate data ++ = 16-bit displacement x = modified
+ = 8-bit displacement +++ = 32-bit displacement (full) - = unchanged

INSTRUCTION	OPCODE	FLAGS OF DF IF TF SF ZF AF PF CF	REAL MODE CLOCK COUNT		PROTECTED MODE CLOCK COUNT		NOTES	
			Reg/ Cache Hit	Cache Miss	Reg/ Cache Hit	Cache Miss	Real Mode	Protected Mode
RCL Rotate Through Carry Left Register/Memory by 1 Register/Memory by CL Register/Memory by Immediate	D [000w] [mod 010 r/m] D [001w] [mod 010 r/m] C [000w] [mod 010 r/m] #	x - - - - - x	9/9 9/9 9/9	10 10 10	9/9 9/9 9/9	10 10 10	b	h
RCR Rotate Through Carry Right Register/Memory by 1 Register/Memory by CL Register/Memory by Immediate	D [000w] [mod 011 r/m] D [001w] [mod 011 r/m] C [000w] [mod 011 r/m] #	x - - - - - x	9/9 9/9 9/9	10 10 10	9/9 9/9 9/9	10 10 10	b	h
REP INS Input String	F2 6 [110w]	- - - - -	20+9n	20+9n	5+9n \\ 18+9n	5+9n \\ 19+9n	b	h,m
REP LODS Load String	F2 A [110w]	- - - - -	4+5n	4+5n	4+5n	4+5n	b	h
REP MOVS Move String	F2 A [010w]	- - - - -	5+4n	5+4n	5+4n	5+4n	b	h
REP OUTS Output String	F2 6 [111w]	- - - - -	20+4n	20+4n	5+4n \\ 18+4n	5+4n \\ 19+4n	b	h,m
REP STOS Store String	F2 A [101w]	- - - - -	3+4n	3+4n	3+4n	3+4n	b	h
REPE CMPS Compare String (Find non-match)	F3 A [011w]	x - - - x x x x x	5+8n	5+8n	5+8n	5+8n	b	h
REPE SCAS Scan String (Find non-AL/AX/EAX)	F3 A [111w]	x - - - x x x x x	4+5n	4+6n	4+5n	4+6n	b	h
REPNE CMPS Compare String (Find match)	F2 A [011w]	x - - - x x x x x	5+8n	5+8n	5+8n	5+8n	b	h
REPNE SCAS Scan String (Find AL/AX/EAX)	F2 A [111w]	x - - - x x x x x	4+5n	4+6n	4+5n	4+6n	b	h

= immediate data ++ = 16-bit displacement x = modified
+ = 8-bit displacement +++ = 32-bit displacement - = unchanged
(full)

INSTRUCTION	OPCODE	FLAGS OF DF IF TF SF ZF AF PF CF	REAL MODE CLOCK COUNT		PROTECTED MODE CLOCK COUNT		NOTES		
			Reg/ Cache Hit	Cache Miss	Reg/ Cache Hit	Cache Miss	Real Mode	Protected Mode	
RET <i>Return from Subroutine</i> Within Segment Within Segment Adding Immediate to SP Intersegment Intersegment Adding Immediate to SP Protected Mode: Different Privilege Level Intersegment Intersegment Adding Immediate to SP	C3 C2 ++ CB CA ++	- - - - -	10 10 13 13	 13 13	10 10 26 26	 26 27	 69 69	 72 72	b g,h,j,k,r
ROL <i>Rotate Left</i> Register/Memory by 1 Register/Memory by CL Register/Memory by Immediate	D [000w] [mod 000 r/m] D [001w] [mod 000 r/m] C [000w] [mod 000 r/m] #	x - - - - - x	2/4 3/5 2/4	6 7 6	2/4 3/5 2/4	6 7 6	 b	 h	
ROR <i>Rotate Right</i> Register/Memory by 1 Register/Memory by CL Register/Memory by Immediate	D [000w] [mod 001 r/m] D [001w] [mod 001 r/m] C [000w] [mod 001 r/m] #	x - - - - - x	2/4 3/5 2/4	6 7 6	2/4 3/5 2/4	6 7 6	 b	 h	
RSDC <i>Restore Segment Register and Descriptor</i>	0F 79 [mod sreg3 r/m]	- - - - -		14		14	s	s	
RSLDT <i>Restore LDTR and Descriptor</i>	0F 7B [mod 000 r/m]	- - - - -		14		14	s	s	
RSM <i>Resume from SMM Mode</i>	0F AA	- - - - -		58		58	s	s	
RSTS <i>Restore TSR and Descriptor</i>	0F 7D [mod 000 r/m]	- - - - -		14		14	s	s	
SAHF <i>Store AH in FLAGS</i>	9E	x - - - x x - x x	2		2				
SAL <i>Shift Left Arithmetic</i> Register/Memory by 1 Register/Memory by CL Register/Memory by Immediate	D [000w] [mod 100 r/m] D [001w] [mod 100 r/m] C [000w] [mod 100 r/m] #	x - - - x x - x x	2/4 3/5 2/4	6 7 6	2/4 3/5 2/4	6 7 6			
SAR <i>Shift Right Arithmetic</i> Register/Memory by 1 Register/Memory by CL Register/Memory by Immediate	D [000w] [mod 111 r/m] D [001w] [mod 111 r/m] C [000w] [mod 111 r/m] #	x - - - x x x x x	2/4 3/5 2/4	6 7 5	2/4 3/5 2/4	6 7 6			

= immediate data ++ = 16-bit displacement x = modified
 + = 8-bit displacement +++ = 32-bit displacement - = unchanged (full)



INSTRUCTION	OPCODE	FLAGS OF DF IF TF SF ZF AF PF CF	REAL MODE CLOCK COUNT		PROTECTED MODE CLOCK COUNT		NOTES	
			Reg/ Cache Hit	Cache Miss	Reg/ Cache Hit	Cache Miss	Real Mode	Protected Mode
SBB <i>Integer Subtract with Borrow</i> Register to Register Register to Memory Memory to Register Immediate to Register/Memory Immediate to Accumulator (short form)	1 [10dw] [11 reg r/m] 1 [100w] [mod reg r/m] 1 [101w] [mod reg r/m] 8 [00sw] [mod 011 r/m] # 1 [110w] #	x - - - x x x x x	1 3 3 1/3 1	 5 5 5 5	1 3 3 1/3 1	 5 3 5 5	b	h
SCAS <i>Scan String</i>	A [111w]	x - - - x x x x x	5	5	5	5	b	h
SETB/SETNAE/SETC <i>Set Byte on Below/Not Above or Equal/Carry</i> To Register/Memory	0F 92 [mod 000 r/m]	- - - - -	2/2	2	2/2	2		h
SETBE/SETNA <i>Set Byte on Below or Equal/Not Above</i> To Register/Memory	0F 96 [mod 000 r/m]	- - - - -	2/2	2	2/2	2		h
SETE/SETZ <i>Set Byte on Equal/Zero</i> To Register/Memory	0F 94 [mod 000 r/m]	- - - - -	2/2	2	2/2	2		h
SETL/SETNGE <i>Set Byte on Less/Not Greater or Equal</i> To Register/Memory	0F 9C [mod 000 r/m]	- - - - -	2/2	2	2/2	2		h
SETLE/SETNG <i>Set Byte on Less or Equal/Not Greater</i> To Register/Memory	0F 9E [mod 000 r/m]	- - - - -	2/2	2	2/2	2		h
SETNB/SETAE/SETNC <i>Set Byte on Not Below/ Above or Equal/Not Carry</i> To Register/Memory	0F 93 [mod 000 r/m]	- - - - -	2/2	2	2/2	2		h

= immediate data ++ = 16-bit displacement x = modified
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INSTRUCTION	OPCODE	FLAGS	REAL MODE CLOCK COUNT		PROTECTED MODE CLOCK COUNT		NOTES	
		OF DF IF TF SF ZF AF PF CF	Reg/ Cache Hit	Cache Miss	Reg/ Cache Hit	Cache Miss	Real Mode	Protected Mode
SETNBE/SETA <i>Set Byte on Not Below or Equal/Above</i> To Register/Memory	0F 97 [mod 000 r/m]	-----	2/2	2	2/2	2		h
SETNE/SETNZ <i>Set Byte on Not Equal/Not Zero</i> To Register/Memory	0F 95 [mod 000 r/m]	-----	2/2	2	2/2	2		h
SETNL/SETGE <i>Set Byte on Not Less/Greater or Equal</i> To Register/Memory	0F 9D [mod 000 r/m]	-----	2/2	2	2/2	2		h
SETNLE/SETG <i>Set Byte on Not Less or Equal/Greater</i> To Register/Memory	0F 9F [mod 000 r/m]	-----	2/2	2	2/2	2		h
SETNO <i>Set Byte on Not Overflow</i> To Register/Memory	0F 91 [mod 000 r/m]	-----	2/2	2	2/2	2		h
SETNP/SETPO <i>Set Byte on Not Parity/Parity Odd</i> To Register/Memory	0F 9B [mod 000 r/m]	-----	2/2	2	2/2	2		h
SETNS <i>Set Byte on Not Sign</i> To Register/Memory	0F 99 [mod 000 r/m]	-----	2/2	2	2/2	2		h
SETO <i>Set Byte on Overflow</i> To Register/Memory	0F 90 [mod 000 r/m]	-----	2/2	2	2/2	2		h
SETP/SETPE <i>Set Byte on Parity/Parity Even</i> To Register/Memory	0F 9A [mod 000 r/m]	-----	2/2	2	2/2	2		h

= immediate data ++ = 16-bit displacement x = modified
 + = 8-bit displacement +++ = 32-bit displacement (full) - = unchanged

INSTRUCTION	OPCODE	FLAGS	REAL MODE CLOCK COUNT		PROTECTED MODE CLOCK COUNT		NOTES		
			OF DF IF TF SF ZF AF PF CF	Reg/ Cache Hit	Cache Miss	Reg/ Cache Hit	Cache Miss	Real Mode	Protected Mode
SETS Set Byte on Sign To Register/Memory	0F 98 [mod 000 r/m]	- - - - -		2/2	2	2/2	2		h
SGDT Store GDT Register To Register/Memory	0F 01 [mod 000 r/m]	- - - - -		6	6	6	6	b,c	h
SHL Shift Left Logical Register/Memory by 1 Register/Memory by CL Register/Memory by Immediate	D [000w] [mod 100 r/m] D [001w] [mod 100 r/m] C [000w] [mod 100 r/m] #	x - - - x x - x x		2/4 3/5 2/4	6 7 6	2/4 3/5 2/4	6 7 6	b	h
SHLD Shift Left Double Register/Memory by Immediate Register/Memory by CL	0F A4 [mod reg r/m] # 0F A5 [mod reg r/m]	- - - - x x - x x		1/3 3/5	5 7	1/3 3/5	5 7		
SHR Shift Right Logical Register/Memory by 1 Register/Memory by CL Register/Memory by Immediate	D [000w] [mod 101 r/m] D [001w] [mod 101 r/m] C [000w] [mod 101 r/m] #	x - - - x x - x x		2/4 3/5 2/4	6 7 5	2/4 3/5 2/4	6 7 6	b	h
SHRD Shift Right Double Register/Memory by Immediate Register/Memory by CL	0F AC [mod reg r/m] # 0F AD [mod reg r/m]	- - - - x x - x x		1/3 3/5	5 7	1/3 3/5	5 7		
SIDT Store IDT Register To Register/Memory	0F 01 [mod 001 r/m]	- - - - -		6	6	6	6	b,c	h
SLDT Store LDT Register To Register/Memory	0F 00 [mod 000 r/m]	- - - - -				1/2	2	a	h
MSW Store Machine Status Word	0F 01 [mod 100 r/m]	- - - - -		1/2	2	1/2	2	b,c	h,l

= immediate data ++ = 16-bit displacement x = modified
 + = 8-bit displacement +++ = 32-bit displacement - = unchanged (full)

INSTRUCTION	OPCODE	FLAGS	REAL MODE CLOCK COUNT		PROTECTED MODE CLOCK COUNT		NOTES	
		OF DF IF TF SF ZF AF PF CF	Reg/ Cache Hit	Cache Miss	Reg/ Cache Hit	Cache Miss	Real Mode	Protected Mode
STC Set Carry Flag	F9	- - - - - 1	1		1			
STD Set Direction Flag	FD	- 1 - - - - -	1		1			
STI Set Interrupt Flag	FB	- - 1 - - - - -	7		7			m
STOS Store String	A [101w]	- - - - -	3	3	3	3	b	h
STR Store Task Register To Register/Memory	0F 00 [mod 001 r/m]	- - - - -			1/2	2	a	h
SUB Integer Subtract Register to Register Register to Memory Memory to Register Immediate to Register/Memory Immediate to Accumulator (short form)	2 [10dw] [11 reg r/m] 2 [100w] [mod reg r/m] 2 [101w] [mod reg r/m] 8 [00sw] [mod 101 r/m] # 2 [110w] #	x - - - x x x x x	1 3 3 1/3 1	5 5 5 5	1 3 3 1/3 1	5 5 5 5	b	h
SVDC Save Segment Register and Descriptor	0F 78 [mod sreg3 r/m]	- - - - -		22		22	s	s
SVLDI Save LDTR and Descriptor	0F 7A [mod 000 r/m]	- - - - -		22		22	s	s
SVTS Save TSR and Descriptor	0F 7C [mod 000 r/m]	- - - - -		22		22	s	s
TEST Test Bits Register/Memory and Register Immediate Data and Register/Memory Immediate Data and Accumulator	8 [010w] [mod reg r/m] F [011w] [mod 000 r/m] # A [100w] #	0 - - - x x - x 0	1/3 1/3 1	5 5	1/3 1/3 1	5 5	b	h
VERR Verify Read Access To Register/Memory	0F 00 [mod 100 r/m]	- - - - - x - - - -			9/10	12	a	g,h,j,p

= immediate data ++ = 16-bit displacement x = modified
 + = 8-bit displacement +++ = 32-bit displacement - = unchanged (full)



INSTRUCTION	OPCODE	FLAGS	REAL MODE CLOCK COUNT		PROTECTED MODE CLOCK COUNT		NOTES	
		OF DF IF TF SF ZF AF PF CF	Reg/ Cache Hit	Cache Miss	Reg/ Cache Hit	Cache Miss	Real Mode	Protected Mode
VERW Verify Write Access To Register/Memory	0F 00 [mod 101 r/m]	- - - - - x - - - -			9/10	12	a	g,h,j,p
WAIT Wait Until FPU Not Busy	9B	- - - - - - - - - -	5	5	5	5		
WBINVD Write-Back and Invalidate Cache	0F 09	- - - - - - - - - -	4		4			
XADD Exchange and Add Register1, Register2 Memory, Register	0F C [000w] [11 reg2 reg1] 0F C [000w] [mod reg r/m]	x - - - - x x x x x	3 6	6	3 6	6		
XCHG Exchange Register/Memory with Register Register with Accumulator	8 [011w] [mod reg r/m] 9 [0 reg]	- - - - - - - - - -	3/4 3	4	3/4 3	4	b,f	f,h
XLAT Translate Byte	D7	- - - - - - - - - -	3	5	3	5		h
XOR Boolean Exclusive OR Register to Register Register to Memory Memory to Register Immediate to Register/Memory Immediate to Accumulator (short form)	3 [00dw] [11 reg r/m] 3 [000w] [mod reg r/m] 3 [001w] [mod reg r/m] 8 [00sw] [mod 110 r/m] # 3 [010w] #	0 - - - - x x - x 0	1 3 3 1/3 1	5 5 5 5	1 3 3 1/3 1	5 5 5 5	b	h

= immediate data ++ = 16-bit displacement x = modified
+ = 8-bit displacement +++ = 32-bit displacement - = unchanged
(full)

Instruction Notes for Instruction Set Summary

Notes a through c apply to Real Address Mode only:

- This is a Protected Mode instruction. Attempted execution in Real Mode will result in exception 6 (invalid op-code).
- Exception 13 fault (general protection) will occur in Real Mode if an operand reference is made that partially or fully extends beyond the maximum CS, DS, ES, FS, or GS segment limit (FFFFH). Exception 12 fault (stack segment limit violation or not present) will occur in Real Mode if an operand reference is made that partially or fully extends beyond the maximum SS limit.
- This instruction may be executed in Real Mode. In Real Mode, its purpose is primarily to initialize the CPU for Protected Mode.

Instruction Notes for Instruction Set Summary (Continued)

Notes e through g apply to Real Address Mode and Protected Virtual Address Mode:

- e. An exception may occur, depending on the value of the operand.
- f. LOCK# is automatically asserted, regardless of the presence or absence of the LOCK prefix.
- g. LOCK# is asserted during descriptor table accesses.

Notes h through r apply to Protected Virtual Address Mode only:

- h. Exception 13 fault will occur if the memory operand in CS, DS, ES, FS, or GS cannot be used due to either a segment limit violation or an access rights violation. If a stack limit is violated, an exception 12 occurs.
- i. For segment load operations, the CPL, RPL, and DPL must agree with the privilege rules to avoid an exception 13 fault. The segment's descriptor must indicate "present" or exception 11 (CS, DS, ES, FS, GS not present). If the SS register is loaded and a stack segment not present is detected, an exception 12 occurs.
- j. All segment descriptor accesses in the GDT or LDT made by this instruction will automatically assert LOCK# to maintain descriptor integrity in multiprocessor systems.
- k. JMP, CALL, INT, RET, and IRET instructions referring to another code segment will cause an exception 13, if an applicable privilege rule is violated.
- l. An exception 13 fault occurs if CPL is greater than 0 (0 is the most privileged level).
- m. An exception 13 fault occurs if CPL is greater than IOPL.
- n. The IF bit of the flag register is not updated if CPL is greater than IOPL. The IOPL and VM fields of the flag register are updated only if CPL = 0.
- o. The PE bit of the MSW (CRO) cannot be reset by this instruction. Use MOV into CRO if desiring to reset the PE bit.
- p. Any violation of privilege rules as apply to the selector operand does not cause a Protection exception, rather, the zero flag is cleared.
- q. If the coprocessor's memory operand violates a segment limit or segment access rights, an exception 13 fault will occur before the ESC instruction is executed. An exception 12 fault will occur if the stack limit is violated by the operand's starting address.
- r. The destination of a JMP, CALL, INT, RET, or IRET must be in the defined limit of a code segment or an exception 13 fault will occur.
- s. All memory accesses using this instruction are non-cacheable as this instruction uses SMM address space.

Notes



Notes

CYRIX Cx486SLC/e™ MICROPROCESSOR

High-Performance 486-Style CPU with Advanced Power Management for Notebook or Battery Powered Systems



Appendix

A.1 Cx486SLC/e Stepping Revision History

The Cx486SLC/e is an enhanced version of the Cx486SLC that adds System Management Mode circuitry including two new pins: SMI# (pin 47) and SMADS# (pin 20).

Also included are seven new software instructions: SVDC, RSDC, SVLDT, SVTS, RSTS, and RSM. Stepping identification can be performed by reading the initialized state of the EDX register (bits 15 - 0). The EDX register data is listed in Table A-1.

Table A-1. Cx486SLC Stepping

STEPPING	EDX REGISTER	DESCRIPTION
Cx486SLC	0410	Original feature set
Cx486SLC/e	0411	SMM feature added

A.2 Manual Revision History

This manual (94069-00) replaces manual (94073-00) and applies Cx486SLC (except SMM mode features) and the Cx486SLC/e. The new features are described as well as many other updates and improvements have been made. The following items have been significantly revised:

Cover Page

Changed to reflect new features.

Section 1.5

Inclusion of system management mode information has been made to this section.

Section 1.6

Figure 1-1 includes SMADS# and SMI# signals.

Section 2.1

In Table 2-1 the four NCR registers in the previous manual have been renamed as ARR registers as the meaning of these registers changed. Within Table 2-1 the initialized contents of the EDX, CR0, CCR1 and DR7 have been corrected and updated.

Section 2.3.2

Figure 2-5 contains AARn registers replacing NCRn registers. Description of TR6 and TR7 has been corrected.

Section 2.3.2.4

This section was re-written to reflect SMM additions. The ARRN registers are described.

Section 2.5

Section 2.5 and its sub-sections were re-written include SMM information.

Section 2.6

This section is new and provides detailed system management mode information. The section describes the SMM memory space, the SMM header and the SMM instruction set.

Section 3.1

Figure 3-1 now shows the signals in the order they are described as well as includes the additional signals used for SMM operations. Table 3-1 include SMM signals.

Section 3.2.6

SMADS# paragraph included.

Section 3.2.7

SMI# paragraph included.

Section 3.2.11

Tables 3-5 and 3.2.12 corrected and updated.

Section 3.3.10

This is a new section and describes the SMM interface. Within this section the SMM bus timing and the SMM I/O trap mechanism are described.

Section 4.1.2

Pull-up resistor for SMI# added to Table 4-1.

Section 4.4

33 MHz information added to Table 4-5.

Section 4.5

SMADS# and SMI# timing information added to Figures 4-1, 4-3, 4-4 and 4-7 and also to Tables 4-7, 4-8, 4-9. Figure 4-9 is new and provides 33 MHz AC characteristics.

Section 5.1

Figure 5-1, Tables 5-1 and 5-2 include the SMADS# and SMI# pins.

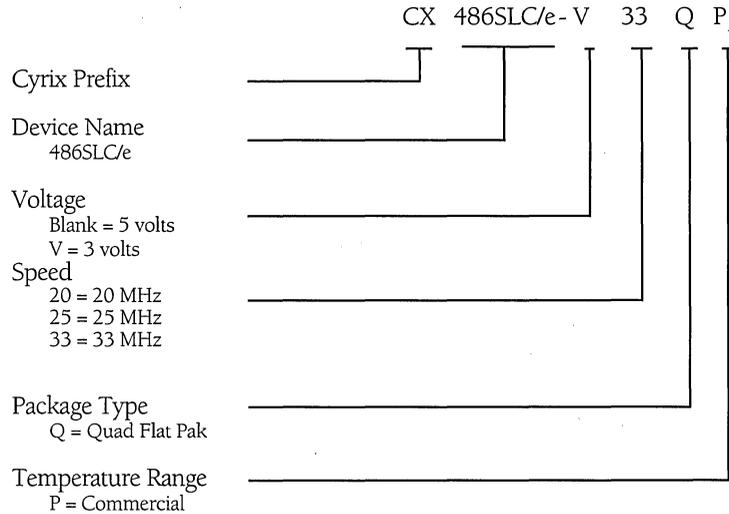
Section 5.3

The section has been corrected and updated. Tables 5-4 and 5-5 have been added to provide airflow as related to ambient temperature for various clock frequencies.

Section 6.4.2

Table 6-16 includes the SVDC, SVLDT, SVTS RSDC, RSLDT, RSTS and RSM instructions.

A.3 Ordering Information



The currently available Cyrix Cx486SLC/e part numbers are listed below:

Cx486SLC/e Part Numbers

PART NUMBER	DESCRIPTION
Cx486SLC/e-25-QP	5 V, 25 MHz, QFP Package
Cx486SLC/e-33-QP	5 V, 33 MHz, QFP Package
Cx486SLC/e-V20-QP	3 V, 20 MHz, QFP Package
Cx486SLC/e-V25-QP	3 V, 25 MHz, QFP Package

INDEX**A**

- AC Characteristics, 4-5
- Addresses
 - address bus, 3-4
 - address space, 2-32
 - offset address calculation, 2-34

B

- Bus
 - bus arbitration, 3-9
 - bus cycles using non-pipelined addressing, 3-14
 - bus cycles using pipelined addressing, 3-18
 - bus interface overview, 3-1
 - bus operation, 3-14
 - bus state diagram, 3-25
- Byte Enable Lines (BLE#, BHE#), 3-4

C

- Cache Interface
 - cache flushing, 3-31
 - internal cache interface signals, 3-7
 - internal cache timing, 3-30
- Clock
 - 2X clock input signal, 3-3
 - clock count assumptions, 6-10
 - clock waveform measurement points, 4-7
 - stopping the input clock, 3-43
- Coprocessor Interface
 - signals, 3-8
 - timing, 3-37

D

- Data Bus Signals, 3-4
- DC Characteristics, 4-4
- Descriptor Table and Segment Selectors, 2-7
- Descriptors, Segment and Gate, 2-16

E

- Exceptions, Trap, Fault and Abort, 2-41

F

- Floating CPU signals using FLT#, 3-44

G

- Gate Descriptors, 2-18
- Gates and Privilege Transfers, 2-57

H

- Halt (HLT) and Shutdown due to Errors, 2-53
- Halt and Shutdown Timing Cycles, 3-27
- Hold Acknowledge (HLDA), 3-9
- Hold Acknowledge State, 3-33

I

- I/O Address Space, 2-32
- Initialization, 2-1
- Instruction Set Formats, 6-1
- Instruction Timing, 6-13
- Interrupt Acknowledge (INTA) Cycles, 3-26
- Interrupts
 - abort exceptions, 2-41
 - exceptions, 2-41
 - fault exceptions, 2-41
 - hardware/software, 2-44
 - interrupt pins, NMI, INTR, SMI# 2-40
 - interrupt vectors, 2-41
 - INTR interrupts, 2-40
 - NMI interrupts, 2-40
 - priorities, 2-43
 - SMI interrupt, 2-47
 - real mode and exceptions, 2-45
 - trap exceptions, 2-41

L

- Lock Prefix for Instructions, 2-3
- Locked Bus Cycles, 3-26

M

- Maximum Temperature and Voltage Ratings, 4-2
- Mechanical Drawing of 100-pin BQFP Package, 5-4
- Memory and I/O Address Spaces, 2-32

INDEX

Modes

- HALT initiated suspend modesuspend, 3-42
- memory addressing modes table, 2-34
- protected mode addressing mode, 2-35
- real mode addressing mode, 2-35
- SUSP# initiated suspend mode, 3-41
- virtual 8086, 2-58

O

- Offset Address Calculation, 2-34
- Operating Conditions, Recommended 4-3

P

- Package Drawing (100-pin BQFP), 5-4
- Paging Mechanism, 2-37
- Pin Assignments, 5-1
- Pins, Unused and N/C Input, 4-2
- Pipelined Addressing, 3-18
- Pipelined Cycles and Wait States, 3-20
- Power and Ground Considerations, 4-1
- Power Management Interface, 3-10
- Power Management Timing, 4-41
- Privilege Level Field in Segment Selector, 2-8,
- Privilege Levels (DPL, CPL, RPL), 2-55
- Protection, Segment and Page, 2-53
- Pull-Up and Pull-Down Resistors, 4-1

R

Registers

- address region registers, 2-22
- application register set, 2-4
- cache test register, 2-30
- configuration control registers, 2-22
- control registers, 2-13
- data registers, 2-4
- debug registers, 2-26
- descriptor table registers and descriptors, 2-15
- flags register (EFLAGS), 2-9
- global descriptor table register, 2-15
- interrupt descriptor table register, 2-15
- instruction pointer register, 2-9
- local descriptor table register, 2-15
- pointer and index register, 2-5

- segment registers and selectors, 2-7
- system register set, 2-11
- task register, 2-19
- test register, 2-28

Requested Privilege Level (RPL), 2-8

RESET

- RESET setup and hold timing, 4-14
- RESET timing, internal clock synchronization, 3-12
- signal status during reset, 3-3

S

- Segment Selector, 2-7
- Segment Descriptor, 2-7
- Selector Address Mechanism, 2-36
- Selectors, Code, Data and Stack 2-7
- Setup and Hold Timing, 4-11
- Signals

- A23 - A1, 3-4
- A20M#, 3-8,
- A20M# timing, 3-32
- ADS#, 3-5
- BHE#, 3-4
- BLE#, 3-4
- BUSY#, 3-8
- D15 - D0, 3-4
- D/C#, 3-4
- ERROR#, 3-8
- FLT#, 3-12
- FLUSH#, 3-7
- HLDA, 3-9
- HOLD, 3-9
- INTR, 2-40, 3-6
- KEN#, 3-7
- LOCK#, 3-4
- M/IO#, 3-4
- NA#, 3-6
- NMI, 2-40, 3-6
- PEREQ, 3-8
- READY#, 3-6
- RESET, 3-3
- RPLSET, 3-7
- RPLVAL#, 3-7

INDEX

SMADS#, 3-6
SMI#, 3-6
SUSP#, 3-10
SUSPA#, 3-10
W/R#, 3-4
Signal Summary, 3-2
Signals Unique to Cx486SLC/e, 1-4
SMI Service Routine Execution, 2-52
SMM Interface, 3-38
SMM Instructions, 2-51
SMM Memory Space, 2-52
SMM Memory Space Header, 2-49
SMM Operation, 2-48
Suspend Mode, 3-41
System Management Mode (SMM), 2-47

T _____

Thermal Characteristics, 5-5
Translation Look-Aside Buffer, 2-39

W _____

Wait States, Non-Pipelined, 3-17

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